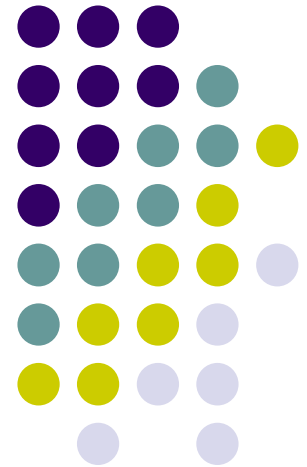


# Computer Graphics (CS 543)

## Lecture 8c: Environment Mapping (Reflections and Refractions)

Prof Emmanuel Agu  
(Adapted from slides by Ed Angel)

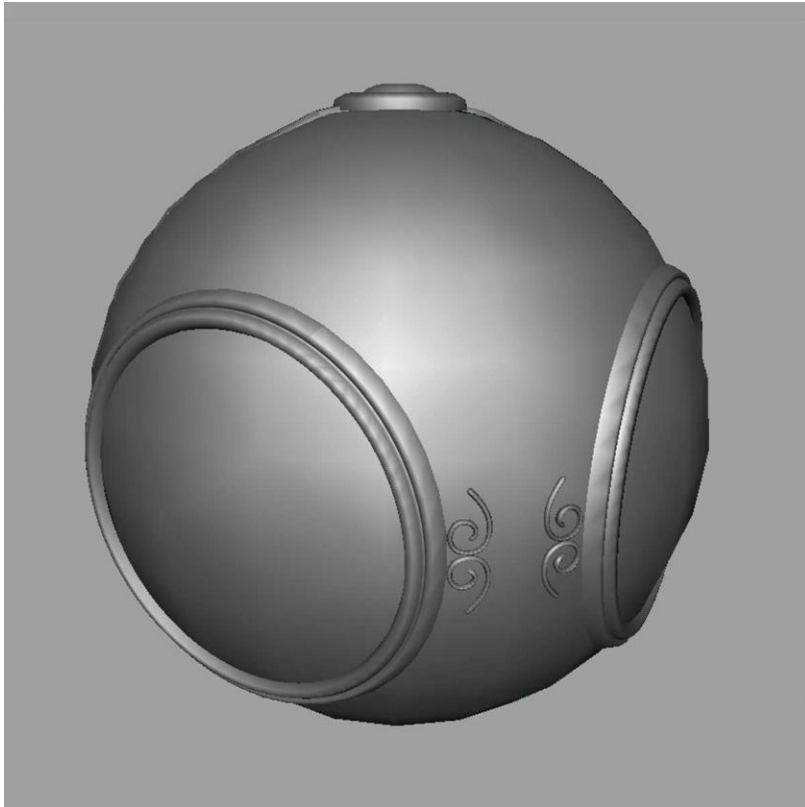
*Computer Science Dept.  
Worcester Polytechnic Institute (WPI)*



# Environment Mapping



- Environmental mapping is way to create the appearance of highly **reflective** and **refractive** surfaces without ray tracing

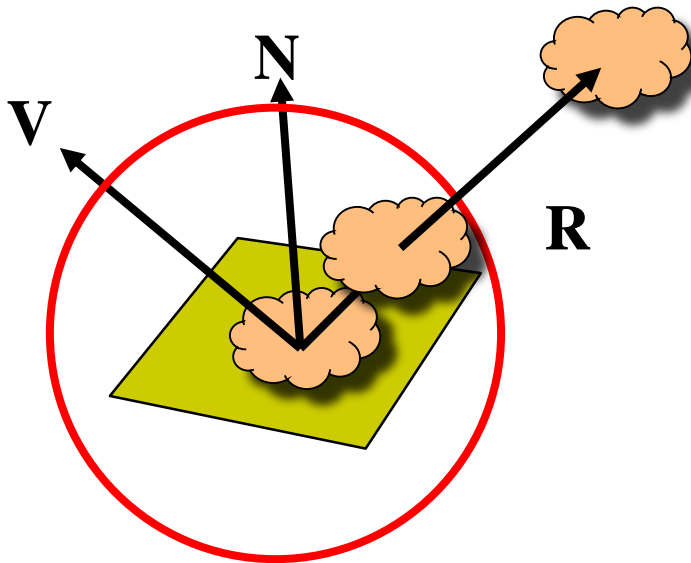




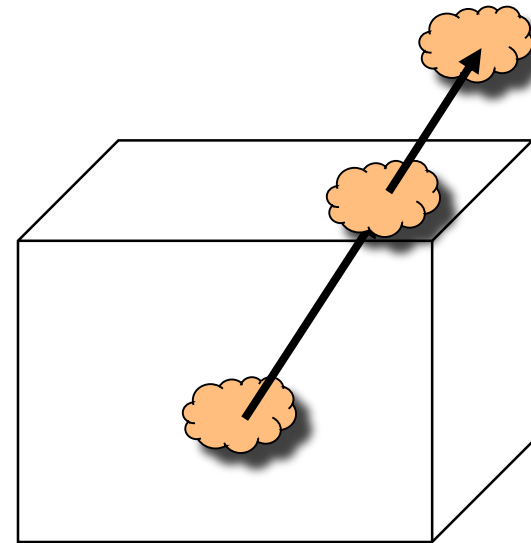
# Types of Environment Maps

- Assumes environment infinitely far away
- Options: Store “object’s environment as

a) Sphere around object (sphere map)



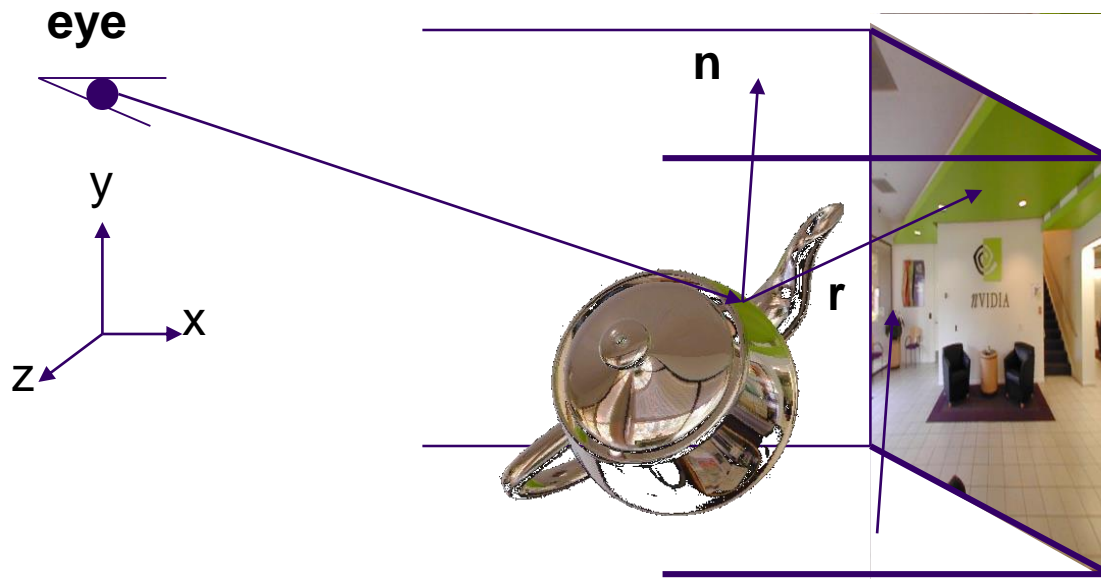
b) Cube around object (cube map)



- OpenGL supports **cube maps** and **sphere maps**



# Cube mapping

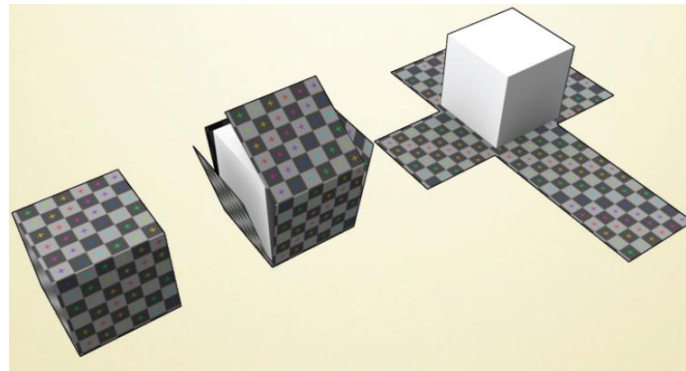
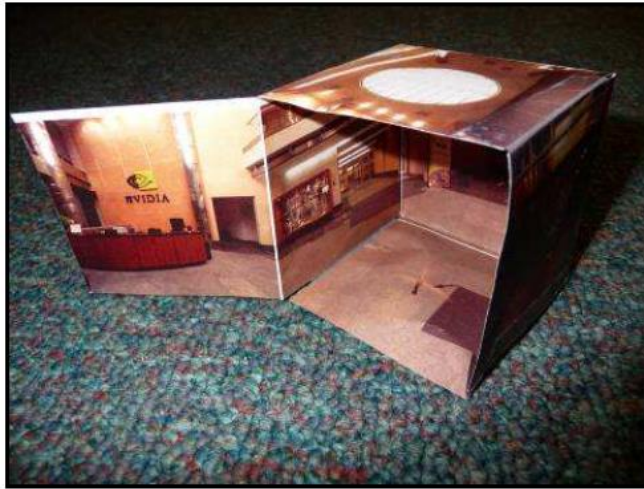


- Need to compute reflection vector,  $\mathbf{r}$
- Use  $\mathbf{r}$  by for environment map lookup

# Cube Map: How to Store



- Stores “**environment**” around objects as 6 sides of a cube (1 texture)
- Load 6 textures separately into 1 OpenGL cubemap



# Cube Maps



- Loaded cube map texture can be accessed in GLSL through cubemap sampler

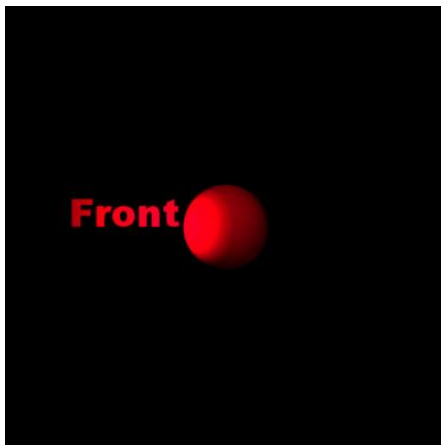
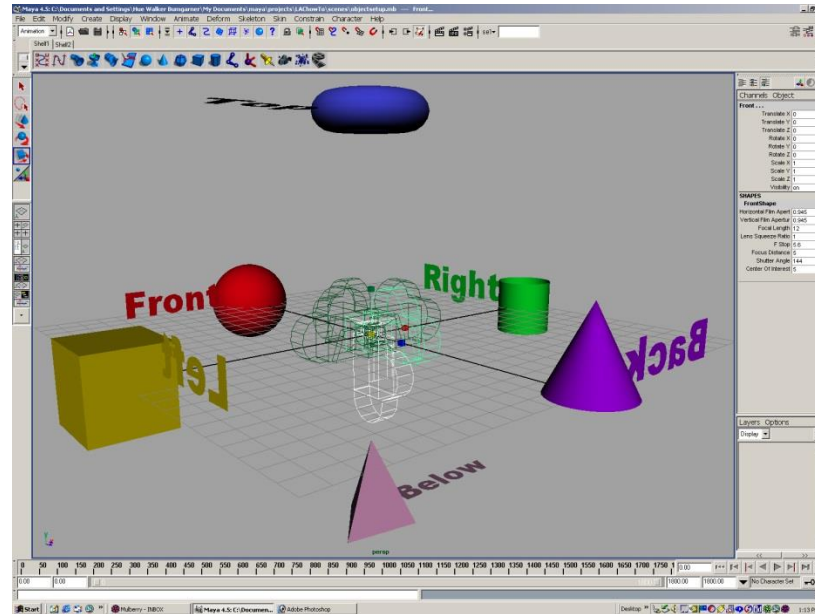
```
vec4 texColor = textureCube(mycube, texcoord);
```

- Texture coordinates must be 3D (x, y, z)



# Creating Cube Map

- Use 6 cameras directions from scene center
  - each with a 90 degree angle of view



# Indexing into Cube Map



- Compute  $\mathbf{R} = 2(\mathbf{N} \cdot \mathbf{V})\mathbf{N} - \mathbf{V}$

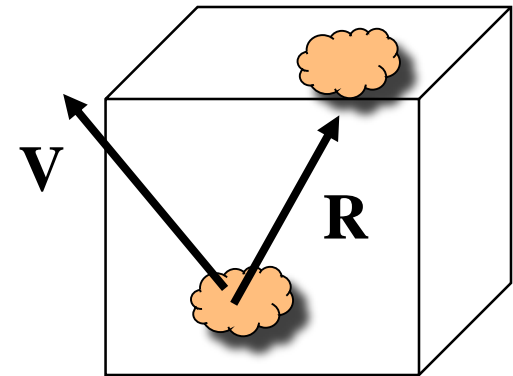
- Object at origin

- Perform lookup:

```
vec4 texColor = textureCube(mycube, R);
```

- **Largest magnitude component of R**  
(x,y,z) used to determine face of cube

- Other 2 components give  
texture coordinates



More on this later....





# Declaring Cube Maps in OpenGL

```
glTextureMap2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X, level, rows,  
              columns, border, GL_RGBA, GL_UNSIGNED_BYTE, image1)
```

- Repeat similar for other 5 images (sides)
- Make **1 cubemap texture object from 6 images**
- Parameters apply to all six images. E.g

```
glTexParameteri( GL_TEXTURE_CUBE_MAP,  
                 GL_TEXTURE_MAP_WRAP_S, GL_REPEAT)
```

- **Note:** texture coordinates are in 3D space (s, t, r)



# Cube Map Example (init)

```
// colors for sides of cube
GLubyte red[3] = {255, 0, 0};
GLubyte green[3] = {0, 255, 0};
GLubyte blue[3] = {0, 0, 255};
GLubyte cyan[3] = {0, 255, 255};
GLubyte magenta[3] = {255, 0, 255};
GLubyte yellow[3] = {255, 255, 0};

glEnable(GL_TEXTURE_CUBE_MAP);

// Create texture object
glGenTextures(1, tex);
glActiveTexture(GL_TEXTURE1);
glBindTexture(GL_TEXTURE_CUBE_MAP, tex[0]);
```

**This example generates simple  
Colors as a texture**

**You can also just load  
6 pictures of environment**

# Cube Map (init II)

Load 6 different pictures into  
1 cube map of environment



```
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X ,
              0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, red);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_X ,
              0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, green);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_Y ,
              0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, blue);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_Y ,
              0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, cyan);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_Z ,
              0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, magenta);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_Z ,
              0,3,1,1,0,GL_RGB,GL_UNSIGNED_BYTE, yellow);
glTexParameteri(GL_TEXTURE_CUBE_MAP,
                 GL_TEXTURE_MAG_FILTER,GL_NEAREST);
```



# Cube Map (init III)

```
GLuint texMapLocation;  
GLuint tex[1];
```

```
texMapLocation = glGetUniformLocation(program, "texMap");  
glUniform1i(texMapLocation, tex[0]);
```

Connect texture map (tex[0])  
to variable texMap in fragment shader  
(texture mapping done in frag shader)



# Adding Normals

```
void quad(int a, int b, int c, int d)
{
```

```
    static int i =0;
```

```
    normal = normalize(cross(vertices[b] - vertices[a],
        vertices[c] - vertices[b]));
```

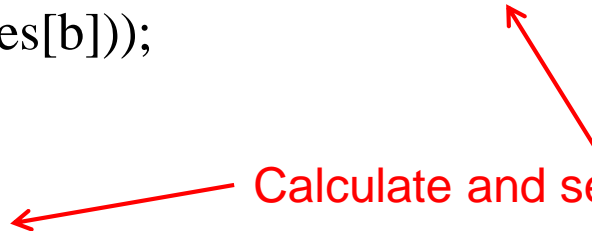
```
    normals[i] = normal;
```

```
    points[i] = vertices[a];
```

```
    i++;
```

```
// rest of data
```

Calculate and set quad normals





# Vertex Shader

```
out vec3 R;
in vec4 vPosition;
in vec4 Normal;
uniform mat4 ModelView;
uniform mat4 Projection;

void main() {
    gl_Position = Projection*ModelView*vPosition;
    vec4 eyePos = vPosition;           // calculate view vector V
    vec4 NN = ModelView*Normal;       // transform normal
    vec3 N =normalize(NN.xyz);         // normalize normal
    R = reflect(eyePos.xyz, N);       // calculate reflection vector R
}
```

# Fragment Shader



```
in vec3 R;
uniform samplerCube texMap;

void main()
{
    vec4 texColor = textureCube(texMap, R); // look up texture map using R

    gl_FragColor = texColor;
}
```



# Refraction using Cube Map

- Can also use cube map for refraction (transparent)



**Reflection**



**Refraction**

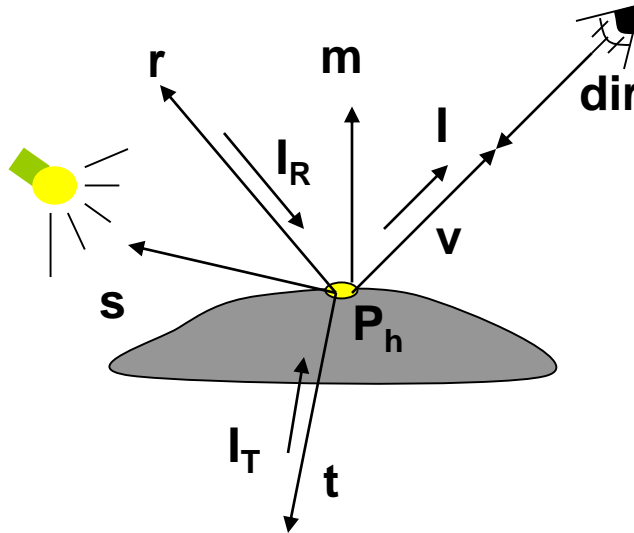




# Reflection and Refraction

- At each vertex

$$I = I_{amb} + I_{diff} + I_{spec} + I_{refl} + I_{tran}$$

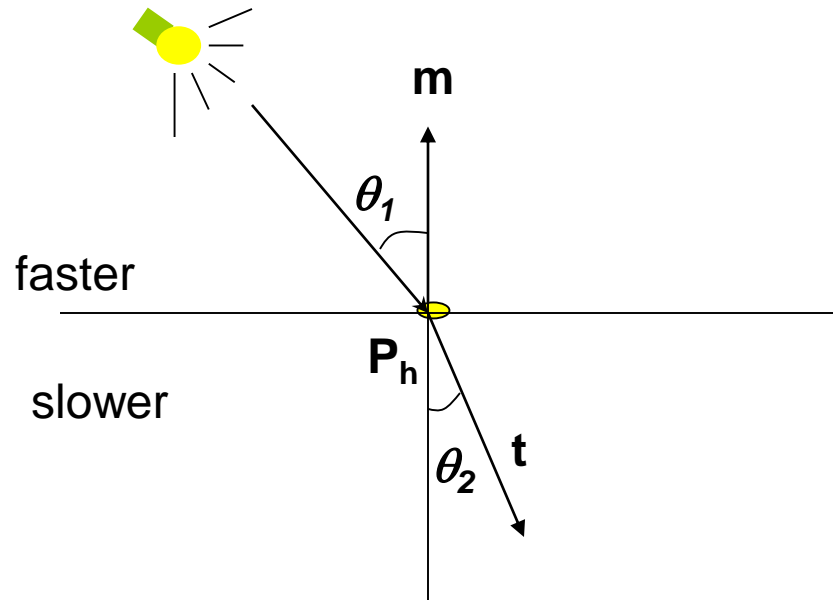


- Refracted component  $I_T$  is along transmitted direction  $t$

# Finding Transmitted (Refracted) Direction



- Transmitted direction obeys **Snell's law**
- Snell's law: relationship holds in diagram below



$$\frac{\sin(\theta_2)}{c_2} = \frac{\sin(\theta_1)}{c_1}$$

$c_1, c_2$  are speeds of light in medium 1 and 2



# Finding Transmitted Direction

- If ray goes from faster to slower medium (e.g. air to glass), ray is bent **towards** normal
- If ray goes from slower to faster medium (e.g. glass to air), ray is bent **away** from normal
- $c_1/c_2$  is important. Usually measured for medium-to-vacuum. E.g water to vacuum
- Some measured relative  $c_1/c_2$  are:
  - Air: 99.97%
  - Glass: 52.2% to 59%
  - Water: 75.19%
  - Sapphire: 56.50%
  - Diamond: 41.33%



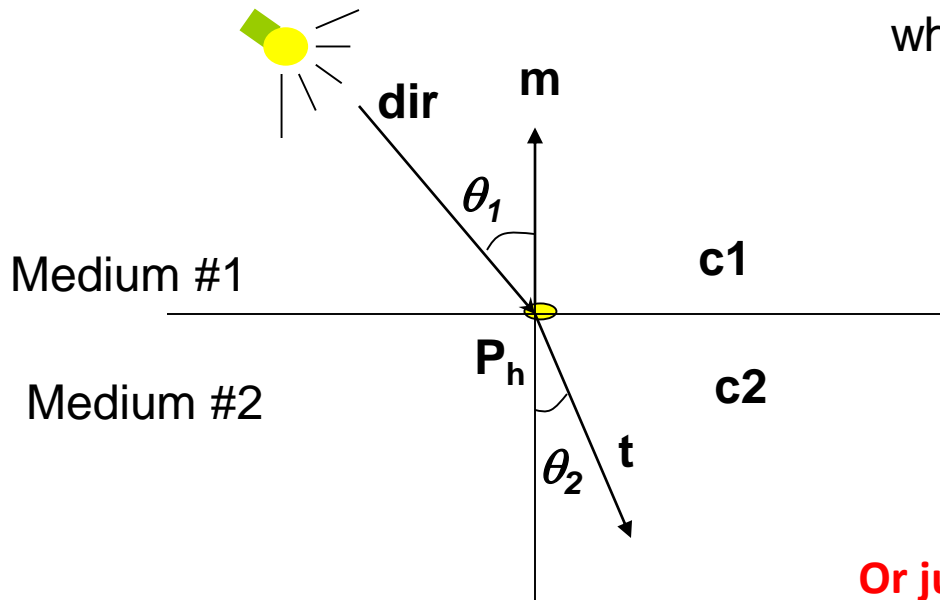
# Transmission Angle

- Vector for transmission angle can be found as

$$\mathbf{t} = \frac{c_2}{c_1} \mathbf{dir} + \left( \frac{c_2}{c_1} (\mathbf{m} \bullet \mathbf{dir}) - \cos(\theta_2) \right) \mathbf{m}$$

where

$$\cos(\theta_2) = \sqrt{1 - \left( \frac{c_2}{c_1} \right)^2 (1 - (\mathbf{m} \bullet \mathbf{dir})^2)}$$



Or just use GLSL built-in function `refract` to get T



# Refraction Vertex Shader

```
out vec3 T;
in vec4 vPosition;
in vec4 Normal;
uniform mat4 ModelView;
uniform mat4 Projection;

void main() {
    gl_Position = Projection*ModelView*vPosition;
    vec4 eyePos = vPosition;           // calculate view vector V
    vec4 NN = ModelView*Normal;       // transform normal
    vec3 N =normalize(NN.xyz);         // normalize normal
    T = refract(eyePos.xyz, N, iorefr); // calculate refracted vector T
}
```

**Was previously** `R = reflect(eyePos.xyz, N);`

# Refraction Fragment Shader

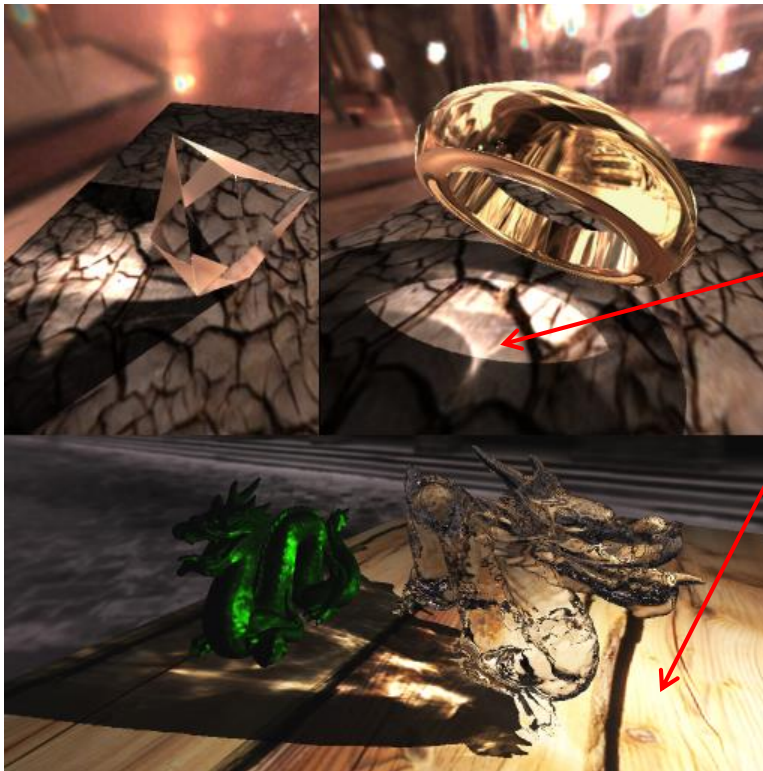


```
in vec3 T;
uniform samplerCube RefMap;

void main()
{
    vec4 refractColor = textureCube(RefMap, T); // look up texture map using T
    refractcolor = mix(refractColor, WHITE, 0.3); // mix pure color with 0.3 white

    gl_FragColor = refractcolor;
}
```

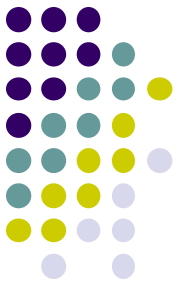
# Caustics



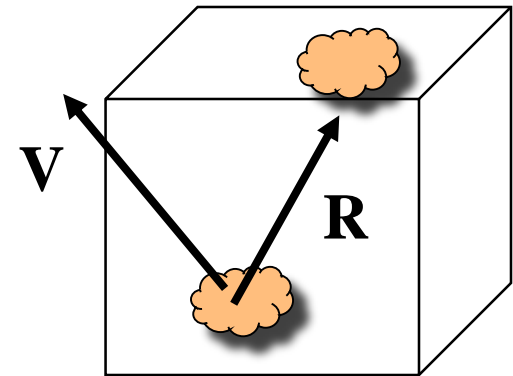
Caustics occur when light is focussed on diffuse surface

Courtesy Chris Wyman, Univ Iowa

# Recall: Indexing into Cube Map

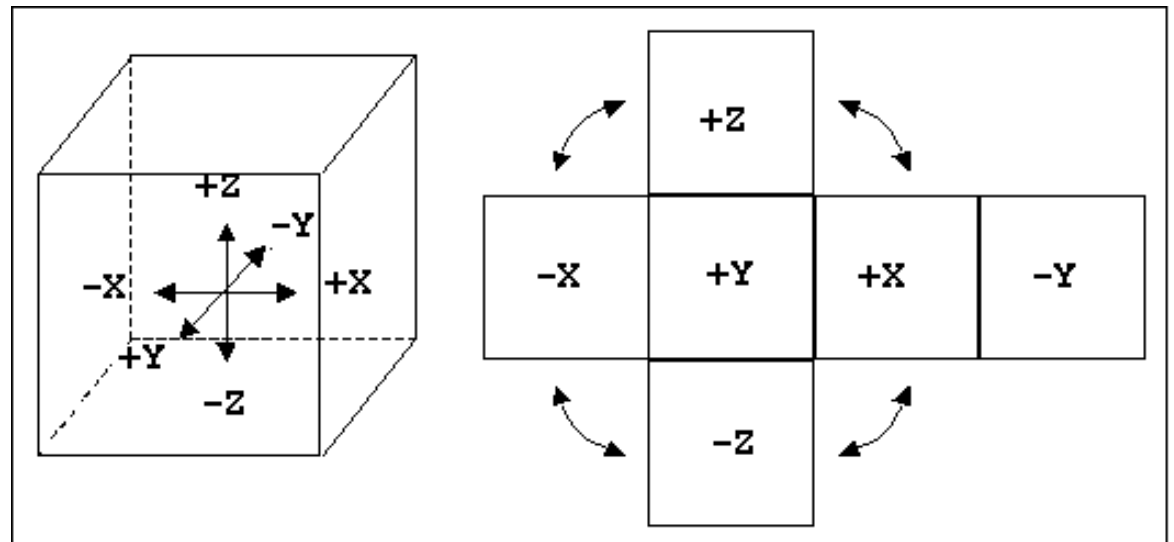
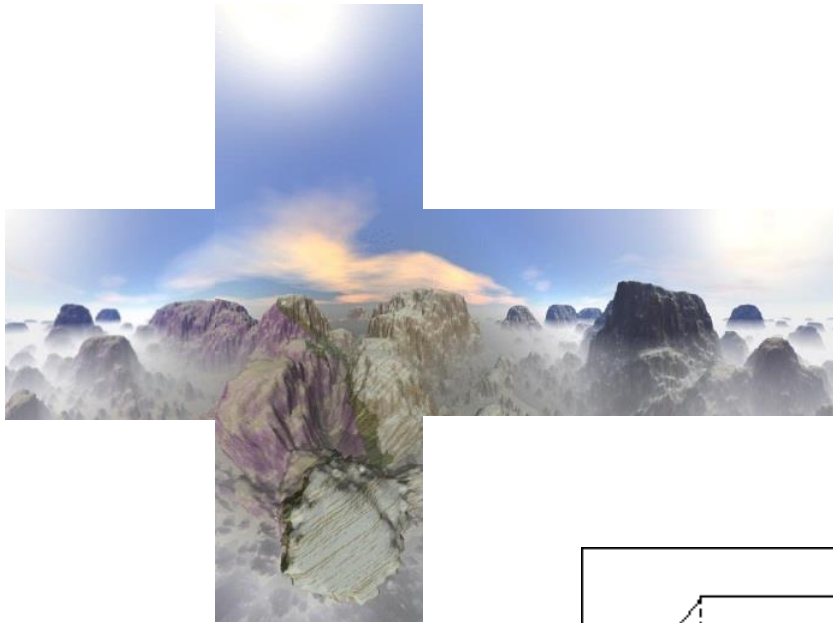
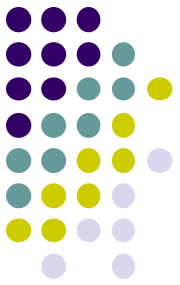


- Compute  $R = 2(N \cdot V)N - V$
- Object at origin
- Use **largest magnitude component** of  $R$  to determine face of cube
- Other 2 components give texture coordinates





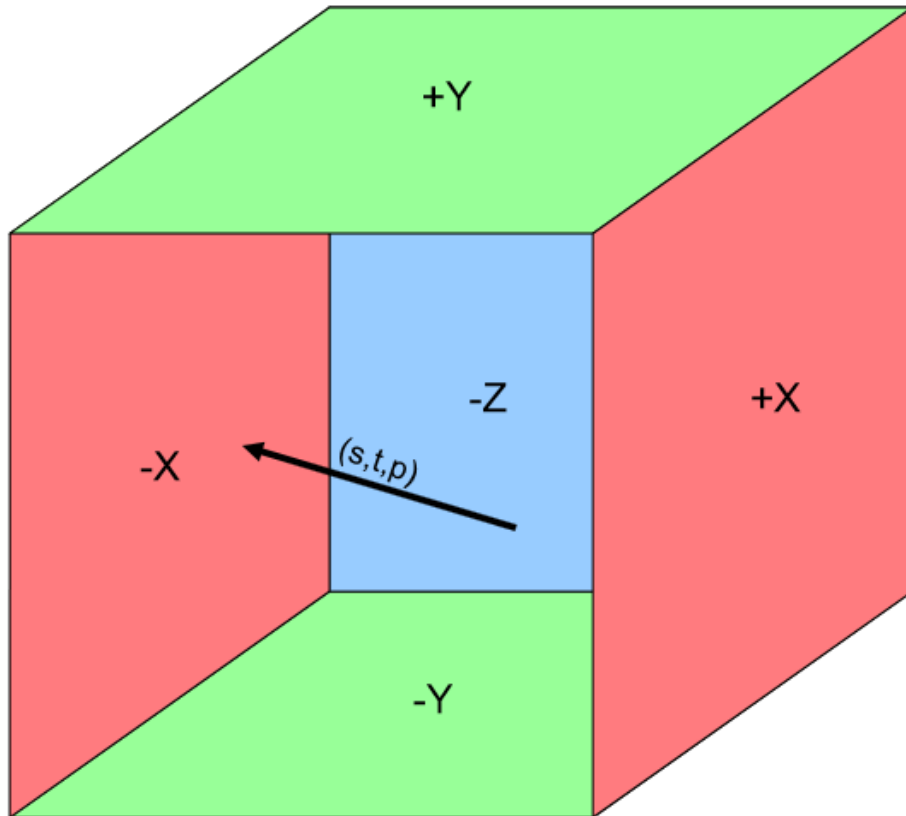
# Cube Map Layout





## Cube Map Texture Lookup:

Given an  $(s,t,p)$  direction vector, what  $(r,g,b)$  does that correspond to?



- Let  $L$  be the texture coordinate of  $(s, t, \text{ and } p)$  with the largest magnitude
- $L$  determines which of the 6 2D texture “walls” is being hit by the vector ( $-X$  in this case)
- The texture coordinates in that texture are the remaining two texture coordinates divided by  $L$ :  $(a/L, b/L)$

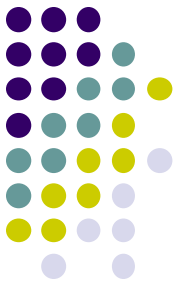
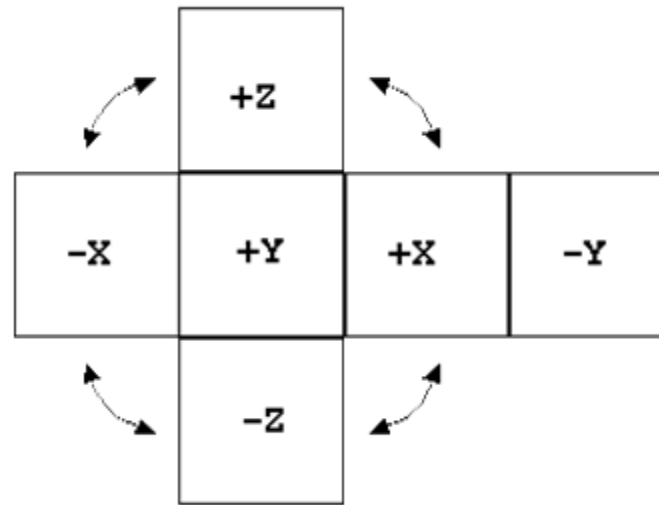
Built-in GLSL functions



```
vec3 ReflectVector = reflect( vec3 eyeDir, vec3 normal );
```

```
vec3 RefractVector = refract( vec3 eyeDir, vec3 normal, float Eta );
```

# Example



- $\mathbf{R} = (-4, 3, -1)$
- Same as  $\mathbf{R} = (-1, 0.75, -0.25)$
- Use face  $x = -1$  and  $y = 0.75, z = -0.25$
- Not quite right since cube defined by  $x, y, z = \pm 1$  rather than  $[0, 1]$  range needed for texture coordinates
- Remap by from  $[-1, 1]$  to  $[0, 1]$  range
  - $s = \frac{1}{2} + \frac{1}{2} y, t = \frac{1}{2} + \frac{1}{2} z$
- Hence,  $s = 0.875, t = 0.375$



# References

- Interactive Computer Graphics (6<sup>th</sup> edition), Angel and Shreiner
- Computer Graphics using OpenGL (3<sup>rd</sup> edition), Hill and Kelley
- Real Time Rendering by Akenine-Moller, Haines and Hoffman