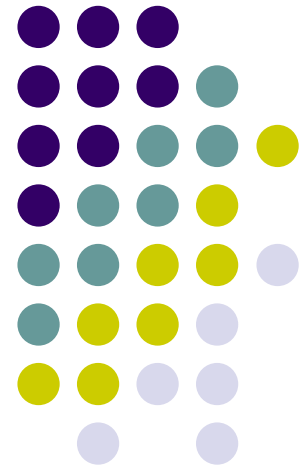


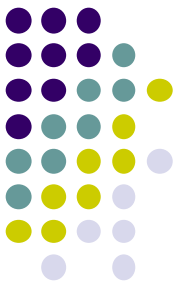
Computer Graphics (CS 4731)

Lecture 8: Building 3D Models

Prof Emmanuel Agu

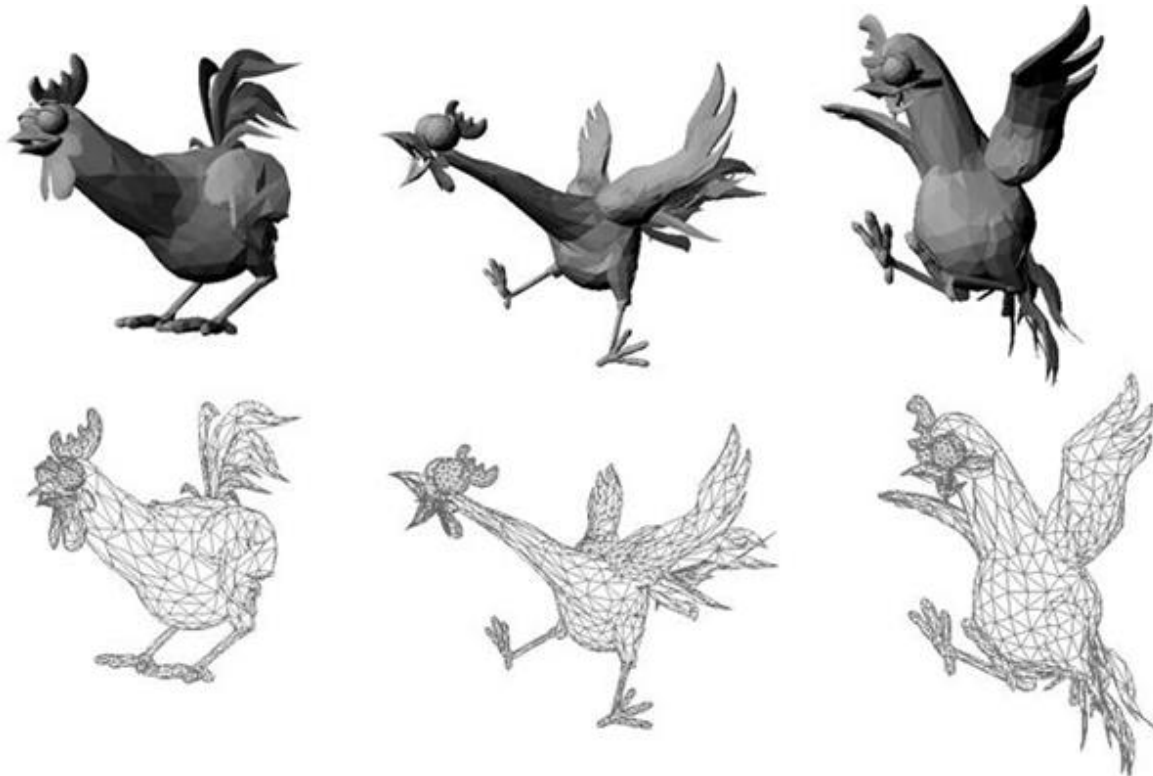
*Computer Science Dept.
Worcester Polytechnic Institute (WPI)*

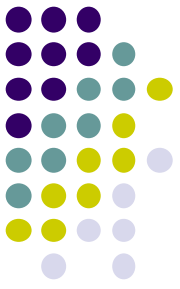




3D Applications

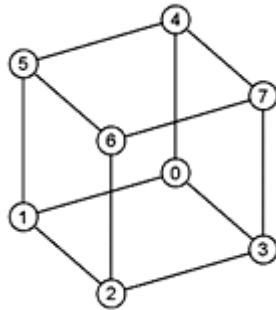
- **2D points:** (x,y) coordinates
- **3D points:** have (x,y,z) coordinates





Setting up 3D Applications: Main Steps

- Programming 3D similar to 2D
 1. Load representation of 3D object into data structure



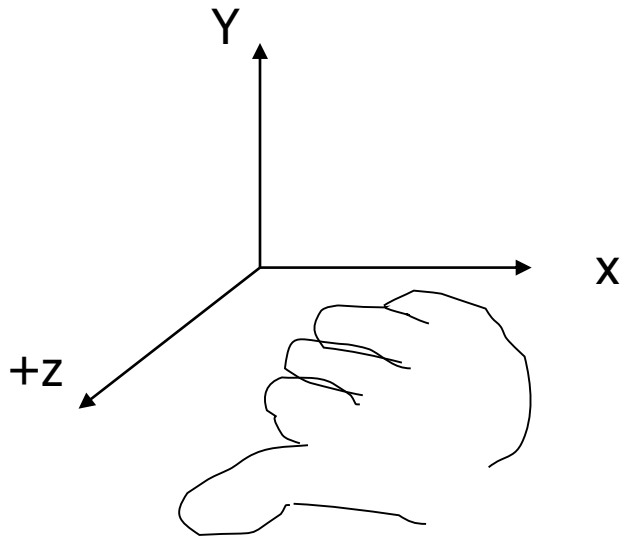
Each vertex has (x,y,z) coordinates.
Store as **vec3** NOT **vec2**

2. Draw 3D object
3. **Set up Hidden surface removal:** Correctly determine order in which primitives (triangles, faces) are rendered (e.g Blocked faces **NOT** drawn)

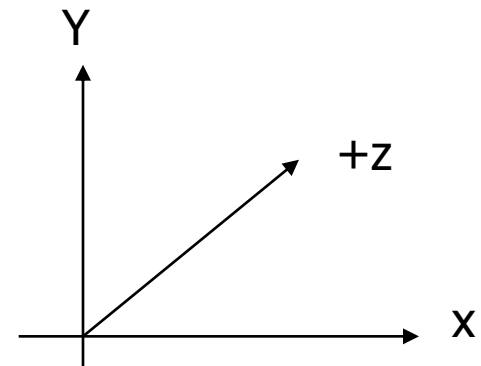


3D Coordinate Systems

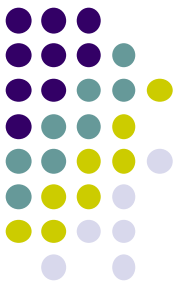
- Vertex (x,y,z) positions specified on coordinate system
- OpenGL uses **right hand coordinate system**



Right hand coordinate system
Tip: sweep fingers x-y: thumb is z

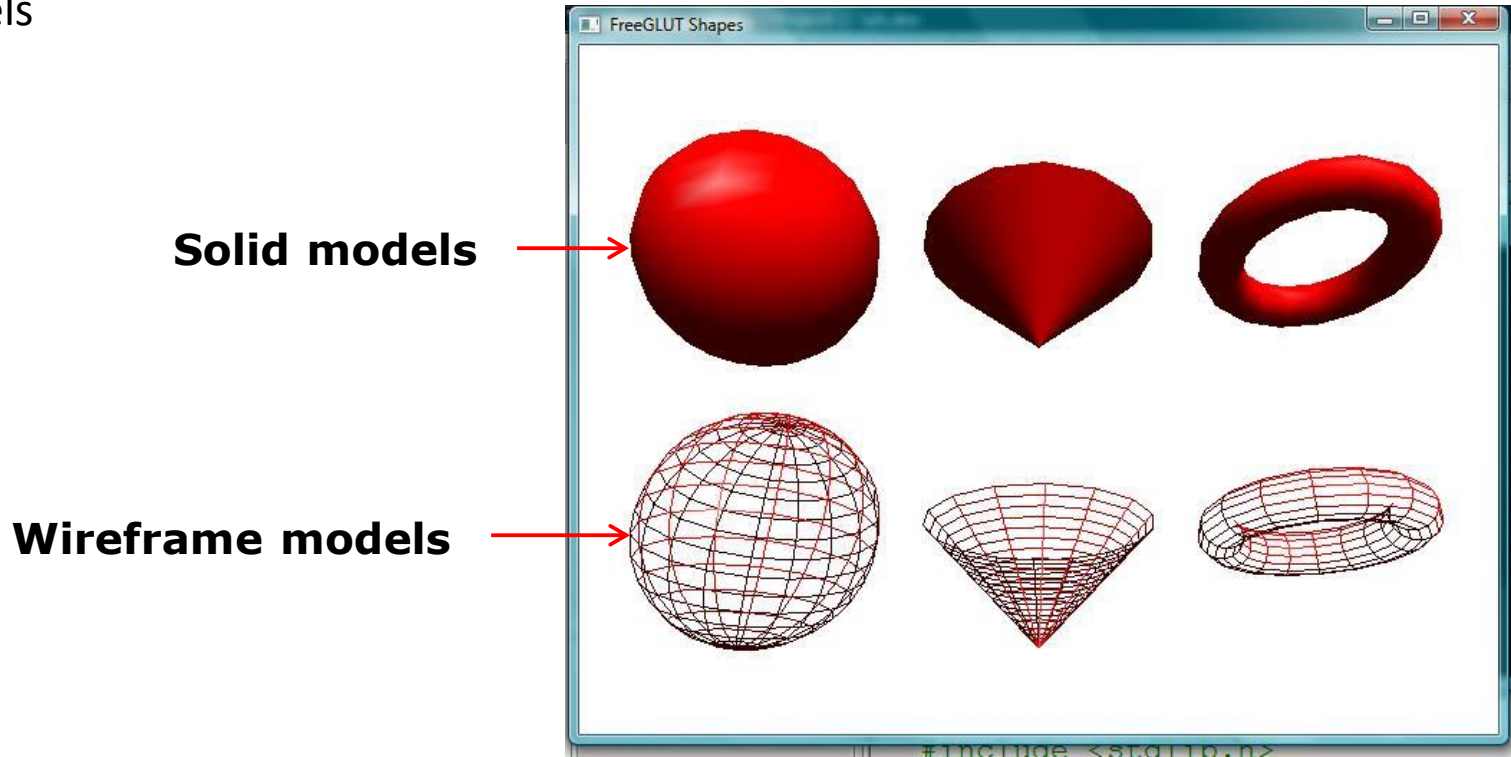


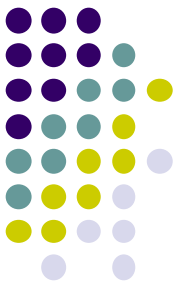
Left hand coordinate system
•Not used in OpenGL



Generating 3D Models: GLUT Models

- Make GLUT 3D calls in **OpenGL program** to generate vertices describing different shapes (Restrictive?)
- Two types of GLUT models:
 - Wireframe Models
 - Solid Models

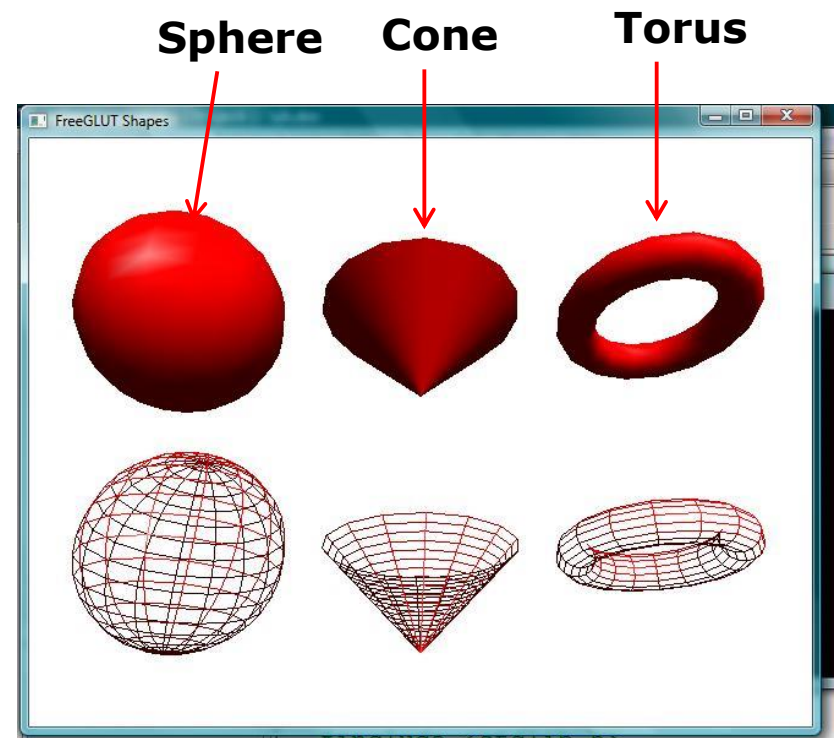
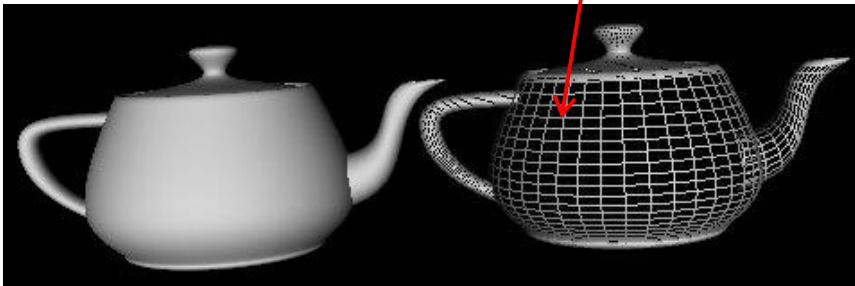


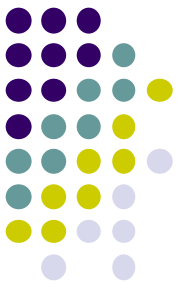


3D Modeling: GLUT Models

- Basic Shapes
 - **Cone:** `glutWireCone()`, `glutSolidCone()`
 - **Sphere:** `glutWireSphere()`, `glutSolidSphere()`
 - **Cube:** `glutWireCube()`, `glutSolidCube()`
- More advanced shapes:
 - Newell Teapot: (symbolic)
 - Dodecahedron, Torus

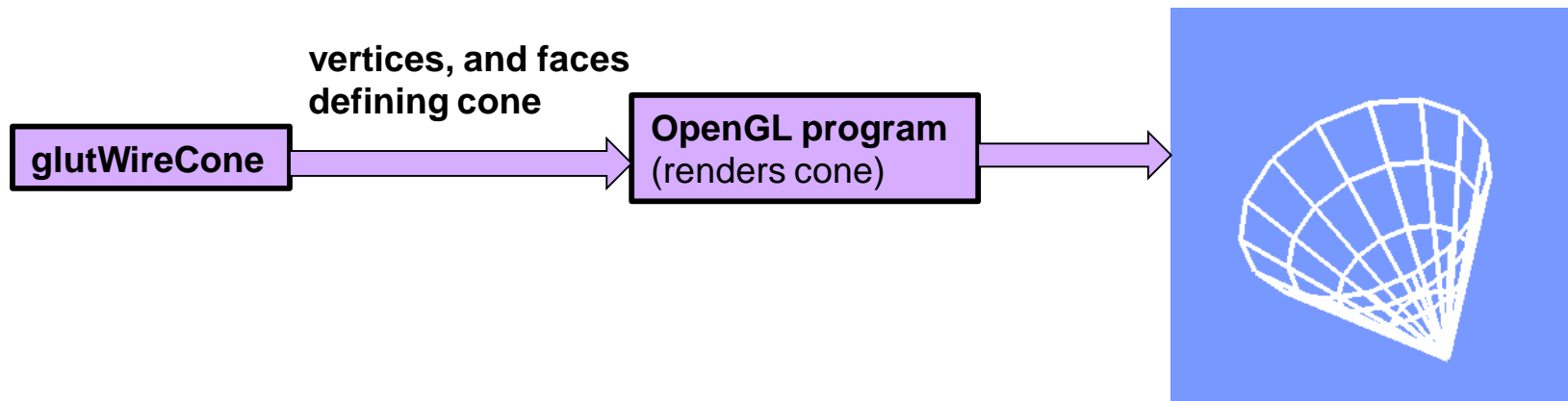
Newell Teapot

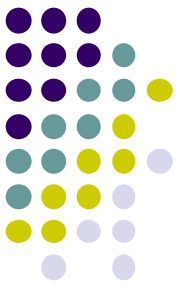




3D Modeling: GLUT Models

- Glut functions under the hood
 - generate sequence of points that define a shape
 - Generated vertices and faces passed to OpenGL for rendering
- **Example:** `glutWireCone` generates sequence of vertices, and faces defining `cone` and connectivity

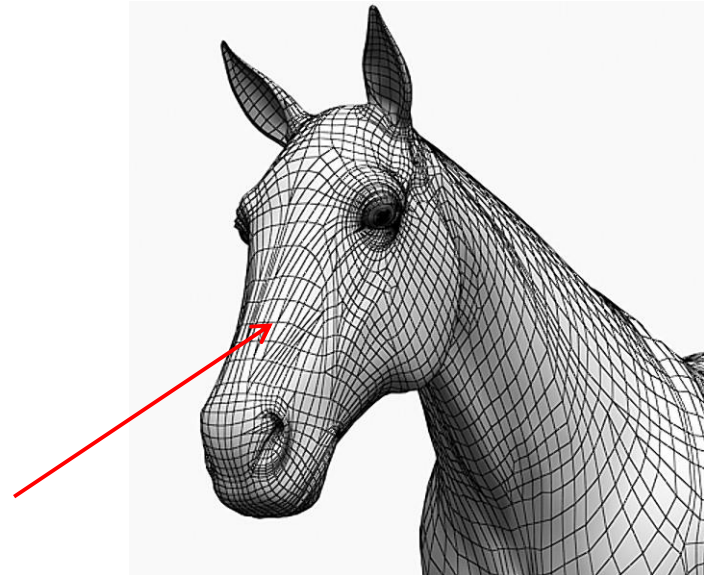




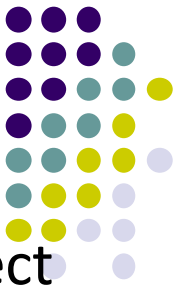
Polygonal Meshes

- Modeling with GLUT shapes (cube, sphere, etc) too restrictive
- Difficult to approach realism. E.g. model a horse
- Preferred way is using polygonal meshes:
 - Collection of polygons, or faces, that form “skin” of object
 - More flexible, represents complex surfaces better
 - Examples:
 - Human face
 - Animal structures
 - Furniture, etc

**Each face of mesh
is a polygon**

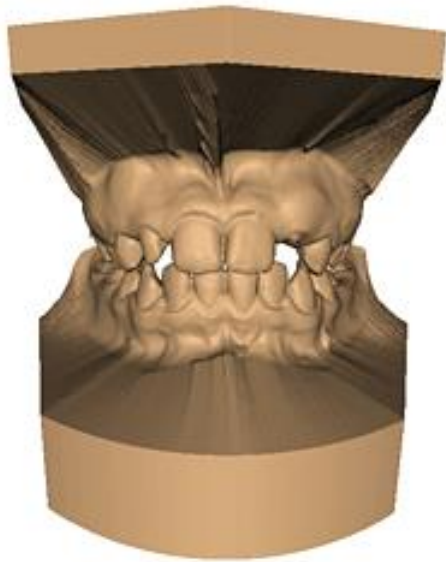
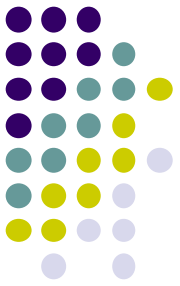


Polygonal Meshes

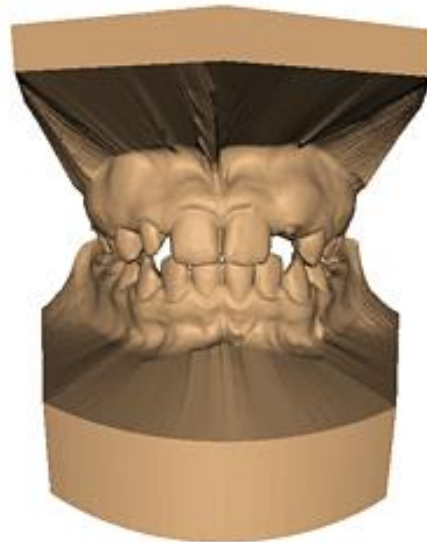


- Mesh = sequence of polygons forming thin skin around object
- OpenGL Good at drawing polygons, triangles
- Meshes now standard in graphics
- Simple meshes exact. (e.g barn)
- Complex meshes approximate (e.g. human face)

Same Mesh at Different Resolutions



**Original: 424,000
triangles**

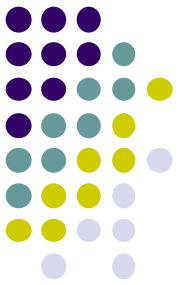


**60,000 triangles
(14%).**



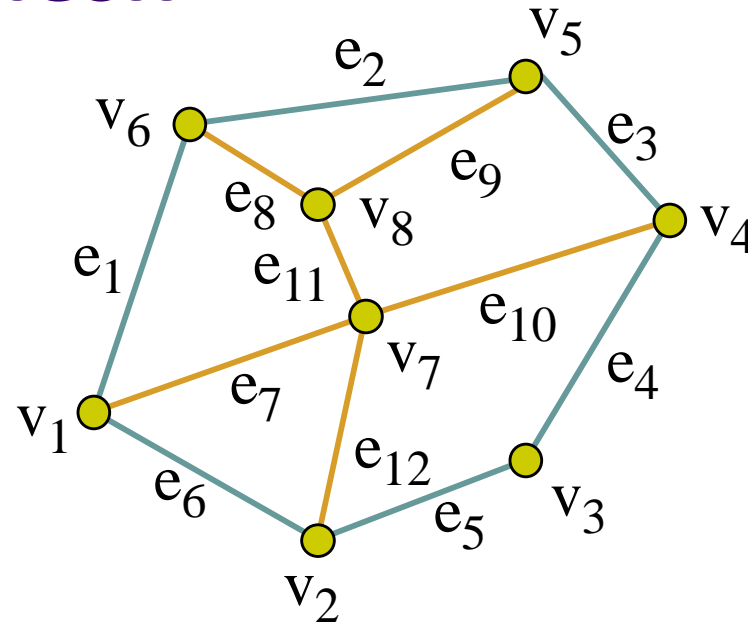
**1000 triangles
(0.2%)**

(courtesy of Michael Garland and Data courtesy of Iris Development.)

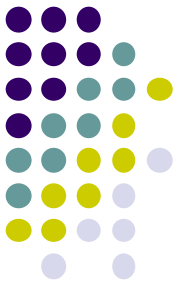


Representing a Mesh

- Consider a mesh



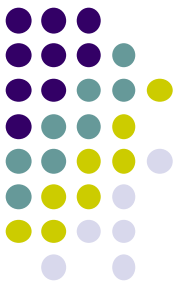
- There are 8 vertices and 12 edges
 - 5 interior polygons
 - 6 interior (shared) edges (shown in orange)
- Each vertex has a location $v_i = (x_i \ y_i \ z_i)$



Simple Representation

- Define each polygon by (x,y,z) locations of its vertices
- OpenGL code

```
vertex[i]    = vec3(x1, y1, z1);  
vertex[i+1]  = vec3(x6, y6, z6);  
vertex[i+2]  = vec3(x7, y7, z7);  
i+=3;
```



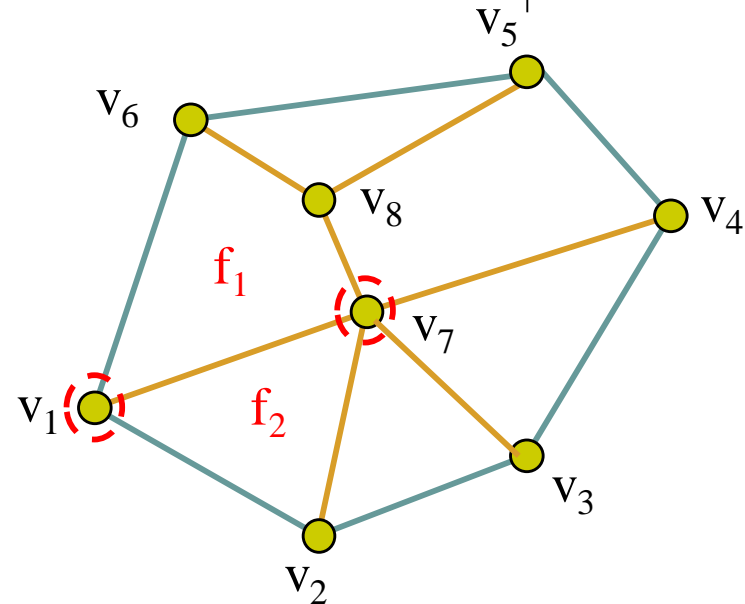
Issues with Simple Representation

- Declaring face f1

```
vertex[i] = vec3(x1, y1, z1);  
vertex[i+1] = vec3(x7, y7, z7);  
vertex[i+2] = vec3(x8, y8, z8);  
vertex[i+3] = vec3(x6, y6, z6);
```

- Declaring face f2

```
vertex[i] = vec3(x1, y1, z1);  
vertex[i+1] = vec3(x2, y2, z2);  
vertex[i+2] = vec3(x7, y7, z7);
```



- Inefficient and unstructured

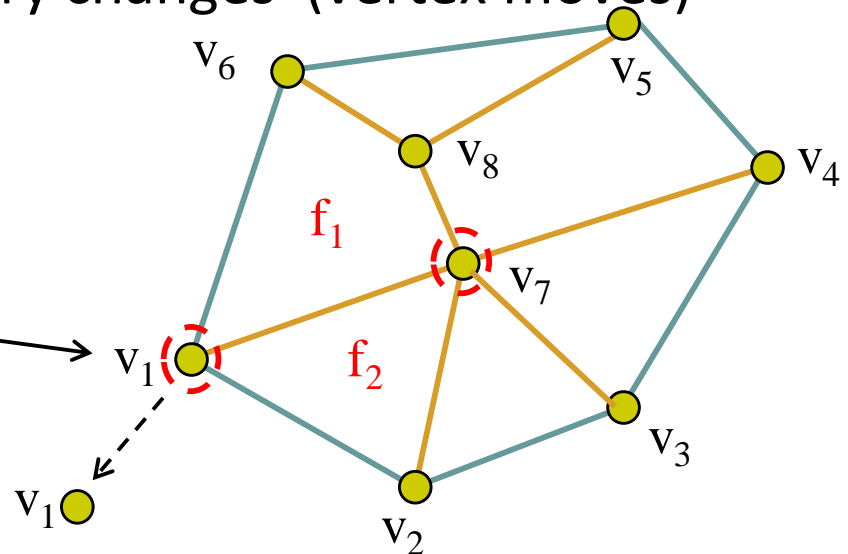
- **Repeats:** vertices **v1 and v7 repeated** while declaring f1 and f2
- Shared vertices shared declared multiple times
- Delete vertex? Move vertex? Search for all occurrences of vertex

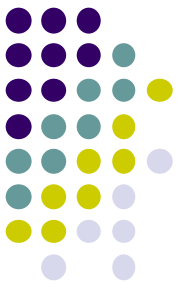


Geometry vs Topology

- **Geometry:** (x,y,z) locations of the vertices
- **Topology:** How vertices and edges are connected
- Good data structures separate **geometry** from **topology**
- **Example:**
 - A polygon is **ordered list** of vertices
 - An edge connects successive pairs of vertices
- Topology holds even if geometry changes (vertex moves)

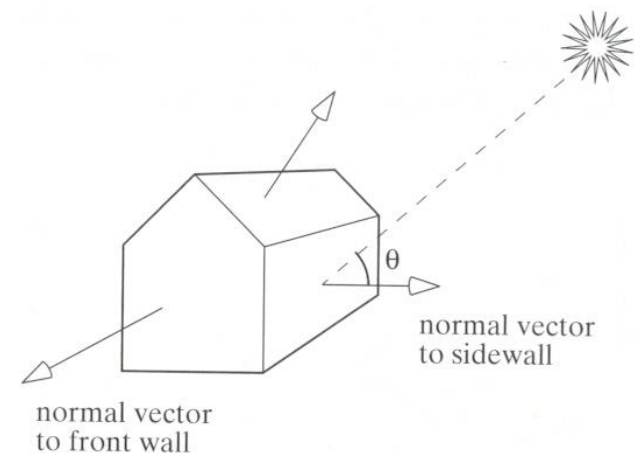
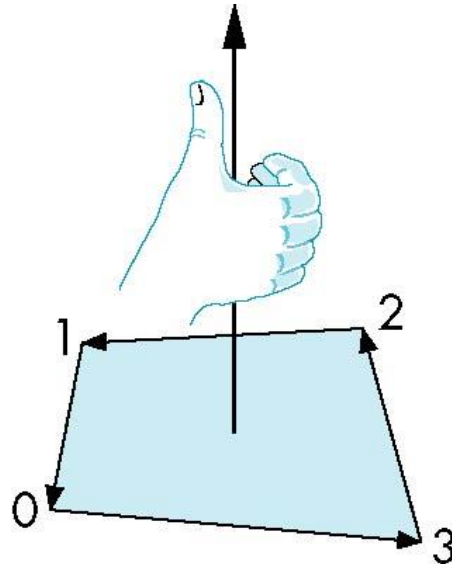
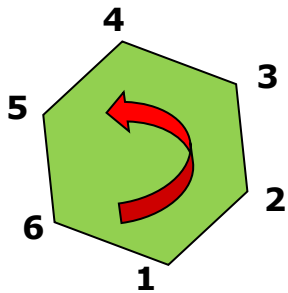
Example: even if we move (x,y,z) location of v_1 , v_1 still connected to v_6 , v_7 and v_2

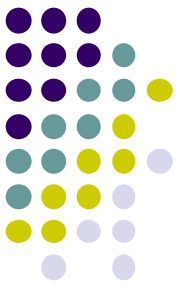




Polygon Traversal Convention

- **Convention:** traverse vertices **counter-clockwise** around normal
- Focus on direction of traversal
 - Orders $\{v_1, v_0, v_3\}$ and $\{v_3, v_2, v_1\}$ are same (*ccw*)
 - Order $\{v_1, v_2, v_3\}$ is different (*clockwise*)
- **Normal vector:** Direction each polygon is facing

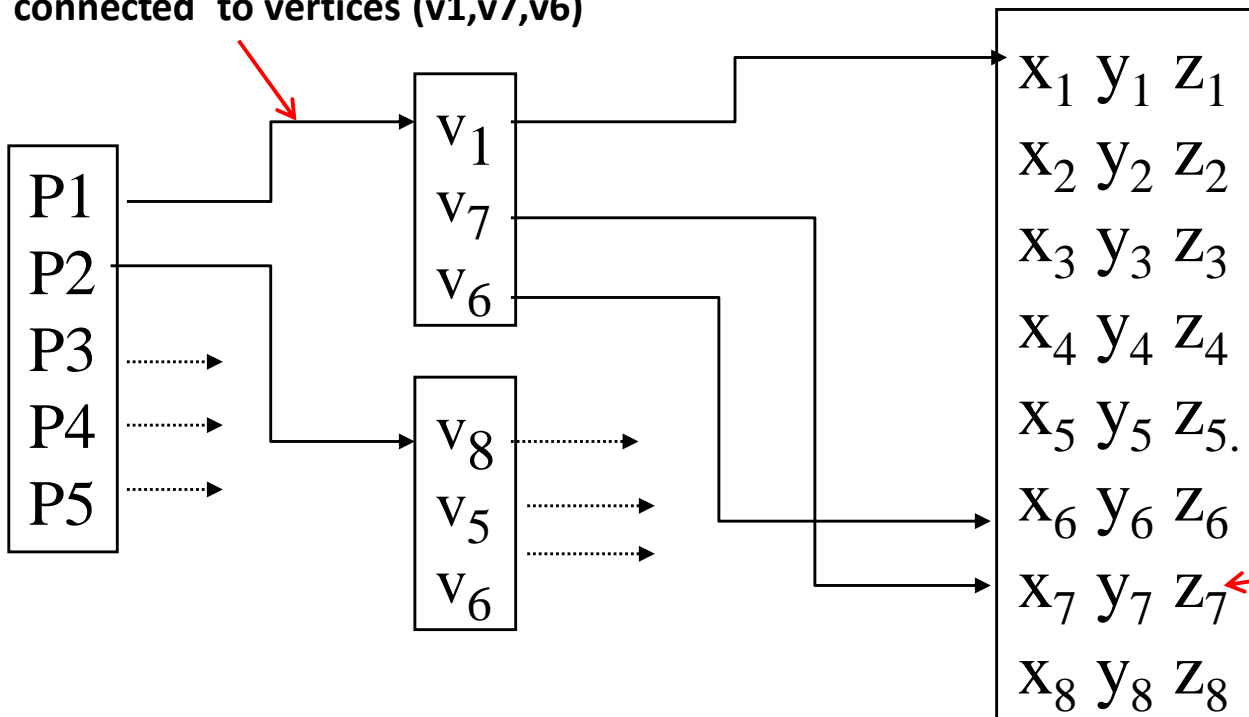




Vertex Lists

- **Vertex list:** (x,y,z) of vertices (its geometry) are put in array
- Use pointers from vertices into vertex list
- **Polygon list:** vertices connected to each polygon (face)

Topology example: Polygon P1 of mesh is connected to vertices (v1,v7,v6)

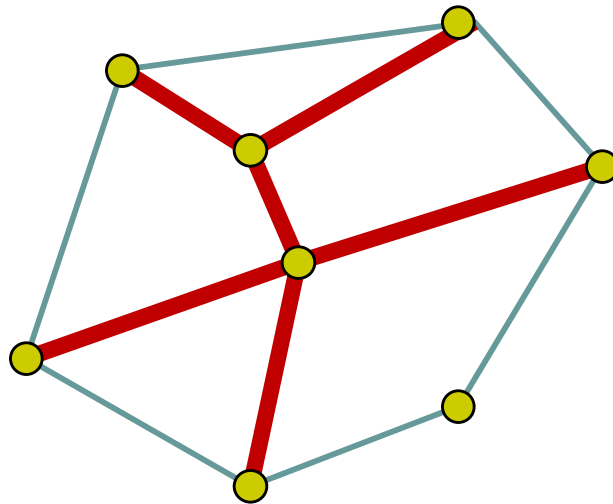


Geometry example:
Vertex v7 coordinates are (x7,y7,z7).
Note: If v7 moves, changed once in vertex list



Vertex List Issue: Shared Edges

- Vertex lists draw filled polygons correctly
- If each polygon is drawn by its edges, shared edges are drawn twice

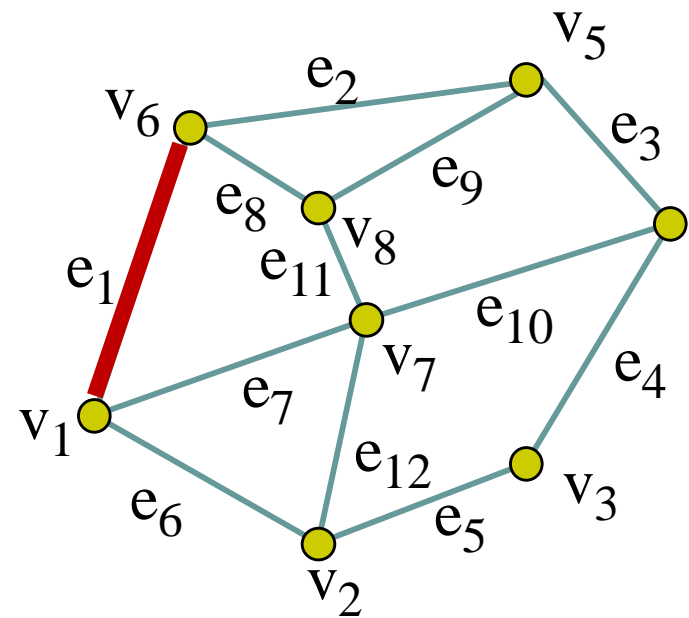
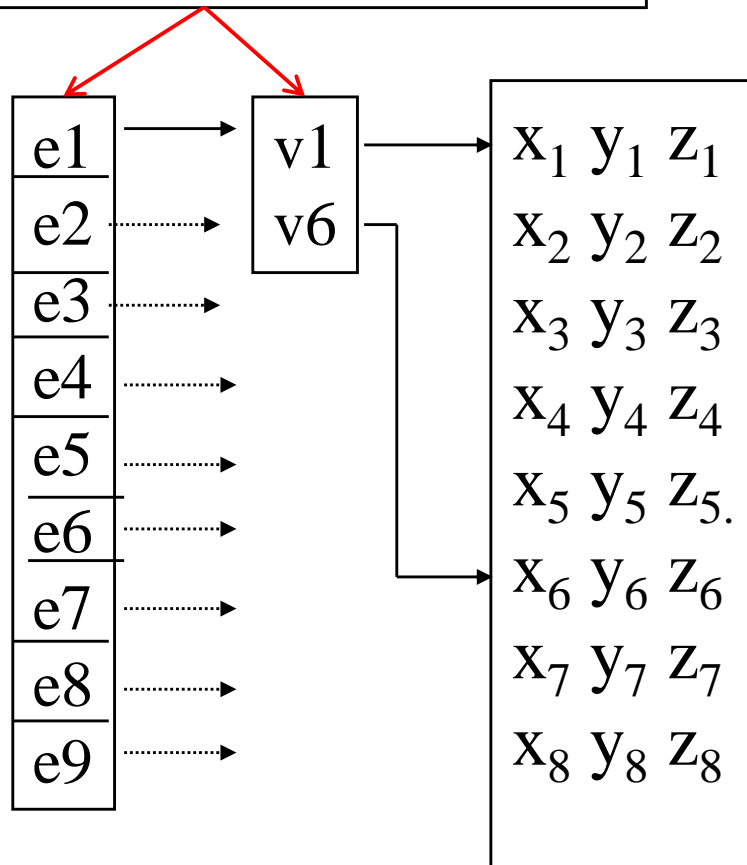


- **Alternatively:** Can store mesh by *edge list*

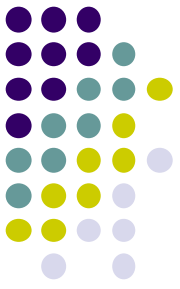


Edge List

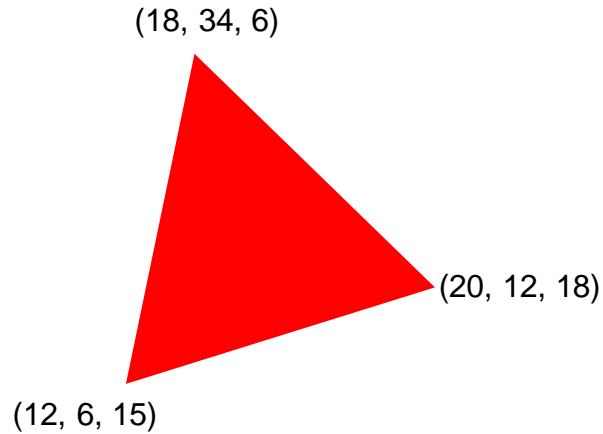
Simply draw each edges once
E.g e1 connects v1 and v6



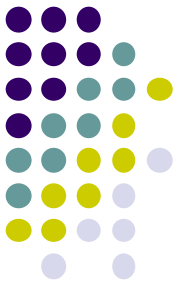
Note polygons are not represented



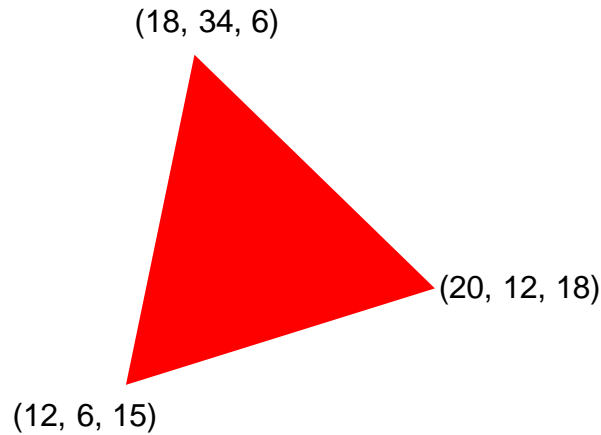
Vertex Attributes



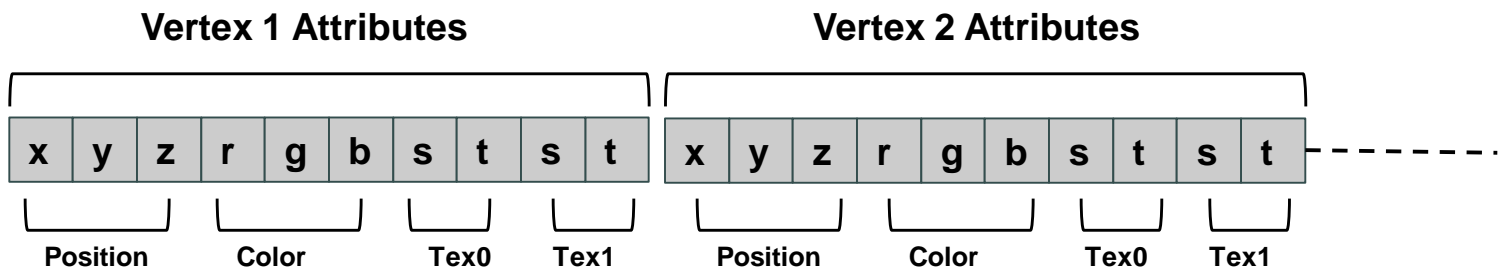
- Vertices can have attributes
 - Position (e.g 20, 12, 18)
 - Color (e.g. red)
 - Normal (x,y,z)
 - Texture coordinates

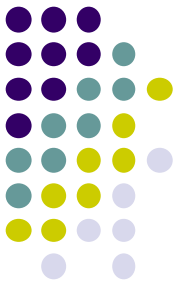


Vertex Attributes



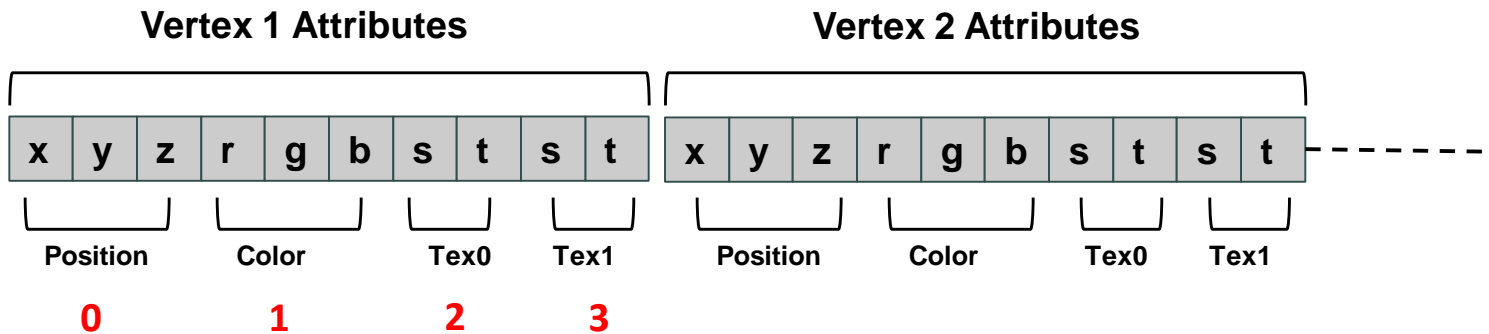
- Store vertex attributes in **single** Array (array of structures)
- **Later:** pass array to OpenGL, specify attributes, order, position using **glVertexAttribPointer**





Declaring Array of Vertex Attributes

- Consider the following array of vertex attributes

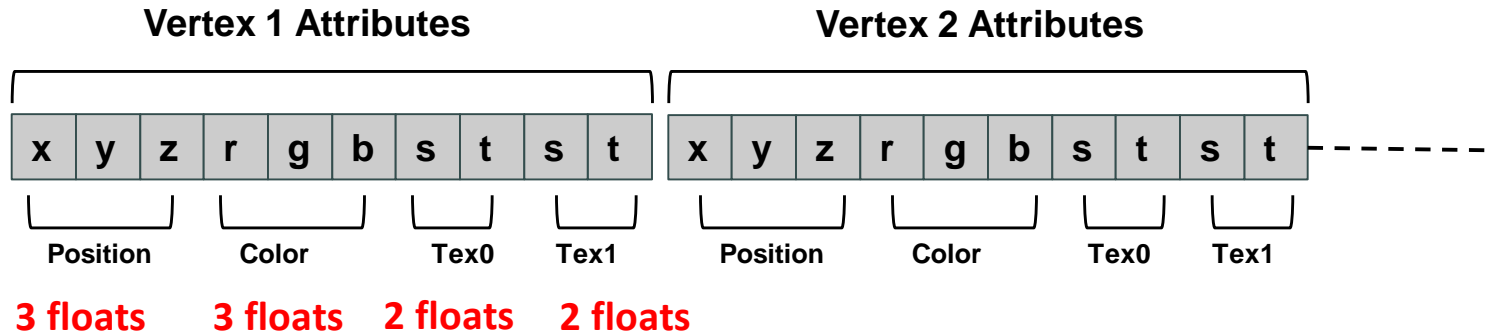


- So we can define attribute positions (per vertex)

```
#define VERTEX_POS_INDEX          0
#define VERTEX_COLOR_INDEX       1
#define VERTEX_TEXCOORD0_INDEX   2
#define VERTEX_TEXCOORD1_INDEX   3
```



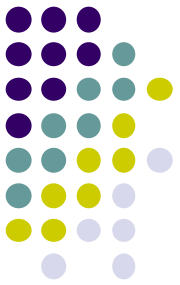
Declaring Array of Vertex Attributes



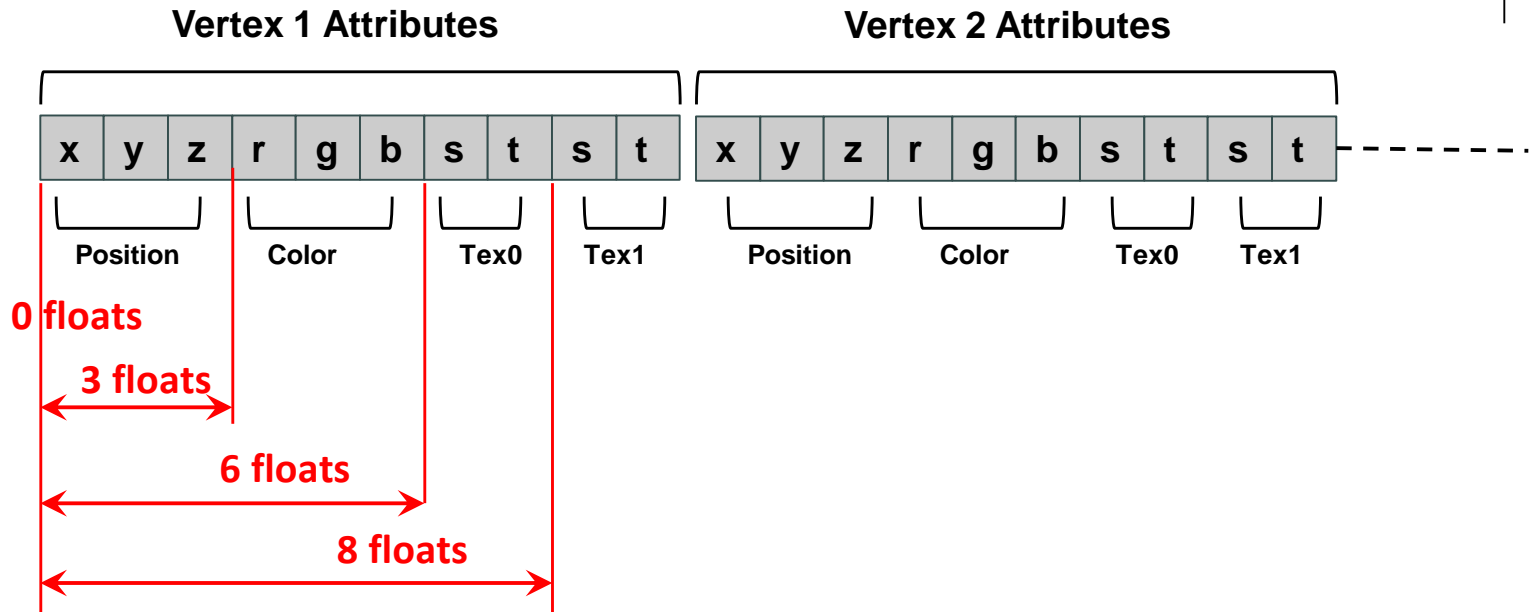
- Also define number of floats (storage) for each vertex attribute

```
#define VERTEX_POS_SIZE          3      // x, y and z
#define VERTEX_COLOR_SIZE       3      // r, g and b
#define VERTEX_TEXCOORD0_SIZE   2      // s and t
#define VERTEX_TEXCOORD1_SIZE   2      // s and t

#define VERTEX_ATTRIB_SIZE      VERTEX_POS_SIZE + VERTEX_COLOR_SIZE + \
                                VERTEX_TEXCOORD0_SIZE + \
                                VERTEX_TEXCOORD1_SIZE
```



Declaring Array of Vertex Attributes

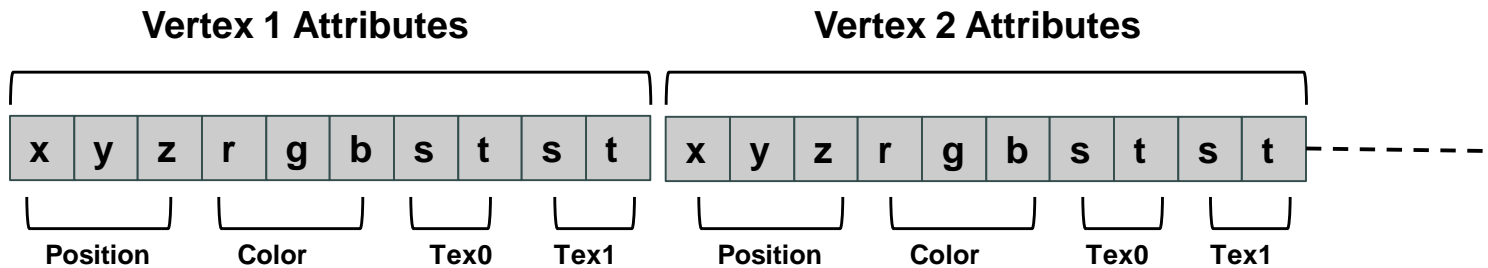


- Define offsets (# of floats) of each vertex attribute from beginning

```
#define VERTEX_POS_OFFSET                      0  
#define VERTEX_COLOR_OFFSET                  3  
#define VERTEX_TEXCOORD0_OFFSET              6  
#define VERTEX_TEXCOORD1_OFFSET              8
```



Allocating Array of Vertex Attributes



- Allocate memory for entire array of vertex attributes

Recall

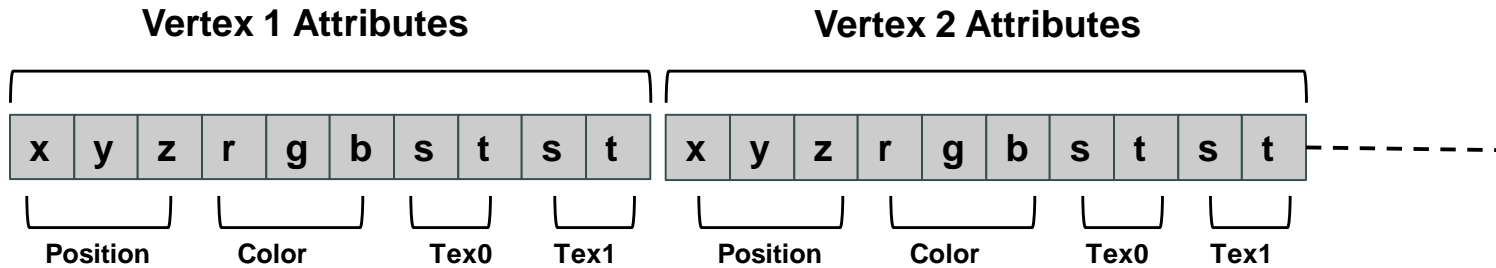
```
#define VERTEX_ATTRIB_SIZE    VERTEX_POS_SIZE + VERTEX_COLOR_SIZE + \
                             VERTEX_TEXCOORD0_SIZE + \
                             VERTEX_TEXCOORD1_SIZE
```

```
float *p = malloc(numVertices * VERTEX_ATTRIB_SIZE * sizeof(float));
```

Allocate memory for all vertices



Specifying Array of Vertex Attributes



- **glVertexAttribPointer** used to specify vertex attributes
- Example: to specify vertex position attribute

```
glVertexAttribPointer(VERTEX_POS_INDX, VERTEX_POS_SIZE,  
GL_FLOAT, GL_FALSE,  
VERTEX_ATTRIB_SIZE * sizeof(float), p);  
glEnableVertexAttribArray(0);
```

Position 0 (points to VERTEX_POS_INDX)

3 values (x, y, z) (points to VERTEX_POS_SIZE)

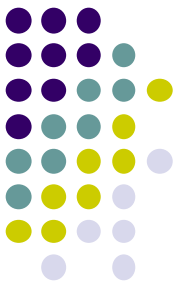
Data is floats (points to GL_FLOAT)

Data should not Be normalized (points to GL_FALSE)

Stride: distance between consecutive vertices (points to VERTEX_ATTRIB_SIZE * sizeof(float))

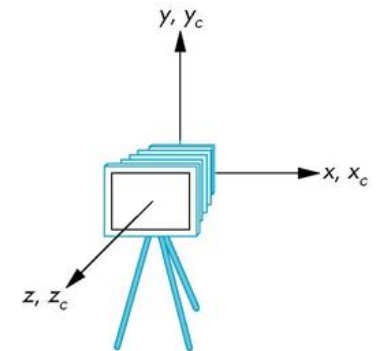
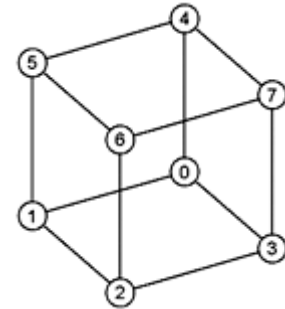
Pointer to data (points to p)

- do same for normal, tex0 and tex1



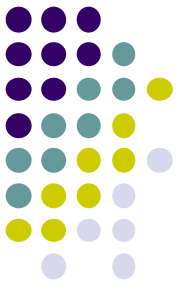
Full Example: Rotating Cube in 3D

- **Desired Program behaviour:**
 - Draw colored cube
 - Continuous rotation about X,Y or Z axis
 - Idle function called repeatedly when nothing to do
 - Increment angle of rotation in idle function
 - Use 3-button mouse to change direction of rotation
 - Click left button -> rotate cube around X axis
 - Click middle button -> rotate cube around Y axis
 - Click right button -> rotate cube around Z axis
- Use default camera
 - If we don't set camera, we get a default camera
 - Located at origin and points in the negative z direction



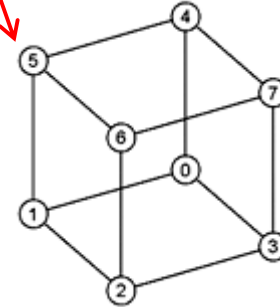
(a)

Cube Vertices



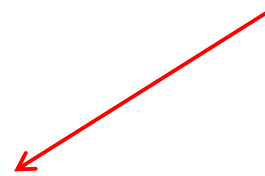
Declare array of (x,y,z,w) vertex positions
for a unit cube centered at origin
(Sides aligned with axes)

```
point4 vertices[8] = {  
0 point4( -0.5, -0.5,  0.5, 1.0 ),  
1 point4( -0.5,  0.5,  0.5, 1.0 ),  
2 point4(  0.5,  0.5,  0.5, 1.0 ),  
3 point4(  0.5, -0.5,  0.5, 1.0 ),  
4 point4( -0.5, -0.5, -0.5, 1.0 ),  
5 point4( -0.5,  0.5, -0.5, 1.0 ),  
6 point4(  0.5,  0.5, -0.5, 1.0 ),  
7 point4(  0.5, -0.5, -0.5, 1.0 )  
};
```



```
color4 vertex_colors[8] = {  
    color4( 0.0, 0.0, 0.0, 1.0 ), // black  
    color4( 1.0, 0.0, 0.0, 1.0 ), // red  
    color4( 1.0, 1.0, 0.0, 1.0 ), // yellow  
    color4( 0.0, 1.0, 0.0, 1.0 ), // green  
    color4( 0.0, 0.0, 1.0, 1.0 ), // blue  
    color4( 1.0, 0.0, 1.0, 1.0 ), // magenta  
    color4( 1.0, 1.0, 1.0, 1.0 ), // white  
    color4( 0.0, 1.0, 1.0, 1.0 ) // cyan  
};
```

Declare array of vertex colors
(set of RGBA colors vertex can have)

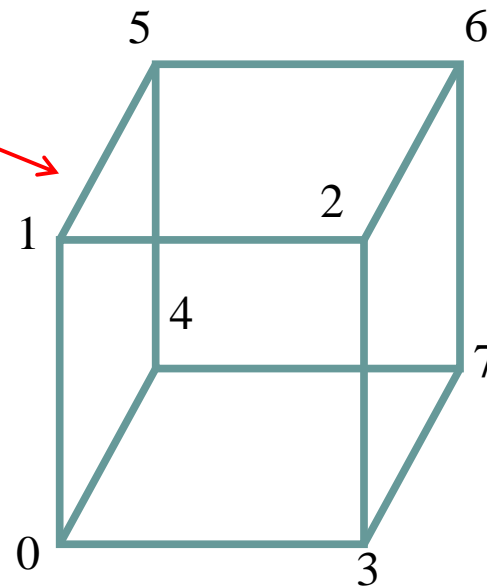


Color Cube

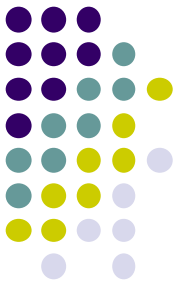


```
// generate 6 quads,  
// sides of cube  
  
void colorcube()  
{  
    quad( 1, 0, 3, 2 );  
    quad( 2, 3, 7, 6 );  
    quad( 3, 0, 4, 7 );  
    quad( 6, 5, 1, 2 );  
    quad( 4, 5, 6, 7 );  
    quad( 5, 4, 0, 1 );  
}
```

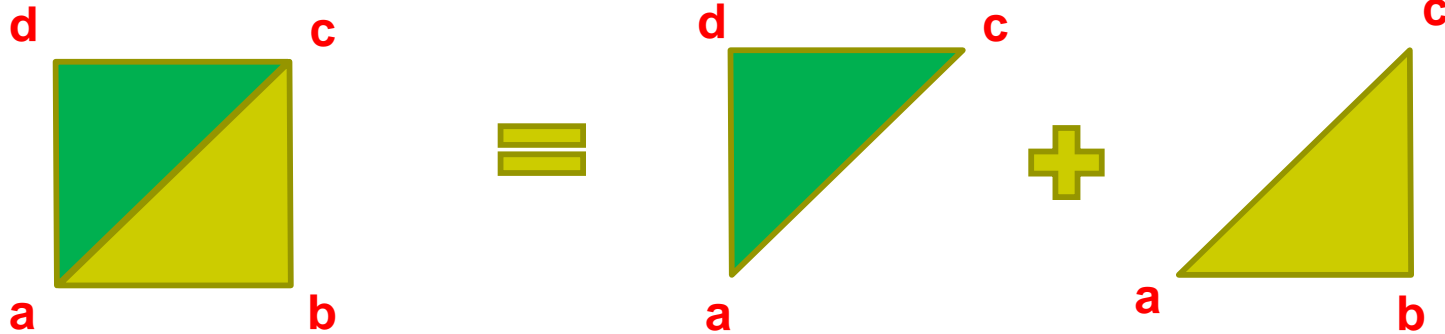
```
point4 vertices[8] = {  
    0 point4( -0.5, -0.5,  0.5, 1.0 ),  
    1 point4( -0.5,  0.5,  0.5, 1.0 ),  
    point4(  0.5,  0.5,  0.5, 1.0 ),  
    point4(  0.5, -0.5,  0.5, 1.0 ),  
    4 point4( -0.5, -0.5, -0.5, 1.0 ),  
    5 point4( -0.5,  0.5, -0.5, 1.0 ),  
    point4(  0.5,  0.5, -0.5, 1.0 ),  
    point4(  0.5, -0.5, -0.5, 1.0 )  
};
```



Function **quad** is
Passed vertex indices



Quad Function



```
// quad generates two triangles (a,b,c) and (a,c,d) for each face
// and assigns colors to the vertices
```

```
int Index = 0; // Index goes 0 to 5, one for each vertex of face
```

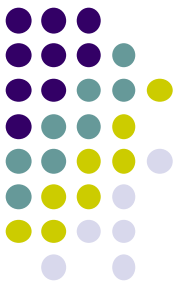
```
void quad( int a, int b, int c, int d )
```

```
{
  0 colors[Index] = vertex_colors[a]; points[Index] = vertices[a]; Index++;
  1 colors[Index] = vertex_colors[b]; points[Index] = vertices[b]; Index++;
  2 colors[Index] = vertex_colors[c]; points[Index] = vertices[c]; Index++;
  3 colors[Index] = vertex_colors[a]; points[Index] = vertices[a]; Index++;
  4 colors[Index] = vertex_colors[c]; points[Index] = vertices[c]; Index++;
  5 colors[Index] = vertex_colors[d]; points[Index] = vertices[d]; Index++;
}
```

quad 0 = points[0 - 5]
quad 1 = points[6 - 11]
quad 2 = points [12 - 17] ...etc

Points[] array to be
Sent to GPU

Read from appropriate index
of unique positions declared



Initialization I

```
void init()
{
    colorcube(); // Generates cube data in application using quads

    // Create a vertex array object
    GLuint vao;
    glGenVertexArrays ( 1, &vao );
    glBindVertexArray ( vao );

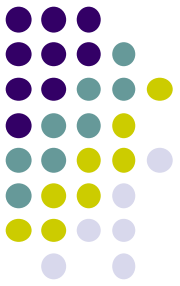
    // Create a buffer object and move data to GPU
    GLuint buffer;
    glGenBuffers( 1, &buffer );
    glBindBuffer( GL_ARRAY_BUFFER, buffer );
    glBufferData( GL_ARRAY_BUFFER, sizeof(points) +
                 sizeof(colors), NULL, GL_STATIC_DRAW );
}
```



Points[] array of vertex positions sent to GPU

colors[] array of vertex colors sent to GPU

Initialization II



Send `points[]` and `colors[]` data to GPU separately using `glBufferSubData`

```
glBufferSubData( GL_ARRAY_BUFFER, 0, sizeof(points), points );  
glBufferSubData( GL_ARRAY_BUFFER, sizeof(points), sizeof(colors), colors );
```



```
// Load vertex and fragment shaders and use the resulting shader program  
GLuint program = InitShader( "vshader36.glsl", "fshader36.glsl" );  
glUseProgram( program );
```

Initialization III



// set up vertex arrays

```
GLuint vPosition = glGetAttribLocation( program, "vPosition" );
glEnableVertexAttribArray( vPosition );
glVertexAttribPointer( vPosition, 4, GL_FLOAT, GL_FALSE, 0,
    BUFFER_OFFSET(0) );
```

Specify vertex data

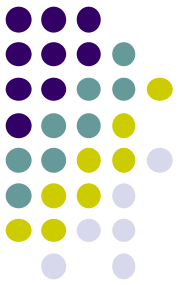
```
GLuint vColor = glGetAttribLocation( program, "vColor" );
glEnableVertexAttribArray( vColor );
glVertexAttribPointer( vColor, 4, GL_FLOAT, GL_FALSE, 0,
    BUFFER_OFFSET(sizeof(points)) );
```

Specify color data



```
theta = glGetUniformLocation( program, "theta" );
```

**Want to Connect rotation variable theta
in program to variable in shader**



Display Callback

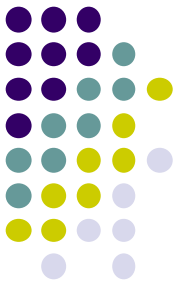
```
void display( void )
{
    glClear( GL_COLOR_BUFFER_BIT|GL_DEPTH_BUFFER_BIT );

    glUniform3fv( theta, 1, theta );
    glDrawArrays( GL_TRIANGLES, 0, NumVertices );

    glutSwapBuffers();
}
```

Draw series of triangles forming cube

A red arrow originates from the text 'Draw series of triangles forming cube' and points upwards to the 'glDrawArrays' line in the code block above.

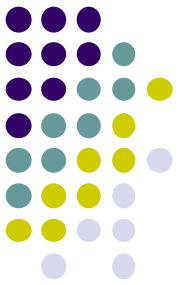


Mouse Callback

```
...
enum { Xaxis = 0, Yaxis = 1, Zaxis = 2, NumAxes = 3 };

void mouse( int button, int state, int x, int y )
{
    if ( state == GLUT_DOWN ) {
        switch( button ) {
            case GLUT_LEFT_BUTTON:    axis = Xaxis;  break;
            case GLUT_MIDDLE_BUTTON:  axis = Yaxis;  break;
            case GLUT_RIGHT_BUTTON:   axis = Zaxis;  break;
        }
    }
}
```

Select axis (x,y,z) to rotate around
Using mouse click



Idle Callback

```
void idle( void )  
{  
    theta[axis] += 0.01;  
  
    if ( theta[axis] > 360.0 ) {  
        theta[axis] -= 360.0;  
    }  
  
    glutPostRedisplay();  
}
```

The idle() function is called whenever nothing to do

Use it to increment rotation angle in steps of $\theta = 0.01$ around currently selected axis

```
void main( void ){  
    .....  
  
    glutIdleFunc( idle );  
    .....  
}
```

Note: still need to:

- Apply rotation by (θ) in shader



References

- Angel and Shreiner, Interactive Computer Graphics, 6th edition, Chapter 3
- Hill and Kelley, Computer Graphics using OpenGL, 3rd edition