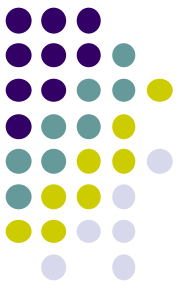




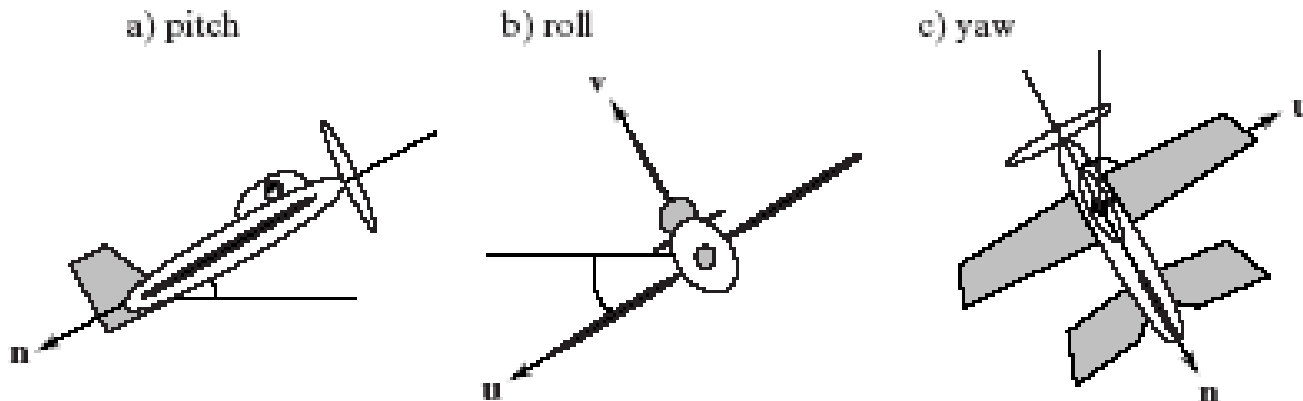
## Other Camera Controls

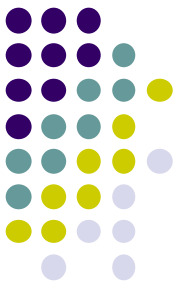
- The LookAt function is only for positioning camera
- Other ways to specify camera position/movement
  - Yaw, pitch, roll
  - Elevation, azimuth, twist
  - Direction angles



# Flexible Camera Control

- Sometimes, we want camera to move
- Like controlling an airplane's orientation
- Adopt aviation terms:
  - **Pitch:** nose up-down
  - **Roll:** roll body of plane
  - **Yaw:** move nose side to side

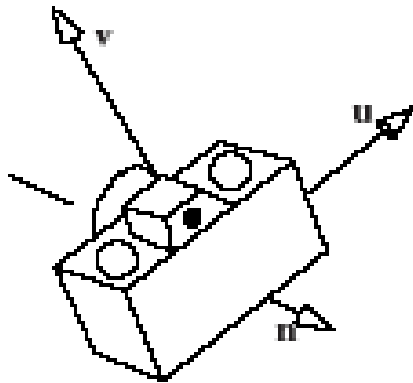




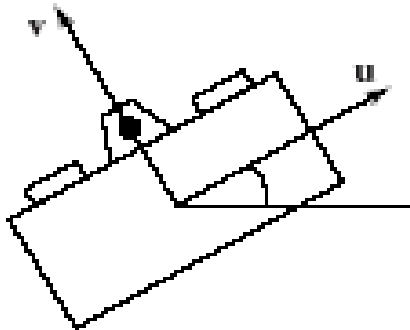
# Yaw, Pitch and Roll Applied to Camera

- Similarly, yaw, pitch, roll with a camera

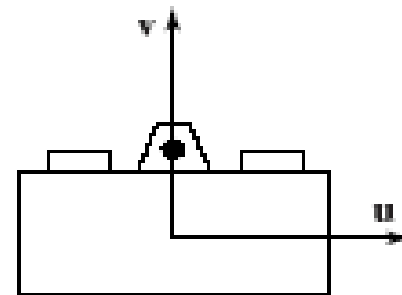
a) camera orientation

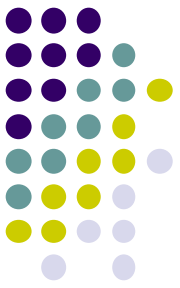


b) with roll



c) no roll

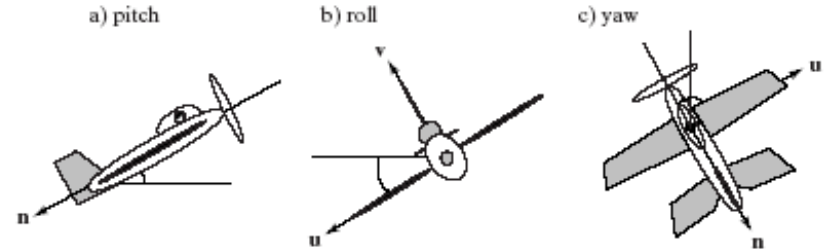




# Flexible Camera Control

- Create a camera class

```
class Camera
  private:
    Point3 eye;
    Vector3 u, v, n;... etc
```

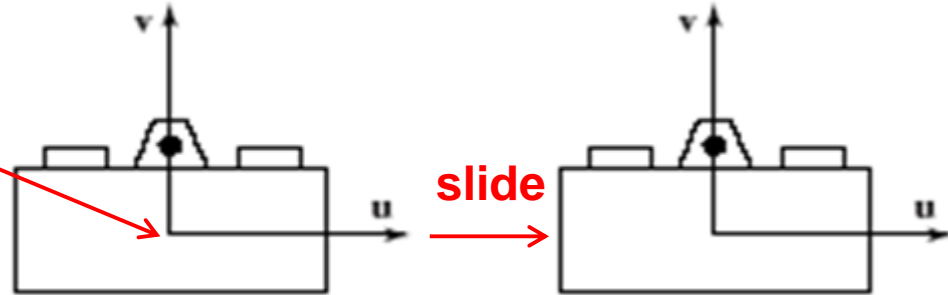


- Camera functions to specify pitch, roll, yaw. E.g

```
cam.slide(1, 0, 2); // slide camera backward 2 and right 1
cam.roll(30); // roll camera 30 degrees
cam.yaw(40); // yaw it 40 degrees
cam.pitch(20); // pitch it 20 degrees
```

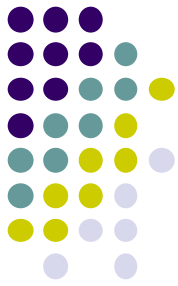
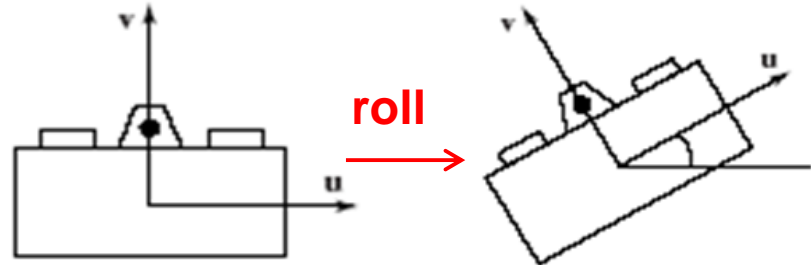
# Recall: Final LookAt Matrix

- Slide along u, v or n
- Changes eye position
- Changes these components



$$\begin{bmatrix} ux & uy & uz & -\mathbf{e} \cdot \mathbf{u} \\ vx & vy & vz & -\mathbf{e} \cdot \mathbf{v} \\ nx & ny & nz & -\mathbf{e} \cdot \mathbf{n} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- Pitch, yaw, roll rotates u, v or n
- Changes u, v or n





# Implementing Flexible Camera Control

- Camera class: maintains current  $(u, v, n)$  and eye position

```
class Camera
private:
    Point3 eye;
    Vector3 u, v, n;... etc
```

- User inputs desired roll, pitch, yaw angle or slide
  1. Roll, pitch, yaw: calculate modified vector  $(u', v', n')$
  2. Slide: Calculate new eye position
  3. Update lookAt matrix, Load it into CTM



# Example: Camera Slide

- Recall: the axes are unit vectors
- User changes eye by delU, delV or delN
- $\text{eye} = \text{eye} + \text{changes}(\text{delU}, \text{delV}, \text{delN})$
- Note: function below combines all slides into one  
E.g moving camera by  **$D$**  along its u axis =  **$\text{eye} + D\mathbf{u}$**

```
void camera::slide(float delU, float delV, float delN)
{
    eye.x += delU*u.x + delV*v.x + delN*n.x;
    eye.y += delU*u.y + delV*v.y + delN*n.y;
    eye.z += delU*u.z + delV*v.z + delN*n.z;
    setModelViewMatrix( );
}
```

# Load Matrix into CTM

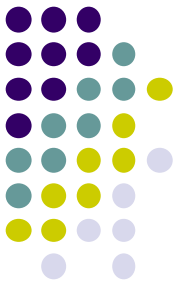


$$\begin{array}{ccc|c} ux & uy & uz & -\mathbf{e} \cdot \mathbf{u} \\ vx & vy & vz & -\mathbf{e} \cdot \mathbf{v} \\ nx & ny & nz & -\mathbf{e} \cdot \mathbf{n} \\ 0 & 0 & 0 & 1 \end{array}$$

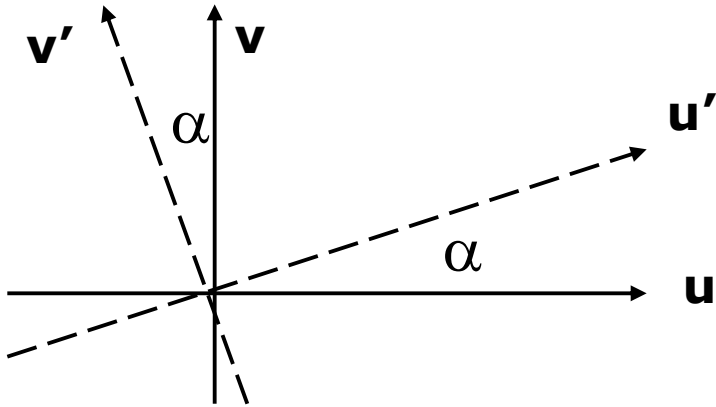
```
void Camera::setModelViewMatrix(void)
{ // load modelview matrix with camera values
  mat4 m;
  Vector3 eVec(eye.x, eye.y, eye.z); // eye as vector
  m[0] = u.x; m[4] = u.y; m[8] = u.z; m[12] = -dot(eVec,u);
  m[1] = v.x; m[5] = v.y; m[9] = v.z; m[13] = -dot(eVec,v);
  m[2] = n.x; m[6] = n.y; m[10] = n.z; m[14] = -dot(eVec,n);
  m[3] = 0; m[7] = 0; m[11] = 0; m[15] = 1.0;
  CTM = m; // Finally, load matrix m into CTM Matrix
}
```

- Slide changes **eVec**,
- roll, pitch, yaw, change **u, v, n**
- Call setModelViewMatrix after slide, roll, pitch or yaw





# Example: Camera Roll



$$\mathbf{u}' = \cos(\alpha)\mathbf{u} + \sin(\alpha)\mathbf{v}$$

$$\mathbf{v}' = -\sin(\alpha)\mathbf{u} + \cos(\alpha)\mathbf{v}$$

```
void Camera::roll(float angle)
{ // roll the camera through angle degrees
  float cs = cos(3.142/180 * angle);
  float sn = sin(3.142/180 * angle);
  Vector3 t = u; // remember old u
  u.set(cs*t.x - sn*v.x, cs*t.y - sn*v.y, cs*t.z - sn*v.z);
  v.set(sn*t.x + cs*v.x, sn*t.y + cs*v.y, sn*t.z + cs*v.z)
  setModelViewMatrix( );
}
```

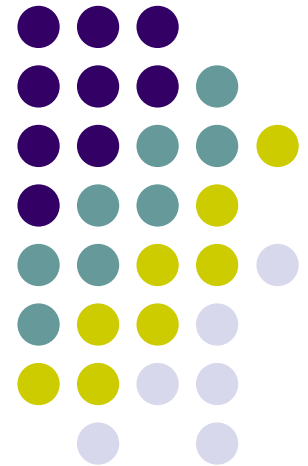
# Computer Graphics (CS 4731)

## Lecture 14: Projection (Part I)

---

Prof Emmanuel Agu

*Computer Science Dept.  
Worcester Polytechnic Institute (WPI)*



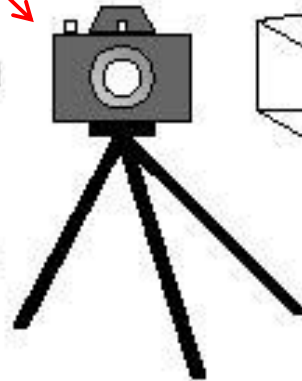


# Recall: 3D Viewing and View Volume

**Previously:**  
**Lookat( )** to set  
camera position

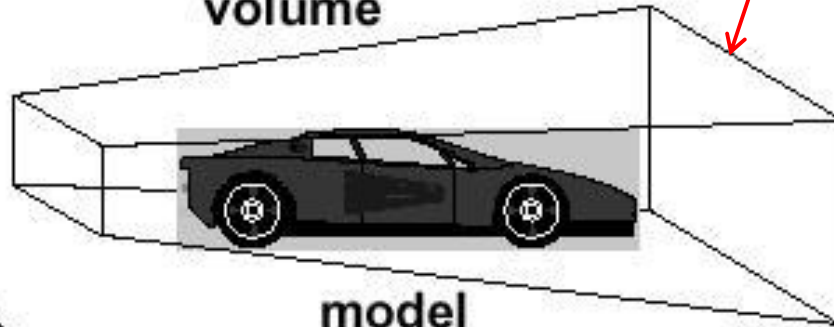
camera

tripod



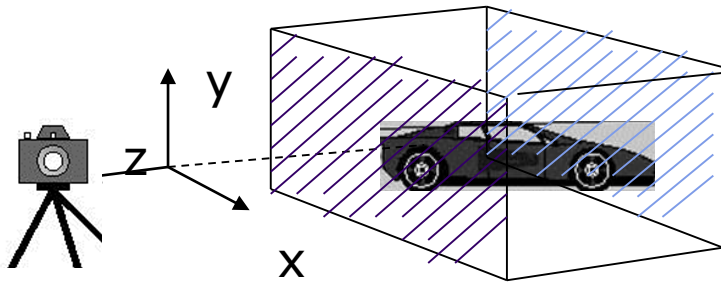
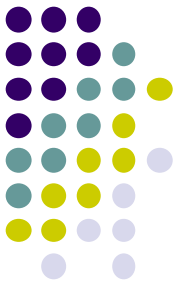
viewing  
volume

**Now:**  
Set view volume

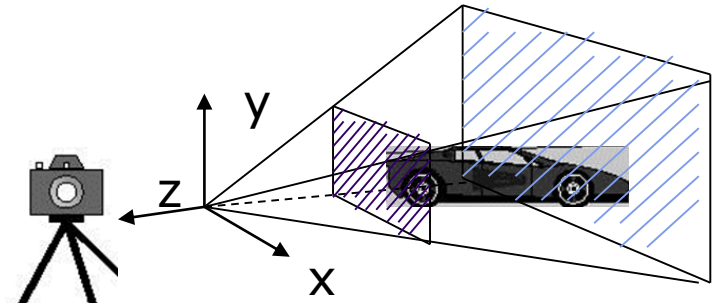


model

# Recall: Different View Volume Shapes



Orthogonal view volume  
(no foreshortening)



Perspective view volume  
(exhibits foreshortening)



- Different view volume => different look
- **Foreshortening?** Near objects bigger





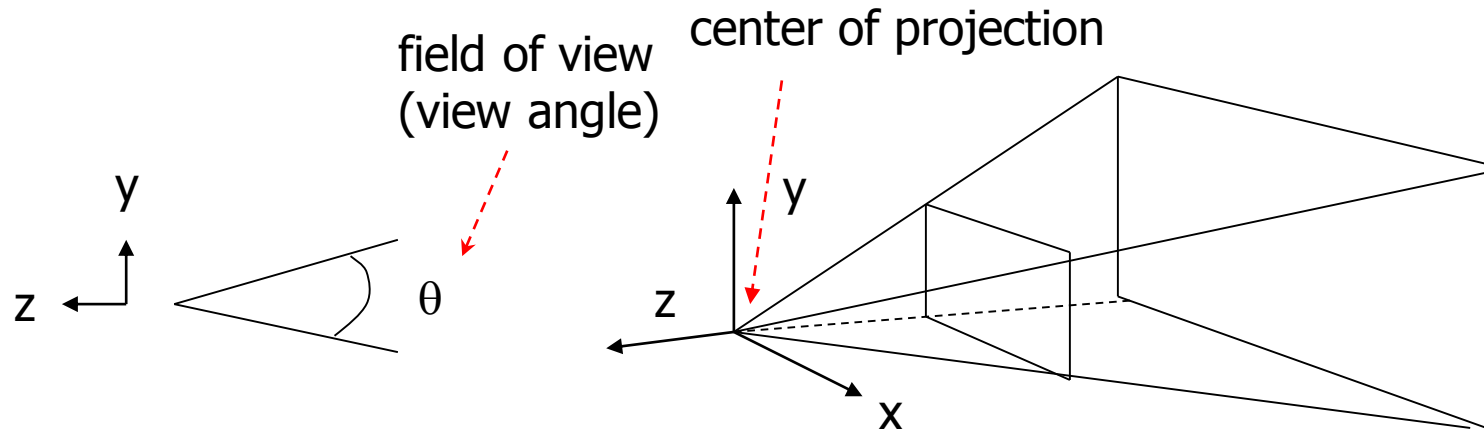
# View Volume Parameters

- Need to set view volume parameters
  - **Projection type:** perspective, orthographic, etc.
  - Field of view and aspect ratio
  - Near and far clipping planes



# Field of View

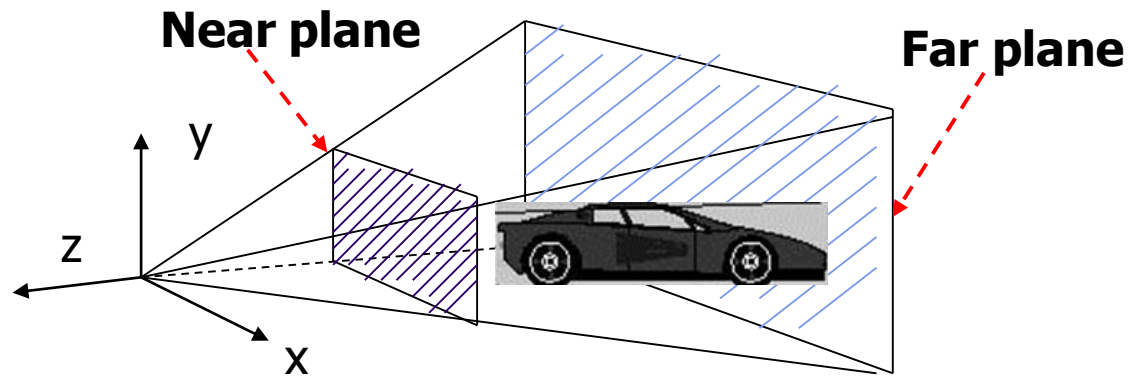
- View volume parameter
- Determines how much of world in picture (vertically)
- Larger field of view = smaller objects drawn





# Near and Far Clipping Planes

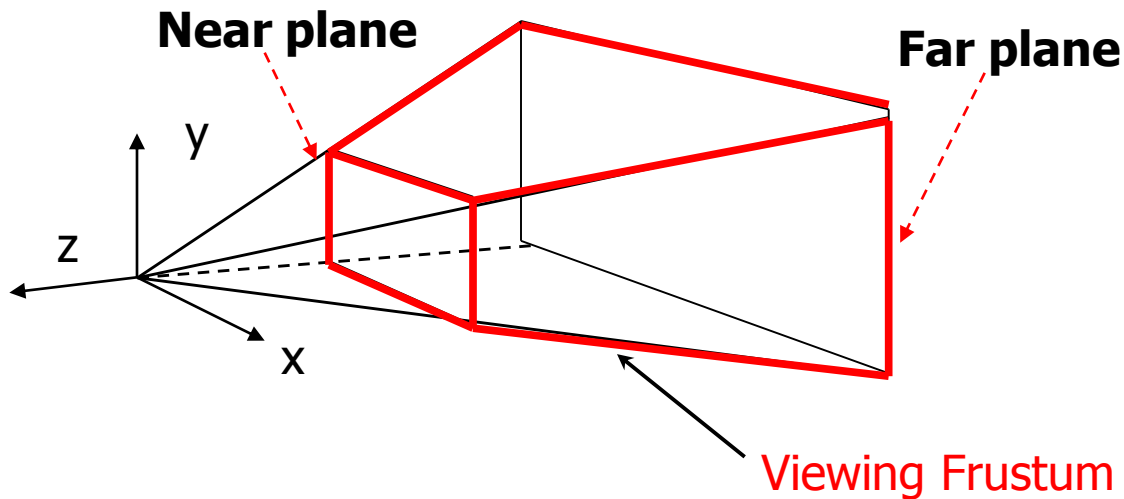
- Only objects between near and far planes drawn





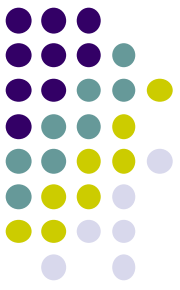
# Viewing Frustum

- Near plane + far plane + field of view = **Viewing Frustum**
- Objects outside the frustum are clipped





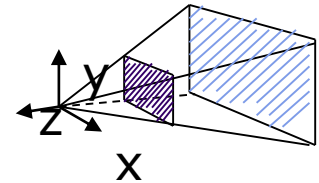
# Setting up View Volume/Projection Type



- Previous OpenGL projection commands **deprecated!!**

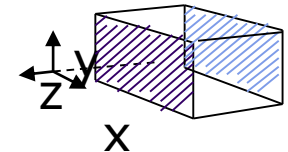
- Perspective view volume/projection:

- **gluPerspective**(fovy, aspect, near, far) or
- **glFrustum**(left, right, bottom, top, near, far)



- Orthographic:

- **glOrtho**(left, right, bottom, top, near, far)



- Useful functions, so we implement similar in **mat.h**:

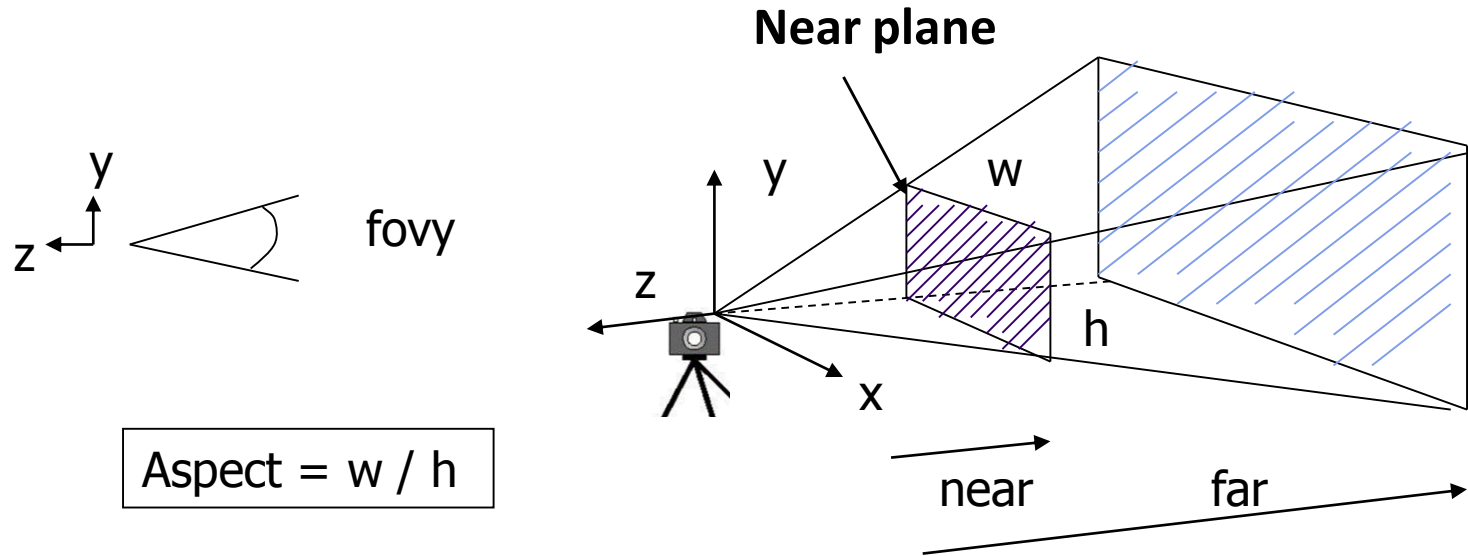
- **Perspective**(fovy, aspect, near, far) or
- **Frustum**(left, right, bottom, top, near, far)
- **Ortho**(left, right, bottom, top, near, far)

What are these arguments? Next!



# Perspective(fovy, aspect, near, far)

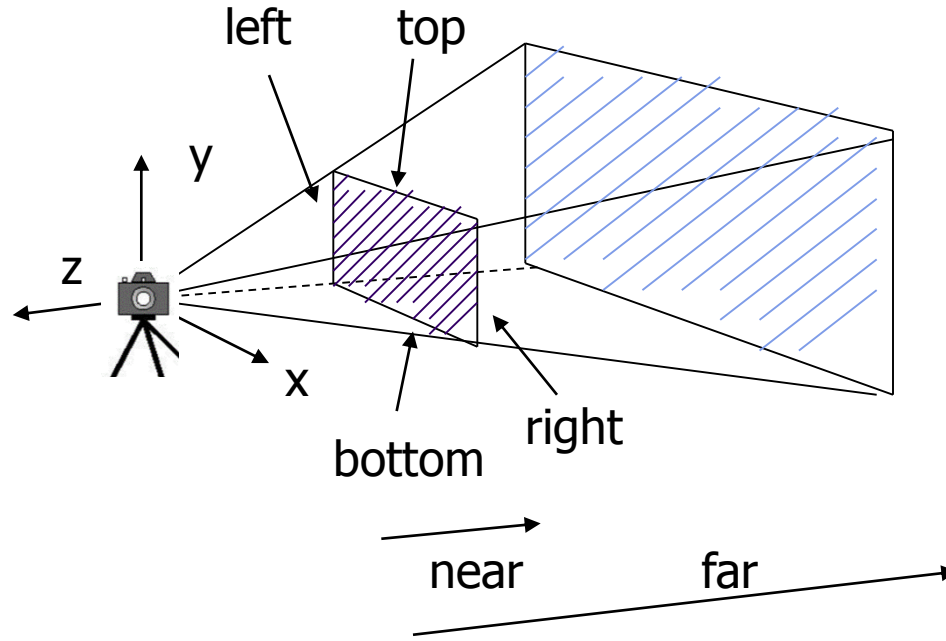
- Aspect ratio used to calculate window width





# Frustum(left, right, bottom, top, near, far)

- Can use **Frustum( )** in place of **Perspective()**
- Same view volume **shape**, different **arguments**

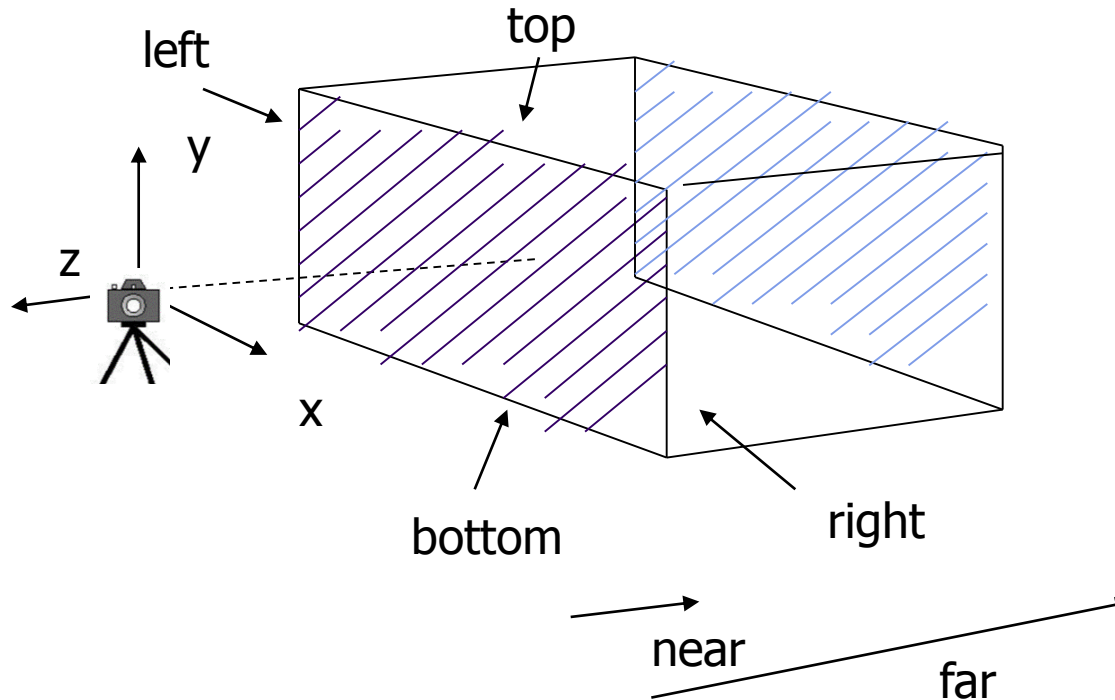


**near** and **far** measured from **camera**



# Ortho(left, right, bottom, top, near, far)

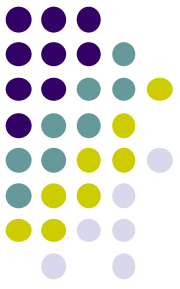
- For orthographic projection



**near** and **far** measured from **camera**

# Example Usage:

## Setting View Volume/Projection Type



```
void display()
{
    // clear screen
    glClear(GL_COLOR_BUFFER_BIT);

    .....

    // Set up camera position
    LookAt(0,0,1,0,0,0,0,1,0);
           eye   at   up

    .....

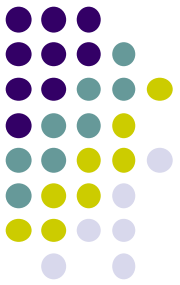
    // set up perspective transformation
    Perspective(fovy, aspect, near, far);

    .....

    // draw something
    display_all();    // your display routine
}
```

# Demo

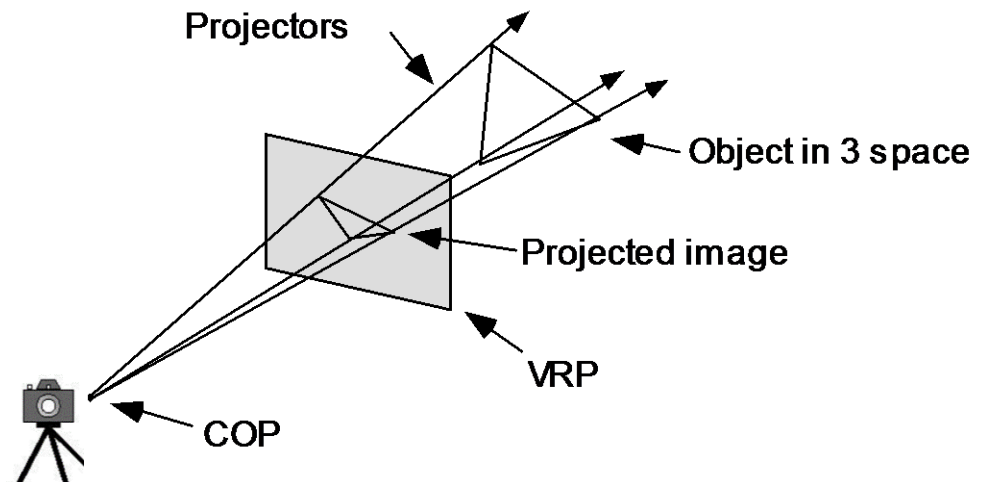
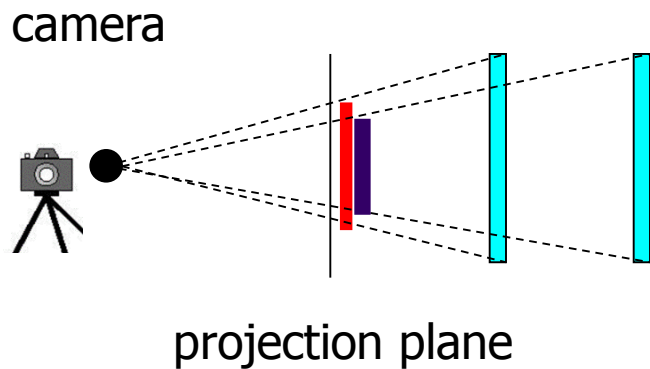
- Nate Robbins demo on projection

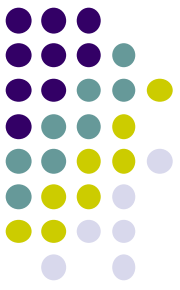




# Perspective Projection

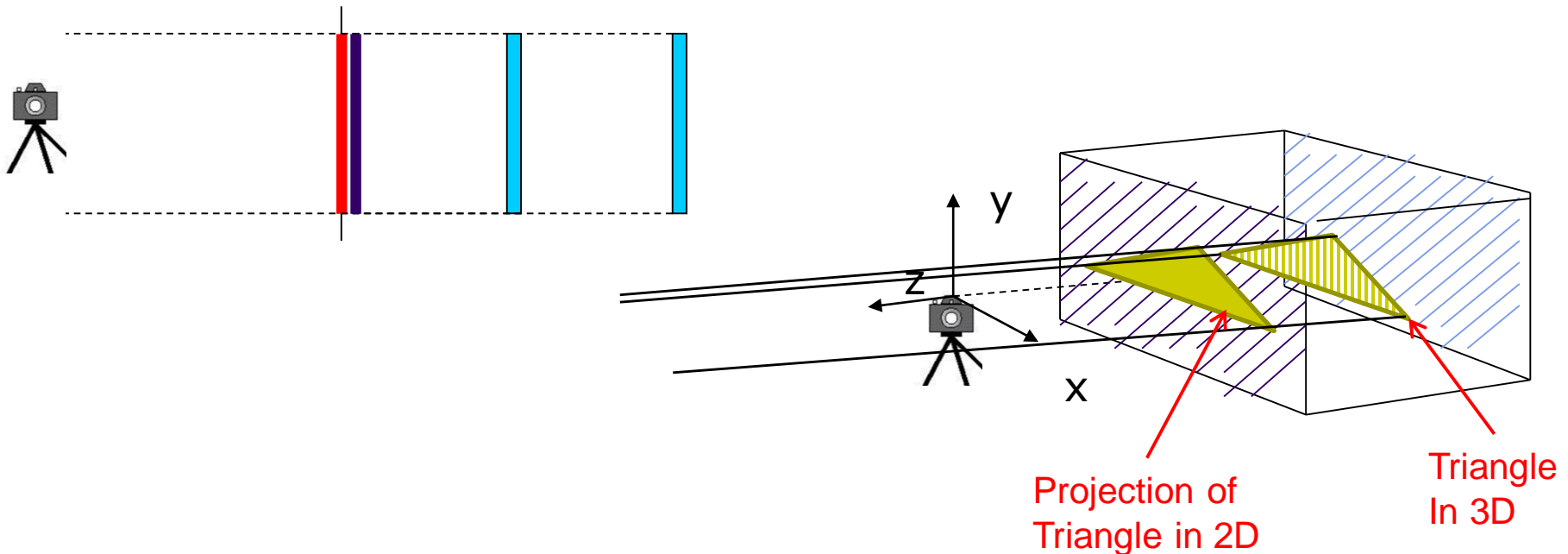
- After setting view volume, then projection transformation
- Projection?
  - **Classic:** Converts 3D object to corresponding 2D on screen
  - How? Draw line from object to projection center
  - Calculate where each intersects projection plane





# Orthographic Projection

- How? Draw parallel lines from each object vertex
- The projection center is at infinite
- In short, use  $(x,y)$  coordinates, just drop  $z$  coordinates

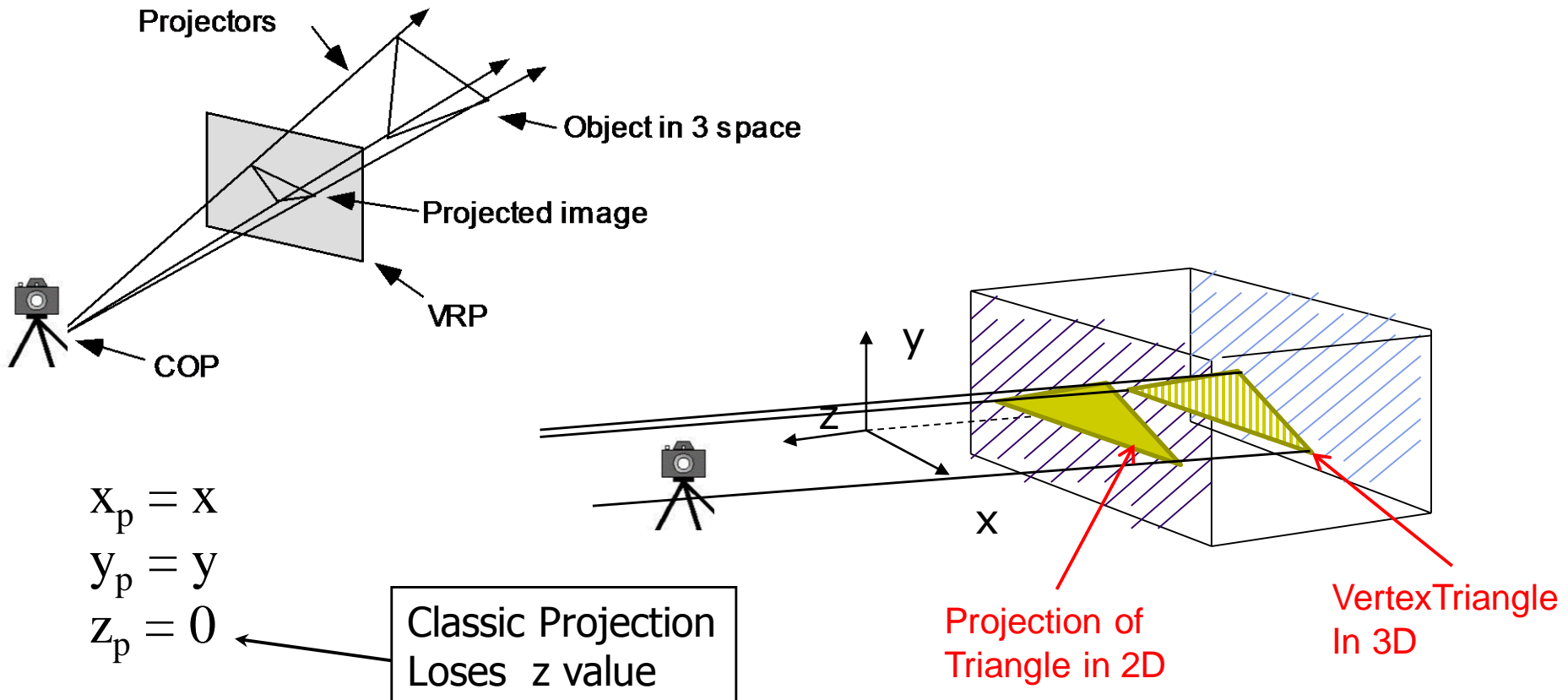






# The Problem with Classic Projection

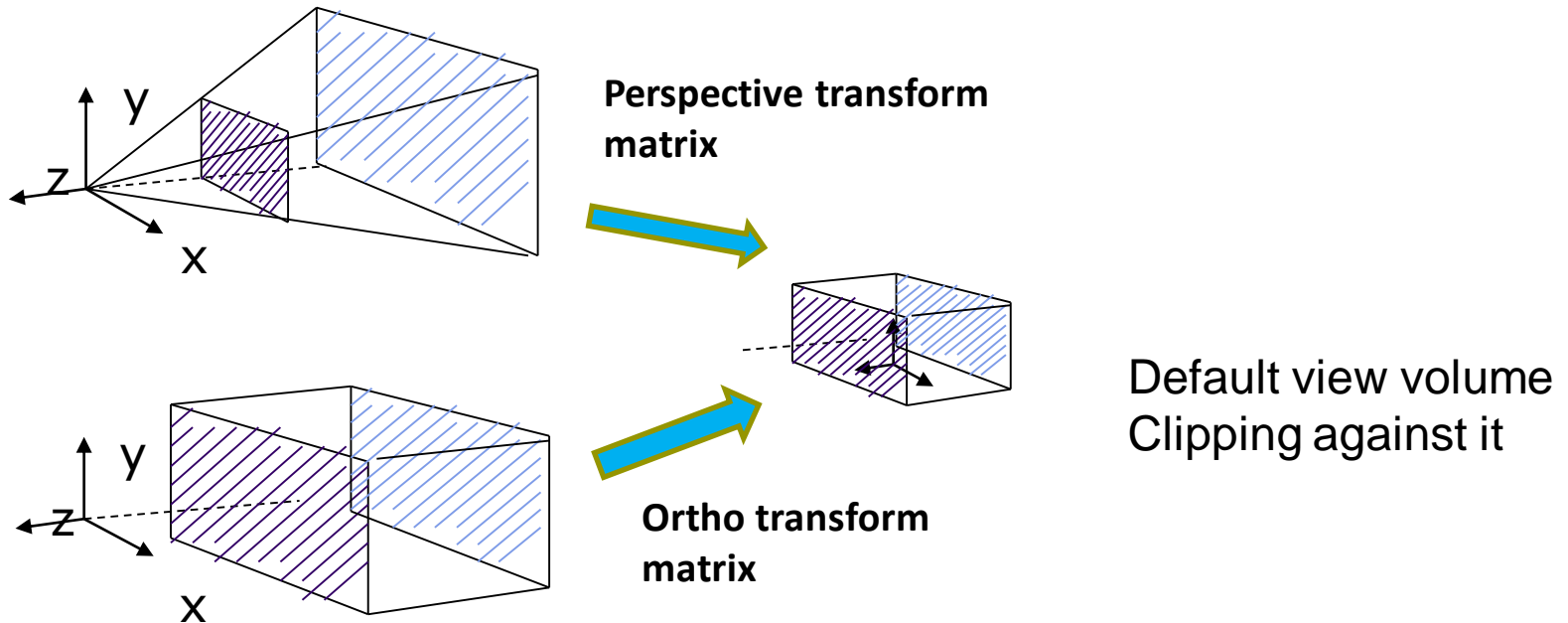
- Keeps (x,y) coordinates for drawing, drops z
- We may need z. Why?





# Normalization: Keeps z Value

- Most graphics systems use *view normalization*
- **Normalization:** convert all other projection types to orthogonal projections with the *default view volume*



# Computer Graphics (CS 4731)

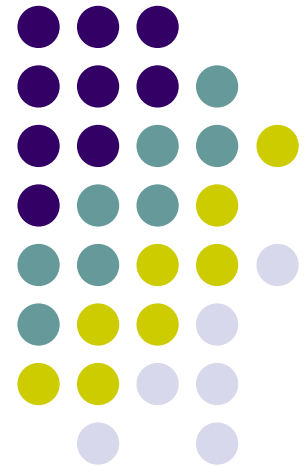
## Lecture 15: Projection (Part 2): Derivation

---

Prof Emmanuel Agu

*Computer Science Dept.*

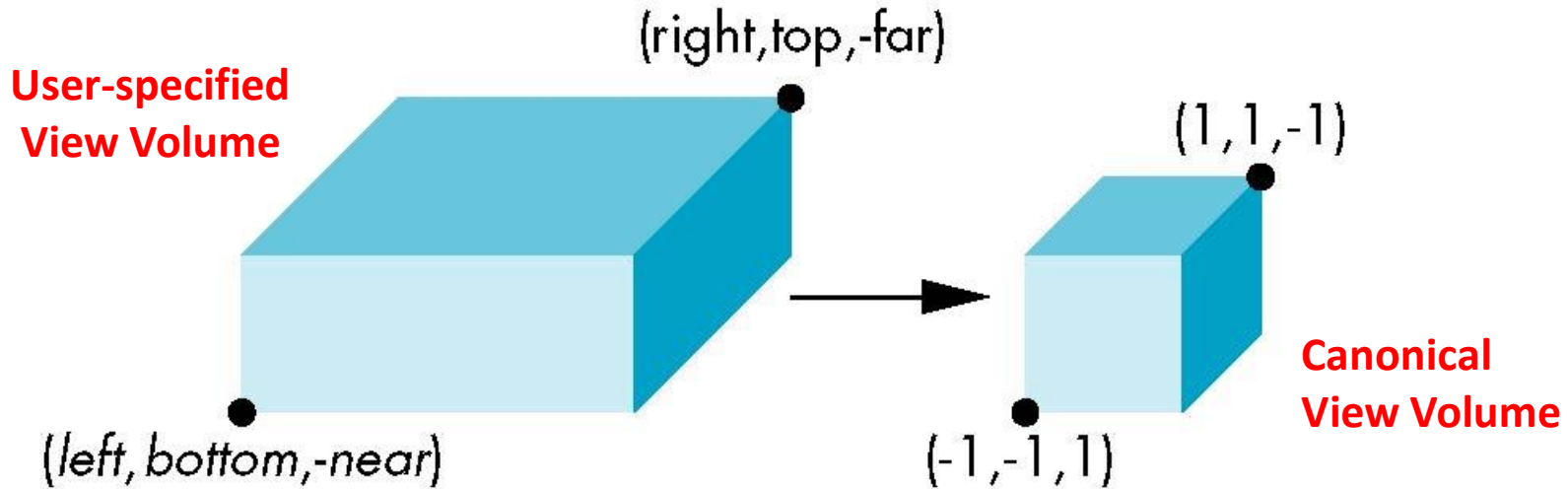
*Worcester Polytechnic Institute (WPI)*



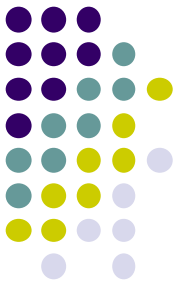


# Parallel Projection

- **normalization**  $\Rightarrow$  find 4x4 matrix to transform **user-specified view volume** to **canonical view volume (cube)**

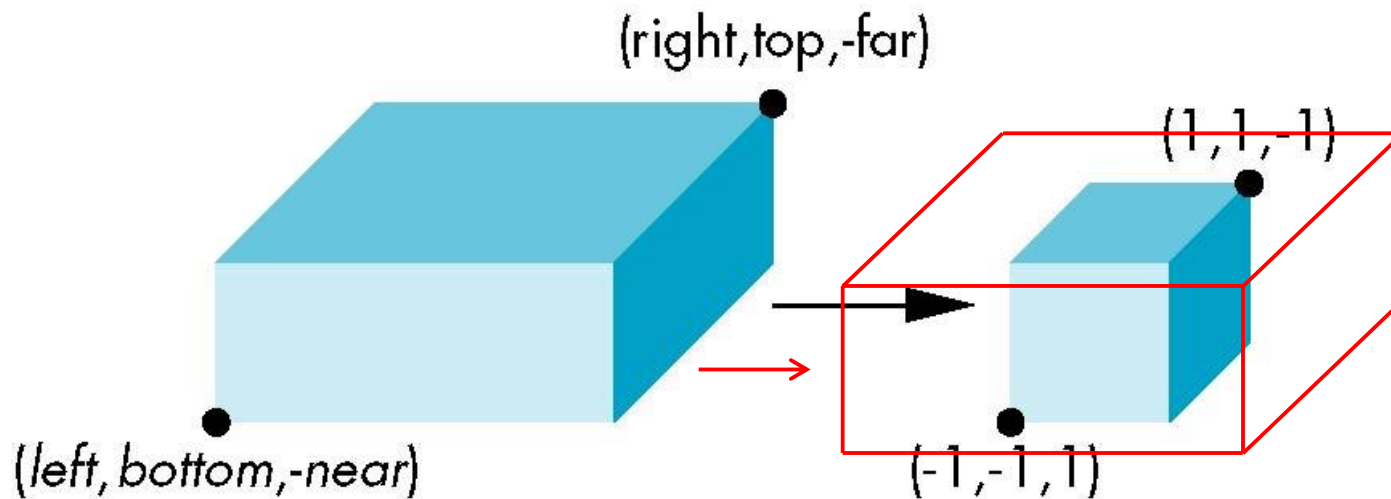


**glOrtho**(left, right, bottom, top, near, far)



# Parallel Projection: Ortho

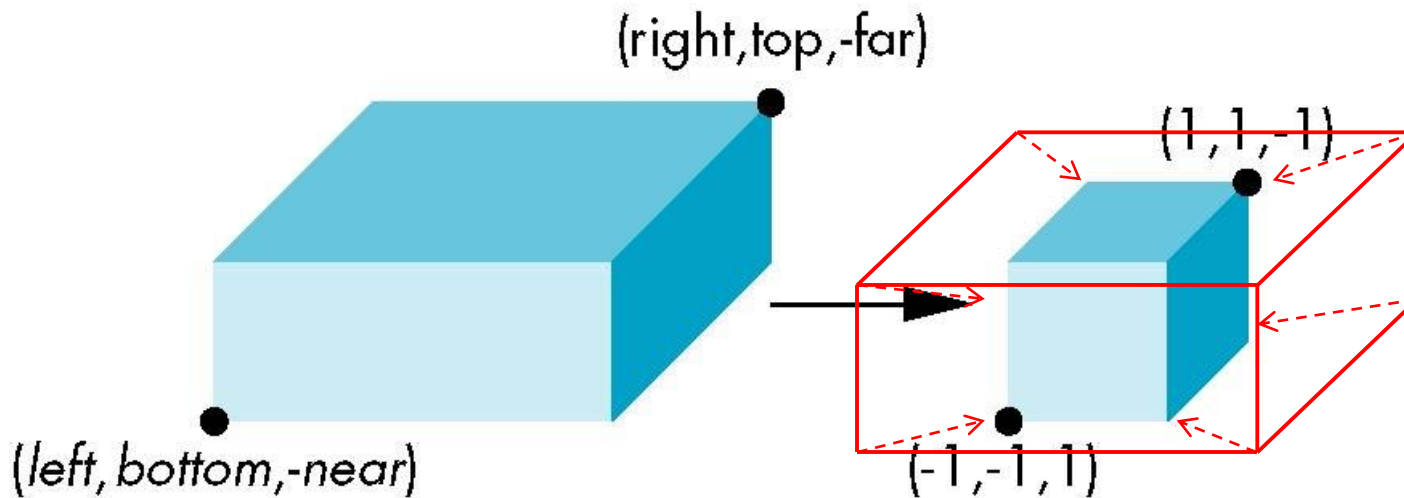
- Parallel projection: 2 parts
  1. **Translation:** centers view volume at origin

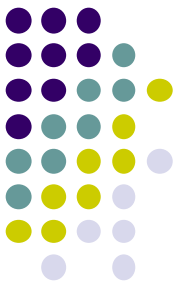




# Parallel Projection: Ortho

2. **Scaling:** reduces user-selected cuboid to canonical cube (dimension 2, centered at origin)

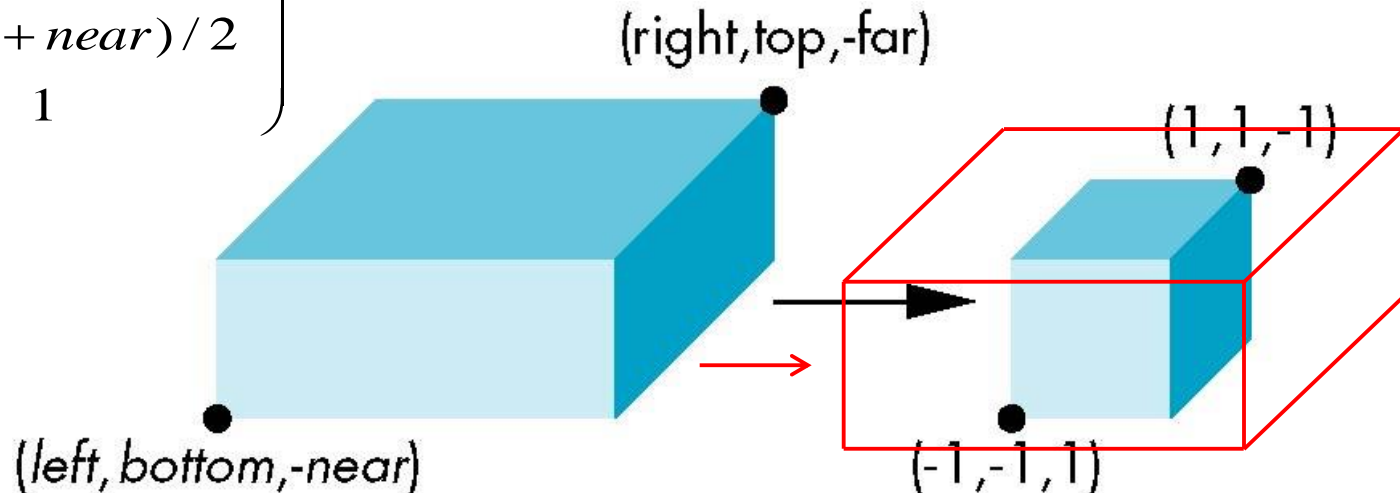


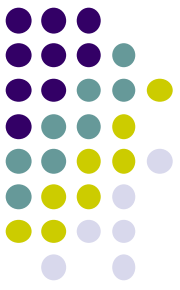


# Parallel Projection: Ortho

- Translation lines up midpoints: E.g. midpoint of  $x = (\text{right} + \text{left})/2$
- Thus translation factors:  
 $-(\text{right} + \text{left})/2, -(\text{top} + \text{bottom})/2, -(\text{far} + \text{near})/2$
- Translation matrix:

$$\begin{pmatrix} 1 & 0 & 0 & -(\text{right} + \text{left})/2 \\ 0 & 1 & 0 & -(\text{top} + \text{bottom})/2 \\ 0 & 0 & 1 & -(\text{far} + \text{near})/2 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

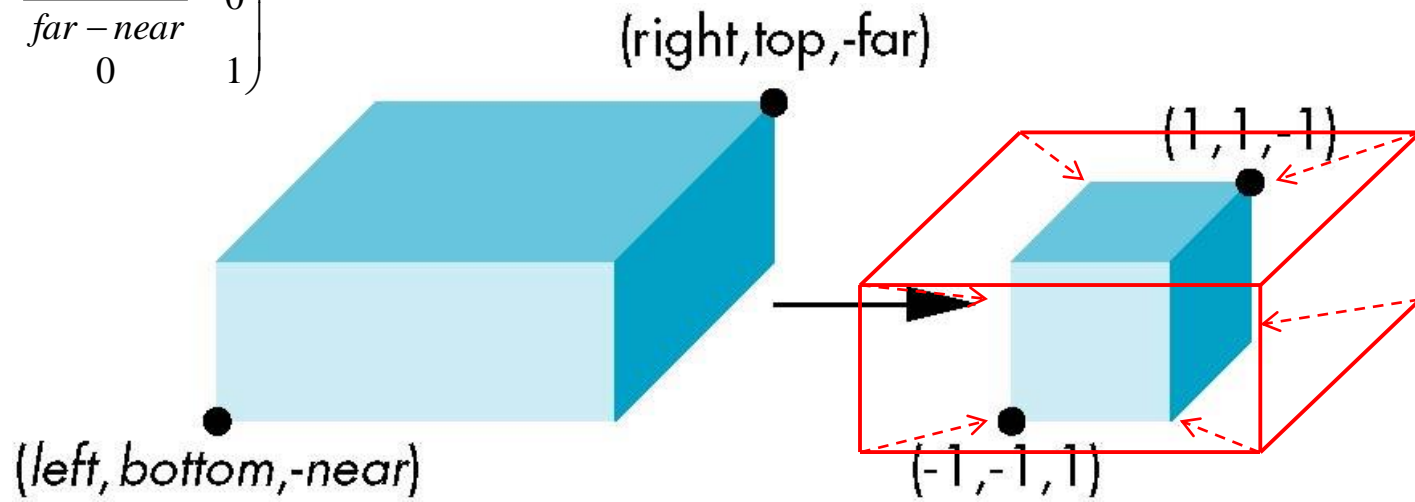




# Parallel Projection: Ortho

- Scaling factor: ratio of ortho view volume to cube dimensions
- Scaling factors:  $2/(right - left)$ ,  $2/(top - bottom)$ ,  $2/(far - near)$
- Scaling Matrix M2:

$$\begin{pmatrix} \frac{2}{right - left} & 0 & 0 & 0 \\ 0 & \frac{2}{top - bottom} & 0 & 0 \\ 0 & 0 & \frac{2}{far - near} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$







# Parallel Projection: Ortho

Concatenating **Translation** x **Scaling**, we get Ortho Projection matrix

$$\begin{pmatrix} \frac{2}{right - left} & 0 & 0 & 0 \\ 0 & \frac{2}{top - bottom} & 0 & 0 \\ 0 & 0 & \frac{2}{far - near} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \times \begin{pmatrix} 1 & 0 & 0 & -(right + left) / 2 \\ 0 & 1 & 0 & -(top + bottom) / 2 \\ 0 & 0 & 1 & -(far + near) / 2 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{P} = \mathbf{ST} = \begin{bmatrix} \frac{2}{right - left} & 0 & 0 & -\frac{right - left}{right - left} \\ 0 & \frac{2}{top - bottom} & 0 & -\frac{top + bottom}{top - bottom} \\ 0 & 0 & \frac{2}{near - far} & \frac{far + near}{far - near} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



# Final Ortho Projection

- Set  $z = 0$
- Equivalent to the homogeneous coordinate transformation

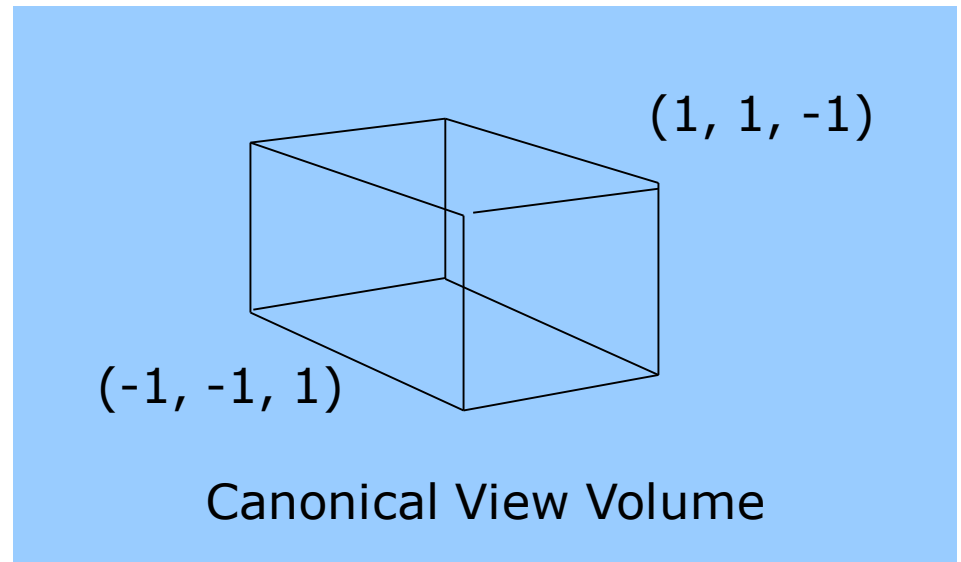
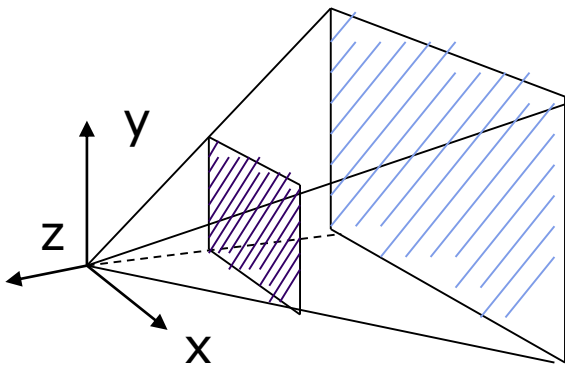
$$\mathbf{M}_{\text{orth}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- Hence, general orthogonal projection in 4D is  $\mathbf{P} = \mathbf{M}_{\text{orth}}\mathbf{ST}$



# Perspective Transformation


- We want to transform viewing frustum volume into canonical view volume





# Perspective Projection Matrix

Derivation skipped!

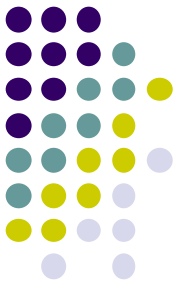

$$\begin{pmatrix} \frac{2N}{x_{\max} - x_{\min}} & 0 & \frac{right + left}{right - left} & 0 \\ 0 & \frac{2N}{top - bottom} & \frac{top + bottom}{top - bottom} & 0 \\ 0 & 0 & \frac{-(F + N)}{F - N} & \frac{-2FN}{F - N} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

**Final Perspective Transform Matrix**

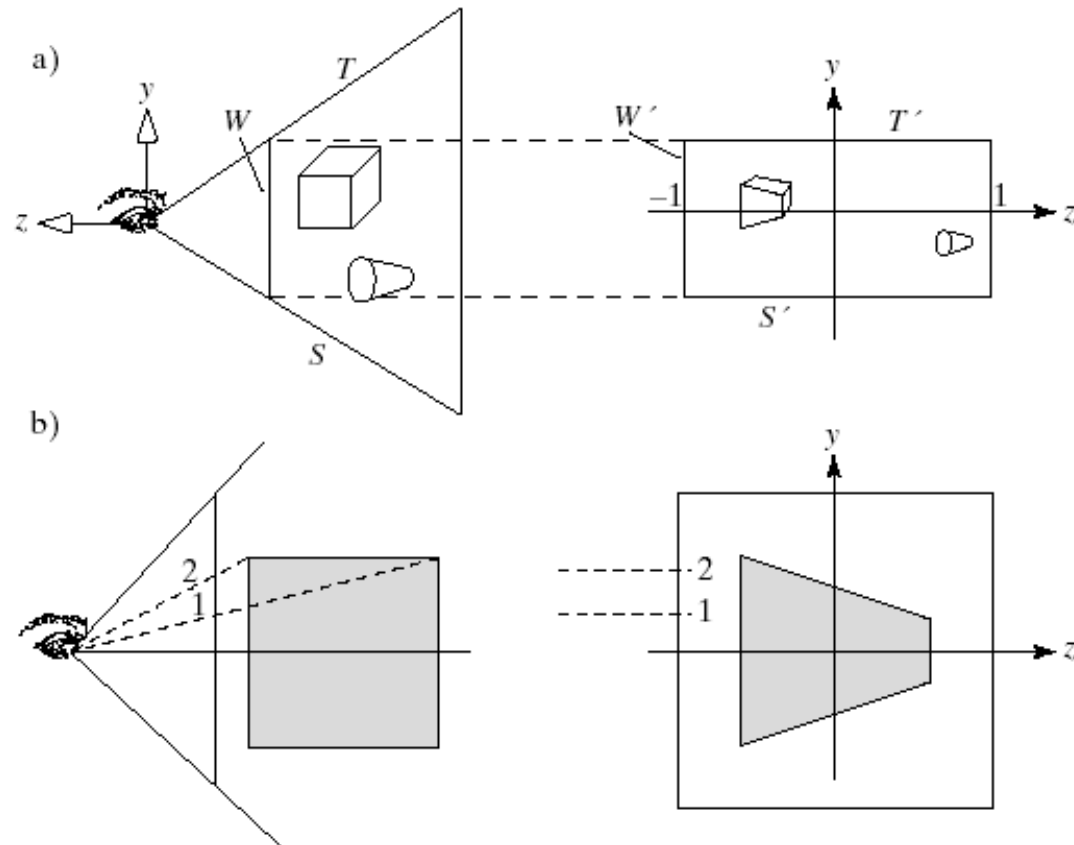
**glFrustum(left, right, bottom, top, N, F)**

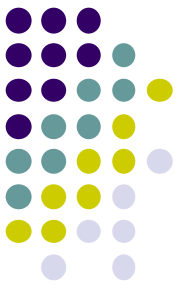
N = near plane, F = far plane

# Geometric Nature of Perspective Transform



- a) Lines through eye map into lines parallel to  $z$  axis after transform
- b) Lines perpendicular to  $z$  axis map to lines perp to  $z$  axis after transform





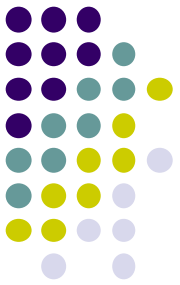
# Implementation

- Set modelview and projection matrices in application program
- Pass matrices to shader

```
void display( ) {  
    .....  
    model_view = LookAt(eye, at, up);  
    projection = Ortho(left, right, bottom, top, near, far);  
  
    // pass model_view and projection matrices to shader  
    glUniformMatrix4fv(matrix_loc, 1, GL_TRUE, model_view);  
    glUniformMatrix4fv(projection_loc, 1, GL_TRUE, projection);  
    .....  
}
```

Build 4x4 projection matrix

A red arrow points from the text "Build 4x4 projection matrix" to the 'projection' variable in the code line 'projection = Ortho(left, right, bottom, top, near, far);'.



# Implementation

- And the corresponding shader

```
in vec4 vPosition;
in vec4 vColor;
Out vec4 color;
uniform mat4 model_view;
Uniform mat4 projection;

void main( )
{
    gl_Position = projection*model_view*vPosition;
    color = vColor;
}
```



# References

- Interactive Computer Graphics (6<sup>th</sup> edition), Angel and Shreiner
- Computer Graphics using OpenGL (3<sup>rd</sup> edition), Hill and Kelley