#### **BRDF Evolution**



- BRDFs have evolved historically
- 1970's: Empirical models
  - Phong's illumination model
- 1980s:
  - Physically based models
  - Microfacet models (e.g. Cook Torrance model)
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# **Physically-Based Shading Models**



- Phong model produces pretty pictures
- Cons: empirical (fudged?) ( $\cos^{\alpha}\phi$ ), plastic look
- Shaders can implement better lighting/shading models
- Big trend towards Physically-based lighting models
- Physically-based?
  - Based on physics of how light interacts with actual surface
  - Apply Optics/Physics theories
- Classic: Cook-Torrance shading model (TOGS 1982)

# **Cook-Torrance Shading Model**

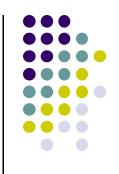


- Same ambient and diffuse terms as Phong
- New, better specular component than  $(\cos^{\alpha}\phi)$ ,

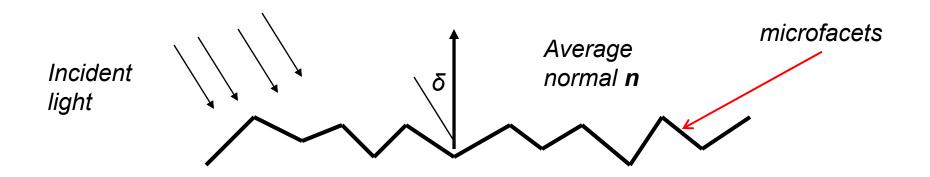
$$\cos^{\alpha} \phi \to \frac{F(\phi, \eta)DG}{(\mathbf{n} \cdot \mathbf{v})}$$

- Where
  - D Distribution term
  - G Geometric term
  - F Fresnel term





Idea: surfaces consist of small V-shaped microfacets (grooves)

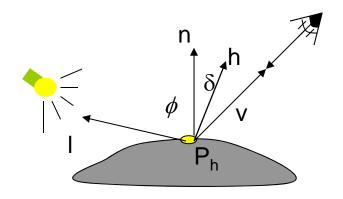


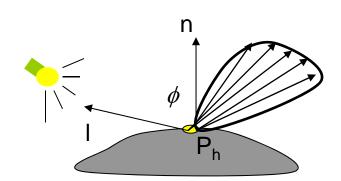
- Many grooves at each surface point
- Grooves facing a direction contribute
- D( $\delta$ ) term: what fraction of grooves facing each angle  $\delta$
- E.g. half of grooves at hit point face 30 degrees, etc





- Define angle  $\delta$  as deviation of **h** from surface normal
- Only microfacets with pointing along halfway vector,  $\mathbf{h} = \mathbf{s} + \mathbf{v}$ , contributes



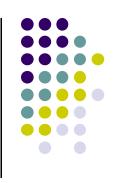


- Can use old Phong cosine  $(\cos^n \phi)$ , as D
- Use Beckmann distribution instead

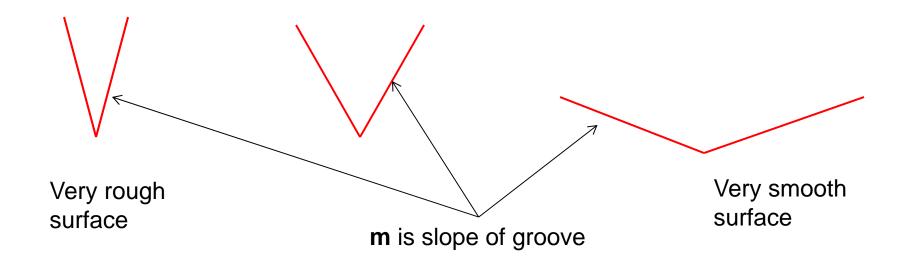
$$D(\delta) = \frac{1}{4\mathbf{m}^2 \cos^4(\delta)} e^{-\left(\frac{\tan(\delta)}{\mathbf{m}}\right)^2}$$

m expresses roughness of surface. How?





- m is Root-mean-square (RMS) of slope of V-groove
- m = 0.2 for nearly smooth
- m = 0.6 for very rough







 Some grooves on extremely rough surface may block other grooves

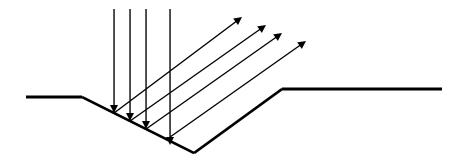




#### Geometric Term, G

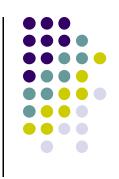


- Surface may be so rough that interior of grooves is blocked from light by edges
- Self blocking known as shadowing or masking
- Geometric term G accounts for this
- Break G into 3 cases:
- G, case a: No self-shadowing (light in-out unobstructed)

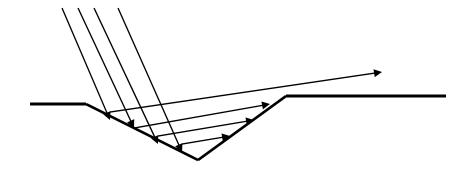


Mathematically, G = 1





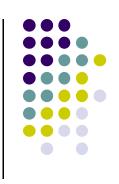
 G<sub>m</sub>, case b: No blocking on entry, blocking of exitting light (masking)



Mathematically,

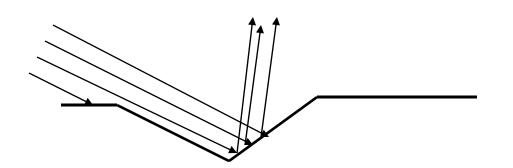
$$G_m = \frac{2(\mathbf{n} \cdot \mathbf{h})(\mathbf{n} \cdot \mathbf{h})}{\mathbf{h} \cdot \mathbf{s}}$$





- G<sub>s</sub>, case c: blocking of incident light, no blocking of exitting light (shadowing)
- Mathematically,

$$G_s = \frac{2(\mathbf{n} \cdot \mathbf{h})(\mathbf{n} \cdot \mathbf{h})}{\mathbf{h} \cdot \mathbf{s}}$$



• G term is minimum of 3 cases, hence

$$G = (1, G_m, G_s)$$

#### Fresnel Term, F



$$spec = \frac{F(\phi, \eta)DG}{(\mathbf{n} \cdot \mathbf{v})}$$

- Microfacets not perfect mirrors
- F term,  $F(\phi, \eta)$  gives fraction of incident light reflected

$$F = \frac{1}{2} \frac{(g-c)^2}{(g+c)^2} \left\{ 1 + \left( \frac{c(g+c)-1}{c(g-c)-1} \right)^2 \right\}$$

F is function of material and incident angle

- where  $c = cos(\phi) = n.s$  and  $g^2 = \eta^{2+}c^2 + 1$
- ullet  $\phi$  is incident angle,  $\eta$  is refractive index of material



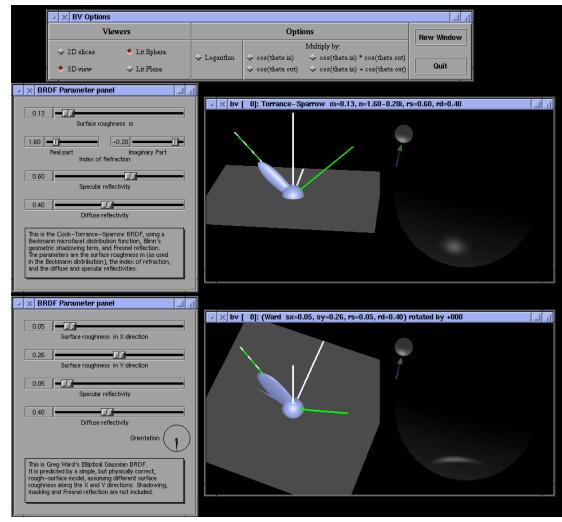
# **Other Physically-Based BRDF Models**



- Oren-Nayar Diffuse term changed not specular
- Aishikhminn-Shirley Grooves not v-shaped. Other Shapes
- Microfacet generator (Design your own microfacet)

#### **BV BRDF Viewer**

BRDF viewer (View distribution of light bounce)



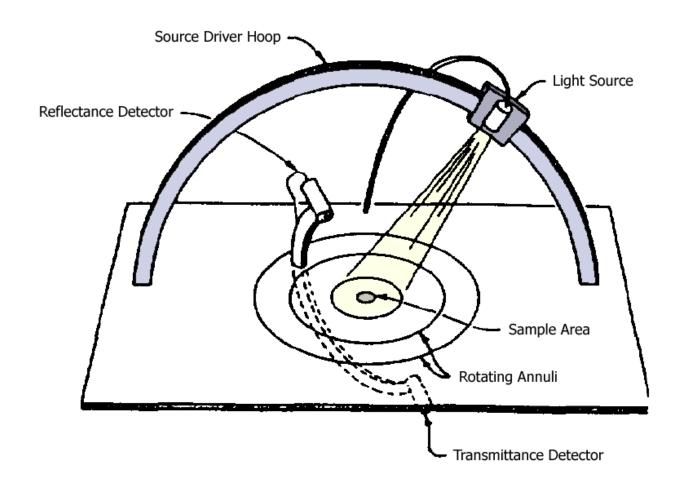
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Murray-Coleman and Smith Gonioreflectometer. (Copied and Modified from [Ward92]).

### **Measured BRDF Samples**



Mitsubishi Electric Research Lab (MERL)

http://www.merl.com/brdf/

- Wojciech Matusik
- MIT PhD Thesis
- 100 Samples

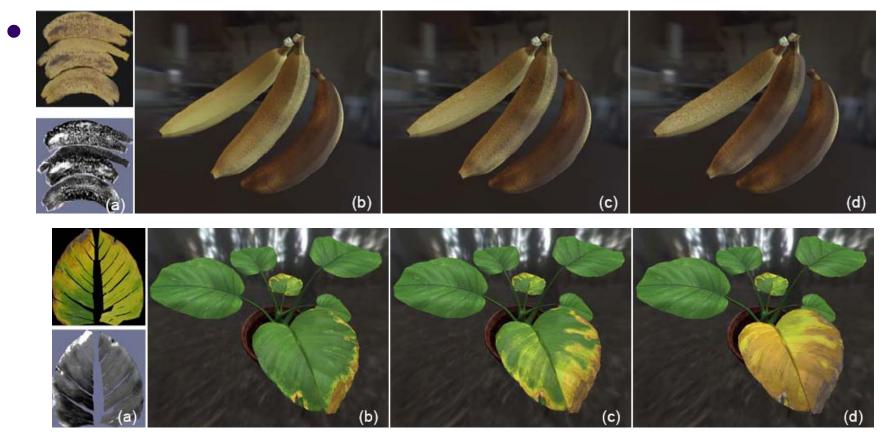


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- BRDF: How different materials reflect light
- Time varying?: how reflectance changes over time



### Computer Graphics (CS 4731) Lecture 19: Shadows and Fog

#### Prof Emmanuel Agu

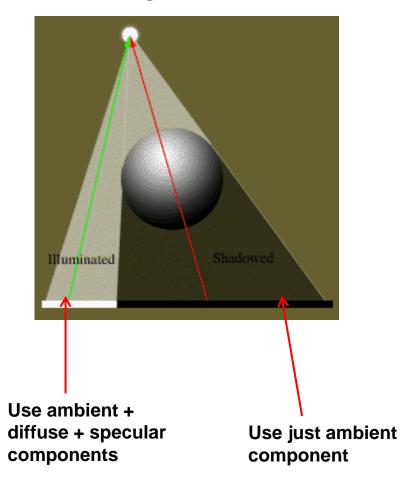
Computer Science Dept.
Worcester Polytechnic Institute (WPI)







Shadows give information on relative positions of objects





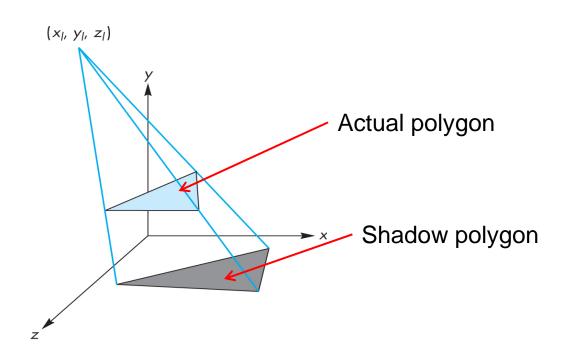
#### **Introduction to Shadows**

- Two popular shadow rendering methods:
  - Shadows as texture (projection)
  - Shadow buffer
- Third method used in ray-tracing (covered in grad class)



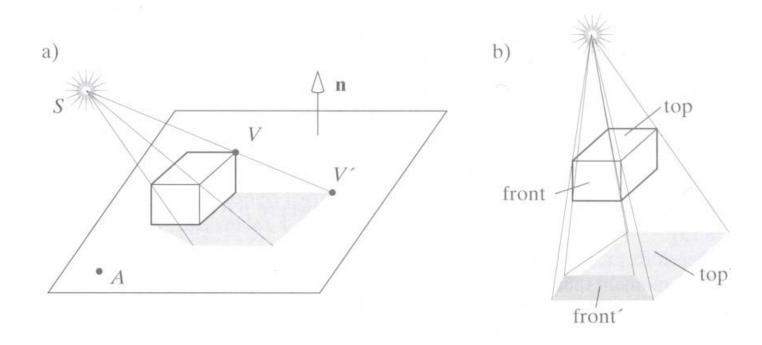


- Oldest method: Used in early flight simulators
- Projection of polygon is polygon called shadow polygon





- Works for flat surfaces illuminated by point light
- For each face, project vertices V to find V' of shadow polygon
- Object shadow = union of projections of faces



#### **Projective Shadow Algorithm**

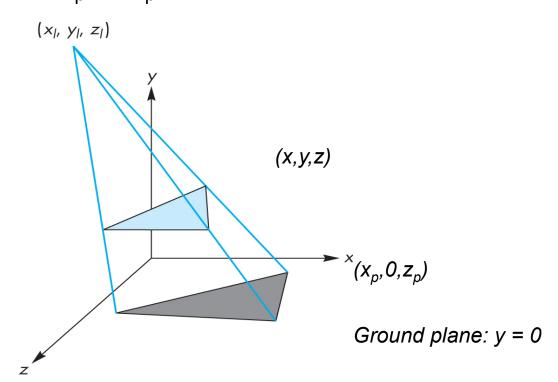


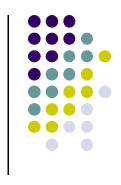
- Project light-object edges onto plane
- Algorithm:
  - First, draw ground plane using specular+diffuse+ambient components
  - Then, draw shadow projections (face by face) using only ambient component





- 1. If light is at  $(x_1, y_1, z_1)$
- 2. Vertex at (x, y, z)
- Would like to calculate shadow polygon vertex V projected onto ground at  $(x_p, 0, z_p)$

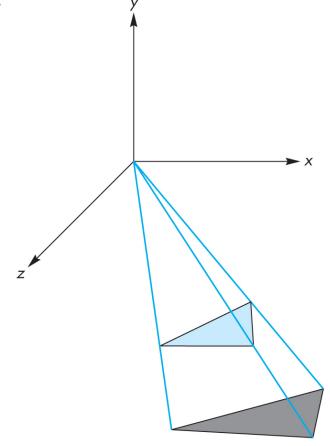




### **Projective Shadows for Polygon**

- If we move original polygon so that light source is at origin
- Matrix M projects a vertex V to give its projection V' in shadow polygon

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & \frac{1}{-y_l} & 0 & 0 \end{bmatrix}$$



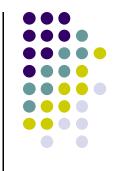




- Translate source to origin with T(-x<sub>1</sub>, -y<sub>1</sub>, -z<sub>1</sub>)
- 2. Perspective projection
- 3. Translate back by  $T(x_1, y_1, z_1)$

$$M = \begin{bmatrix} 1 & 0 & 0 & x_l \\ 0 & 1 & 0 & y_l \\ 0 & 0 & 1 & z_l \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & \frac{1}{-y_l} & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -x_l \\ 0 & 1 & 0 & -y_l \\ 0 & 0 & 1 & -z_l \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Final matrix that projects Vertex V onto V' in shadow polygon



### **Code snippets?**

Set up projection matrix in OpenGL application

```
float light[3]; // location of light mat4 m; // shadow projection matrix initially identity M[3][1] = -1.0/\text{light}[1]; M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & \frac{1}{-y_l} & 0 & 0 \\ 0 & -\frac{y_l}{-y_l} & 0 & 0 \end{bmatrix}
```





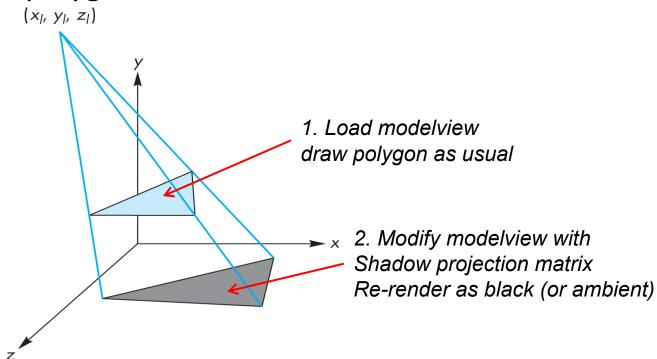
Set up object (e.g a square) to be drawn

- Copy square to VBO
- Pass modelview, projection matrices to vertex shader

#### What next?



- Next, we load model\_view as usual then draw original polygon
- Then load shadow projection matrix, change color to black, re-render polygon





# **Shadow projection Display() Function**

```
void display( )
{
    mat4 mm;
    // clear the window
    glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);

    // render red square (original square) using modelview
    // matrix as usual (previously set up)
    glUniform4fv(color_loc, 1, red);
    glDrawArrays(GL_TRIANGLE_STRIP, 0, 4);
```



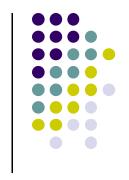
#### **Shadow projection Display() Function**

```
// modify modelview matrix to project square
// and send modified model view matrix to shader
mm = model view
        * Translate(light[0], light[1], light[2]
        *m
        * Translate(-light[0], -light[1], -light[2]);
glUniformMatrix4fv(matrix loc, 1, GL TRUE, mm);
//and re-render square as
// black square (or using only ambient component)
 glUniform4fv(color loc, 1, black);
 glDrawArrays(GL_TRIANGLE_STRIP, 0, 4);
                                                       M = \begin{bmatrix} 1 & 0 & 0 & x_l \\ 0 & 1 & 0 & y_l \\ 0 & 0 & 1 & z_l \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & \frac{1}{-v_l} & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -x_l \\ 0 & 1 & 0 & -y_l \\ 0 & 0 & 1 & -z_l \\ 0 & 0 & 0 & 1 \end{bmatrix}
 glutSwapBuffers( );
```





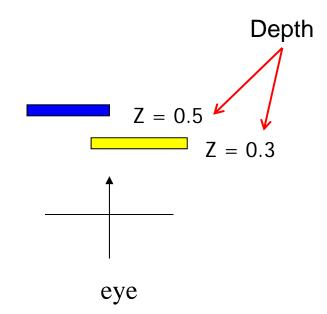
- Uses second depth buffer called shadow buffer
- Pros: not limited to plane surfaces
- Cons: needs lots of memory
- Depth buffer?

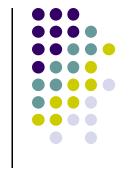


#### **OpenGL Depth Buffer (Z Buffer)**

- Depth: While drawing objects, depth buffer stores distance of each polygon from viewer
- Why? If multiple polygons overlap a pixel, only closest one polygon is drawn

1.0	1.0	1.0	1.0
1.0	0.3	0.3	1.0
0.5	0.3	0.3	1.0
0.5	0.5	1.0	1.0





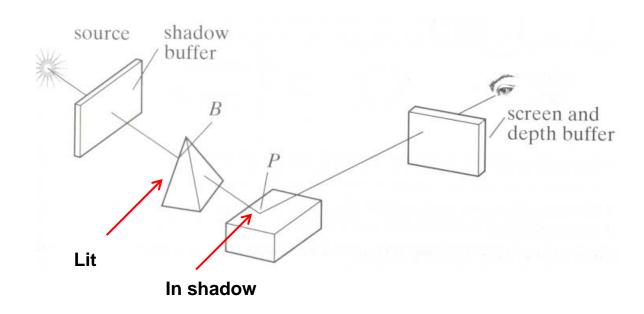
### Setting up OpenGL Depth Buffer

- Note: You did this in order to draw solid cube, meshes
- glutInitDisplayMode(GLUT\_DEPTH | GLUT\_RGB)
   instructs openGL to create depth buffer
- 2. glEnable(GL\_DEPTH\_TEST) enables depth testing
- 3. glClear(GL\_COLOR\_BUFFER\_BIT | GL\_DEPTH\_BUFFER\_BIT)
  Initializes depth buffer every time we draw a new picture

### **Shadow Buffer Theory**



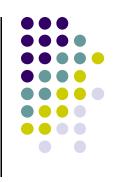
- Along each path from light
  - Only closest object is lit
  - Other objects on that path in shadow
- Shadow buffer stores closest object on each path



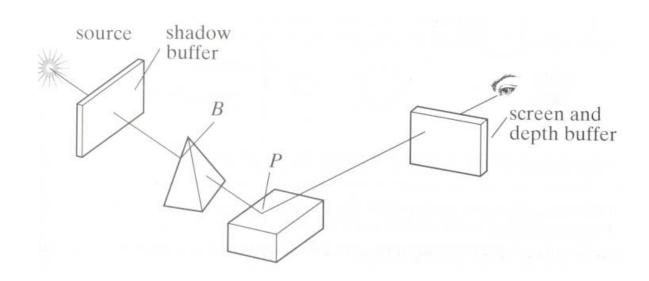
#### **Shadow Buffer Approach**

- Rendering in two stages:
  - Loading shadow buffer
  - Render the scene

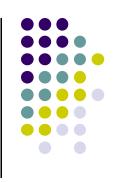




- Initialize each element to 1.0
- Position a camera at light source
- Rasterize each face in scene updating closest object
- Shadow buffer tracks smallest depth on each path



### **Shadow Buffer (Rendering Scene)**

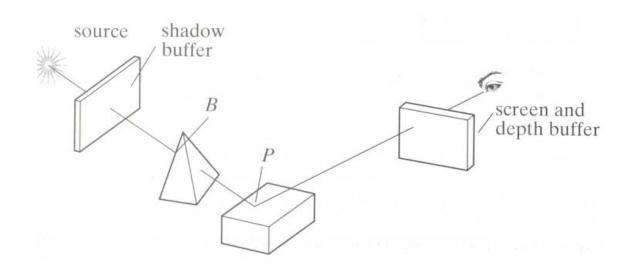


- Render scene using camera as usual
- While rendering a pixel find:
  - pseudo-depth D from light source to P
  - Index location [i][j] in shadow buffer, to be tested
  - Value d[i][j] stored in shadow buffer
- If d[i][j] < D (other object on this path closer to light)</li>
  - point P is in shadow
  - set lighting using only ambient
- Otherwise, not in shadow





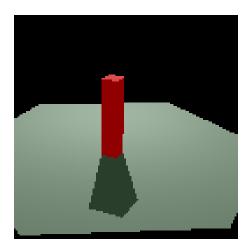
- Shadow buffer calculation is independent of eye position
- In animations, shadow buffer loaded once
- If eye moves, no need for recalculation
- If objects move, recalculation required

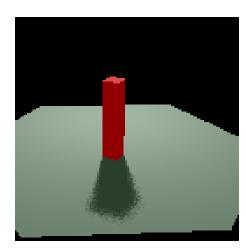




#### **Other Issues**

- Point light sources => simple hard shadows, unrealistic
- Extended light sources => more realistic
- Shadow has two parts:
  - Umbra (Inner part) => no light
  - Penumbra (outer part) => some light









#### References

- Interactive Computer Graphics (6<sup>th</sup> edition), Angel and Shreiner
- Computer Graphics using OpenGL (3<sup>rd</sup> edition), Hill and Kelley
- Real Time Rendering by Akenine-Moller, Haines and Hoffman