CS 525M – Mobile and Ubiquitous Computing Seminar

IEEE 802.11 MAC Protocol Fragmentation or Error Correction?

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Introduction

- IEEE 802.11 MAC Protocol
 - 4 way handshake (RTS/CTS/DATA/ACK)
 - A reliable MAC layer
 - Supports retransmissions
 - Hides loss information to upper layers such as TCP
 - Side effect
 - Increases delays of end-to-end connections

Outline

- Introduction
- Background
- Mathematical Analysis
- Simulation Validation
- Conclusion

Regular 4-way handshake
 – RTS / CTS to reserve
 – DATA / ACK to transmit



[Crow97]

- 4+ way handshake
 - RTS / CTS to reserve
 - Multiple DATA / ACK to transmit



[Crow97]

Low Error Rate	High Error Rate
No fragmentation	Fragmentation
There is rarely any need to retransmit frames. Fragmentation only introduces unnecessary overhead.	It is much faster to retransmit small fragments than an entire frame.

Error Correction

- The source adds a certain amount of redundancy to the data before transmitting.
- The destination repairs the data with the redundant information if errors have occurred.
- Reed-Solomon
 - One of the most popular error correction method
 - Redundancy on a symbol basis
 - With n symbols of redundancy, it can fix up to n / 2 symbols of error.

Error Correction

- IEEE 802.11e Group
 - Concerned with real-time traffic
 - Multimedia, online games, etc
 - A proposal to include error correction to MAC frames



Error	Rate
	naic

High Error Rate

No Error Correction

There is rarely any errors so it is a waste to calculate the necessary redundancy and send the overhead. **Error Correction**

Error correction can help prevent retransmissions by repairing the frames.

What then?

- We know each method can help reduce the delay in the MAC layer.
- Questions
 - Can we use them together?
 - If so, what combination gives the best performance?

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Wireless Errors

- It is known that the wireless errors are usually bursty. There are mathematical models for wireless errors but they are more useful for simulation purposes.
- IID (Independent, Identical Distribution)
 - We assume that there is a fixed bit error rate and that this error rate is identical for each bit and independent of other bits.

Probabilities of Error

• RTS and CTS exchange

$$p_{rts}(0) = (1 - p_b)^{s_{rts}} (1 - p_b)^{s_{rts}}$$
• DATA and ACK exchange

$$- \text{No Error Correction}$$

$$p_{data}(0) = (1 - p_b)^{s_f} (1 - p_b)^{s_a}$$

$$- \text{Error Correction}$$

$$p_{cb} = \sum_{i=0}^{s_c} {s_c + s_{oh} \choose i} (1 - p_{be})^{s_c + s_{oh} - i} p_{bc}^{-i}, \quad p_h = \sum_{i=0}^{4} {s_h + 8 \choose i} (1 - p_{be})^{\frac{s_h + 8}{8} + i}$$

$$p_{eb} = 1 - (1 - p_b)^8, \quad p_{data}(0) = p_h p_{nc}^{-n_c}$$

 p_{be}^{i}

• Common Part : $p_x(i) = (1 - p_x(0))^i p_x(0)$

Service Times

• RTS / CTS Exchange

$$\boldsymbol{t}_{rts}(0) = t_{rts} + t_{cts} + 2t_p + t_s$$
$$\boldsymbol{t}_{rts}(i) = i(t_{rts} + t_r) + \boldsymbol{t}_{rts}(0) + \sum_{k=1}^{i} t_b(k)$$

• DATA / ACK Exchange

$$\boldsymbol{t}_{data}\left(0\right) = t_{f} + t_{a} + 2t_{p} + t_{s}$$
$$\boldsymbol{t}_{data}\left(i\right) = i\left(t_{f} + t_{r}\right) + \boldsymbol{t}_{data}\left(0\right) + \sum_{k=1}^{i} t_{b}\left(k\right)$$

Expected Service Time

$$\boldsymbol{t}_{rts} = \sum_{i=0}^{\prime} p_{rts} \left(i \right) \boldsymbol{t}_{rts} \left(i \right), \quad \boldsymbol{t} = t_d + \boldsymbol{t}_{rts} + t_s + \boldsymbol{t}_{data} + t_d + t_b \left(0 \right)$$

• Fragmentation

$$\boldsymbol{t}_{data} = \sum_{i=0}^{r} p_{data}(i) \boldsymbol{t}_{data}(i)$$

• No Fragmentation $\mathbf{t}_{data} = \sum_{i(0)=0}^{r} \sum_{i(1)=0}^{r} \dots \sum_{i(n-1)=0}^{r} \left(p_{data}(i(0)) p_{data}(i(1)) \dots p_{data}(i(n-1)) \right) \left((n-1)t_s + \sum_{j=0}^{n-1} \mathbf{t}_{data}(i(j)) \right)$

$$\boldsymbol{t}_{data} = n\boldsymbol{t}_{f} p_{s}^{n-1} + (n-1)t_{s} p_{s}^{n}$$

• Finally:
$$t = t_d + t_{rts} + t_s + t_{data} + t_d + t_b (0)$$

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Simulation

- Introduces the IID Error Module for generating errors
- Written in C++
- Modular in order to add different error modules for future research

Graph



Graph



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Conclusion

- Summary
 - Established a mathematical model to calculate the expected service time of a data frame between two nodes
 - Coded a simulator to validate the mathematical model to a certain extent
- Analysis
 - It looks like error correction overhead is reasonable to improve delay performance.

Future Work

- Enhance Mathematical Model
 - Introduce the cost of encoding/decoding error correction overhead.
- More simulation
 - Use a more realistic error model to introduce errors
- Other costs
 - Use power consumption
 - Come up with a metric to balance performance and power consumption