

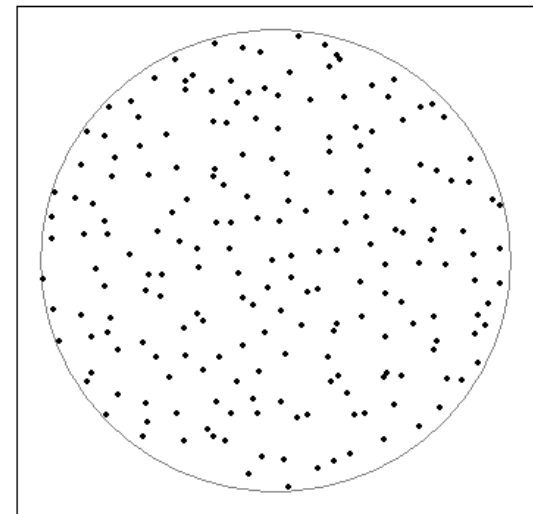
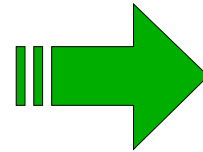
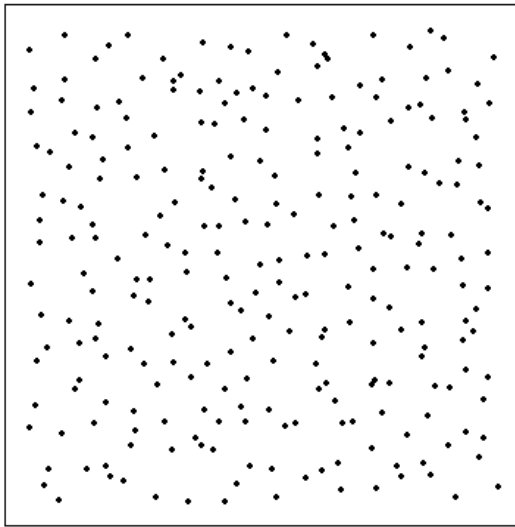


**CS 563 Advanced Topics in
Computer Graphics**
Disc and Hemisphere Sampling

by Joe Miller

Mapping Samples to a Disc

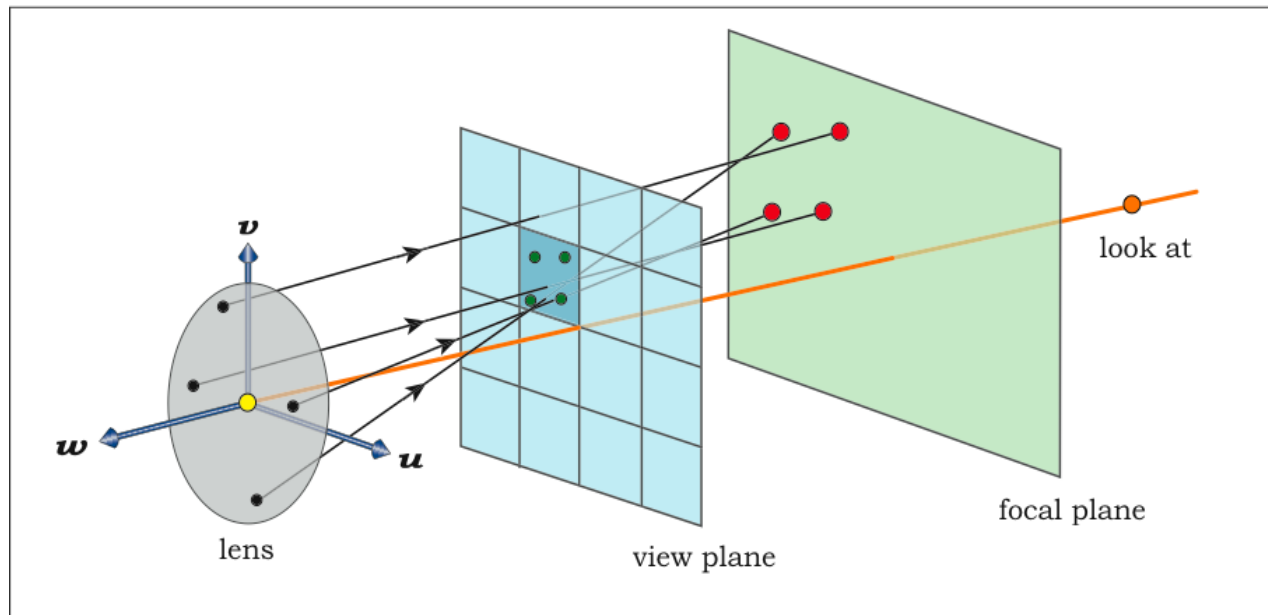
- Until now sampling has been done on the unit square



- Now we'd like to find samples in a circular area

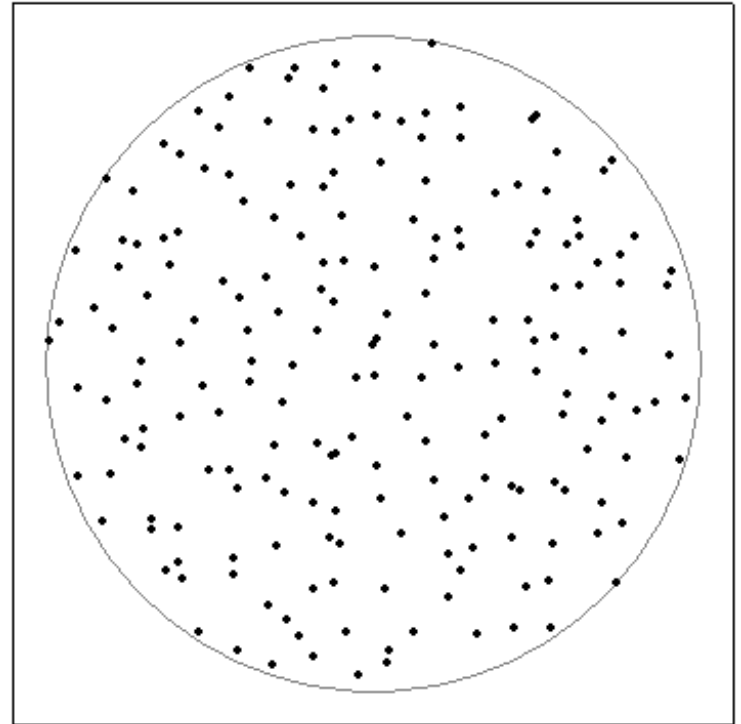
Application of Disc Sampling

- When is disc sampling used?
 - Sampling a circular lens
 - Shading with disc lights



Rejection Sampling

- Simplest approach is to use the same techniques for unit square and **reject** the samples that are not in the circle



Rejection Sampling

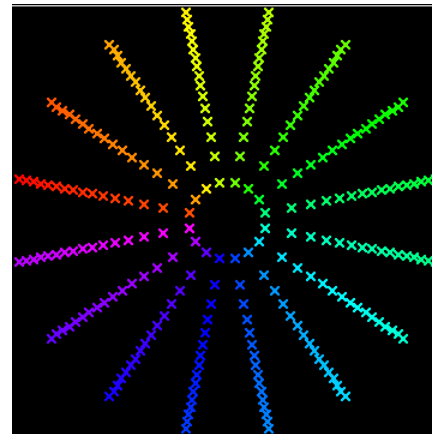
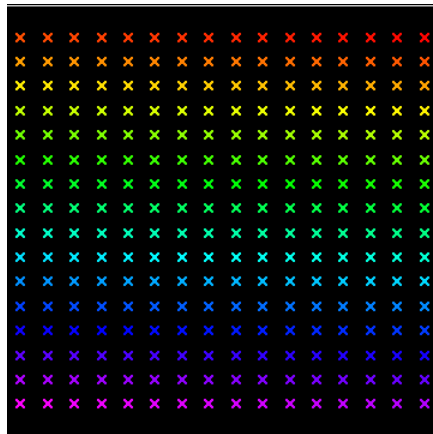
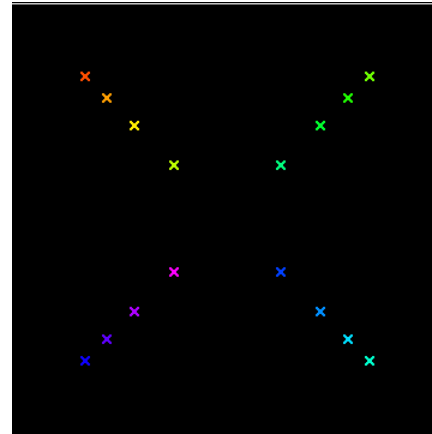
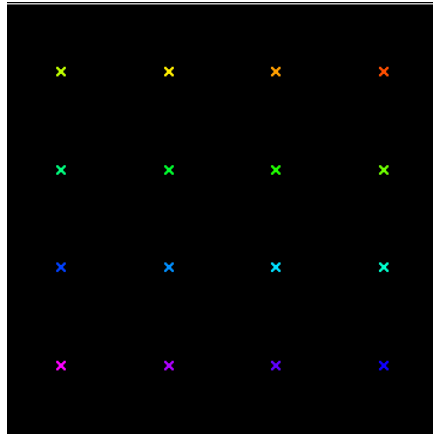
- Advantages
 - Simple, simple, simple
- Disadvantages
 - Breaks uniformity of some sampling techniques
 - N-rook, multi-jittered or Hammersley
 - Wastes time looking at many samples that are simply dropped
 - 2D uniform sampling loses $\sim 21\%$ of the samples
- Alternative is to map sample locations from the unit square to a unit circle

Polar Mapping

- One option is to use a polar mapping technique
- To do this convert unit square coordinates to polar coordinates: $(x_s, y_s) \Rightarrow (r, \theta)$
 - $r = \sqrt{x_s^2 + y_s^2}$
 - $\theta = \arctan2(y_s, x_s)$
- Convert polar coordinates to sample coordinates
 - $x = r * \cos(\theta)$
 - $y = r * \sin(\theta)$

Polar Mapping

- Example using 64 points and 256 points

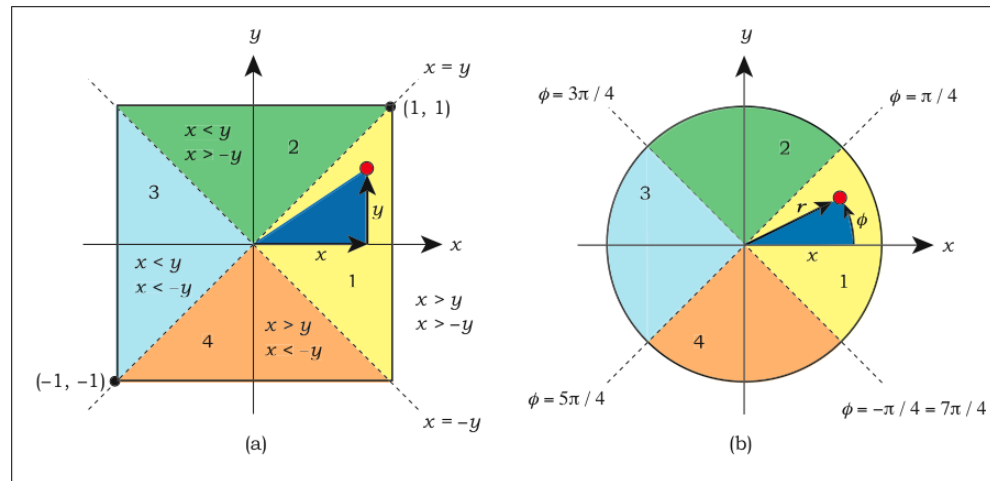


Polar Mapping

- One problem with polar mapping is that the many parts of the disc are under-sampled
 - Doesn't maintain the minimum distance between points
- Another problem is the mapping grossly distorts the original point
- So....

Concentric Mapping

- Another approach is to use a concentric mapping of the unit square to a unit circle
- Divide the unit square and circle into 4 quadrants along the 45° lines
- Set r to x or y and ϕ to a ratio of x and y based on the quadrant



Concentric Mapping

- Here's a table of the radius and angle for each of the quadrants

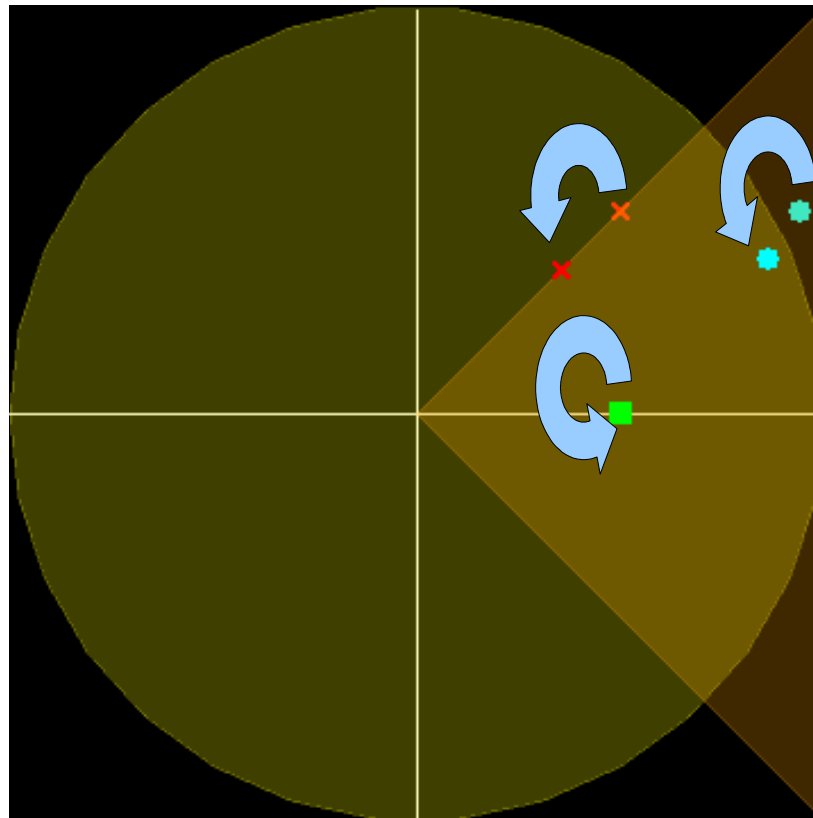
Quadrant	Angular Range	(x,y) Range	Map Equations
1	$315^\circ < \theta \leq 45^\circ$	$x > -y$ $x > y$	$r = x$ $\theta = \theta/4 * y/x$
2	$45^\circ < \theta \leq 135^\circ$	$x > -y$ $x < y$	$r = y$ $\theta = \theta/4 * (2 - x/y)$
3	$135^\circ < \theta \leq 225^\circ$	$x < y$ $x < -y$	$r = -x$ $\theta = \theta/4 * (4 + y/x)$
4	$225^\circ < \theta \leq 315^\circ$	$x > y$ $x < -y$	$r = -y$ $\theta = \theta/4 * (6 - x/y)$

- Calculate x,y same as before
 - $x = r * \cos(\theta)$
 - $y = r * \sin(\theta)$

Concentric Mapping

- Here's an example of how the unit square maps back to the unit circle

- Unit Circle

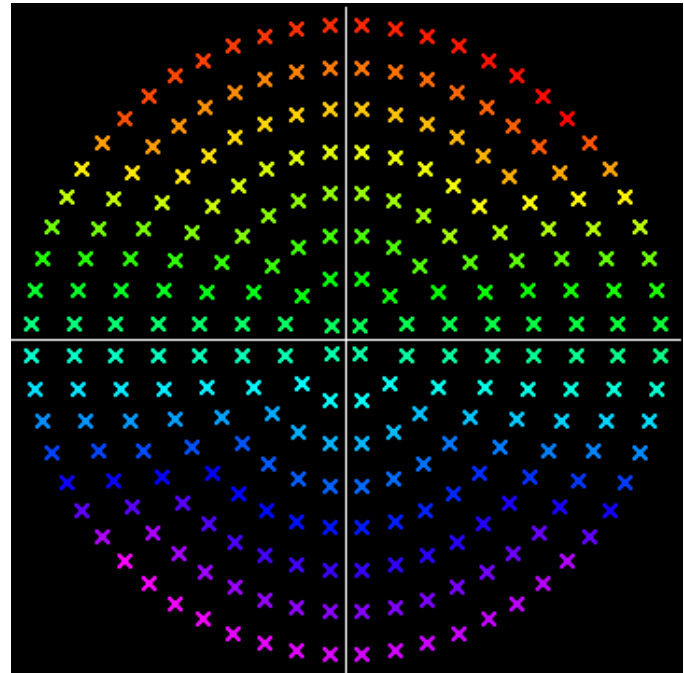
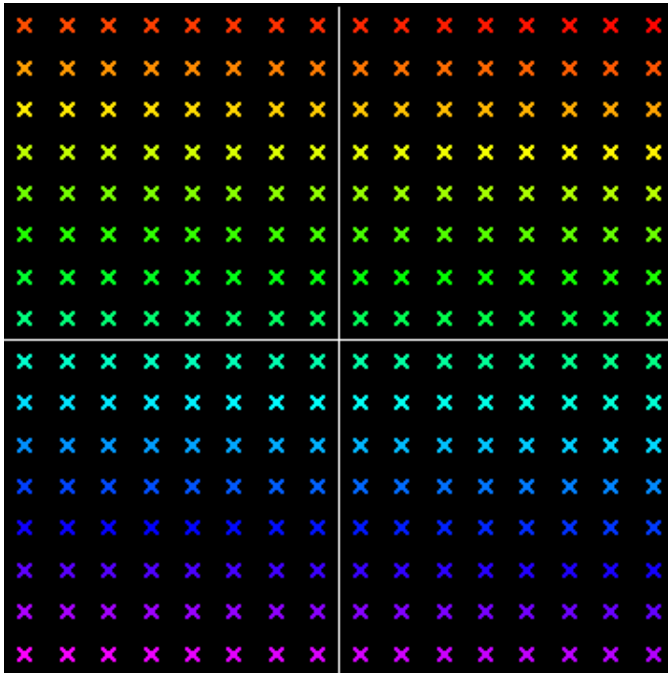


- Quadrant 1

- $r = x$
- $\theta = \arccos(y/x)$
- $x = r \cdot \cos(\theta)$
- $y = r \cdot \sin(\theta)$

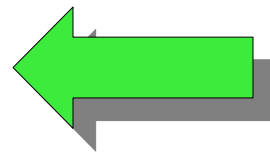
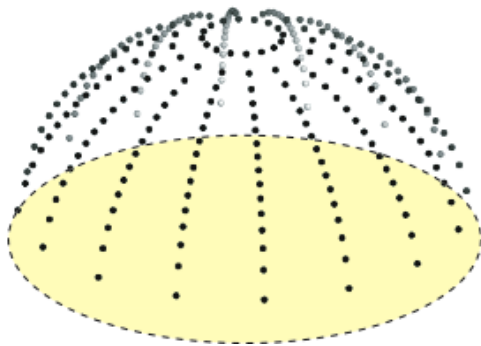
Concentric Mapping

- Here's the projection of 256 points



Mapping Samples to a Hemisphere

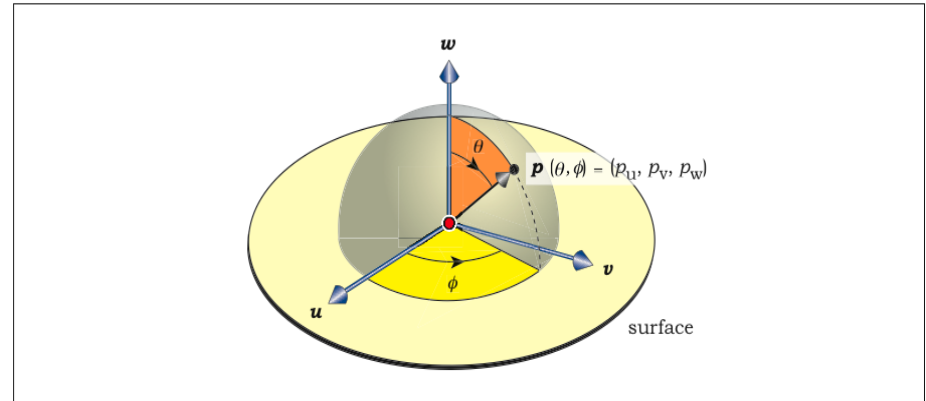
- The next challenge is to get samples on a unit hemisphere
- Use the same concept as disc mapping of using the algorithms derived for a unit square and remapping them to the unit hemisphere



256 regular samples
mapped to a hemisphere

Hemisphere Mapping Algorithm

- In this case we'll define a hemisphere in spherical coordinates (θ, ϕ) and then revert that back to a cartesian 3D point



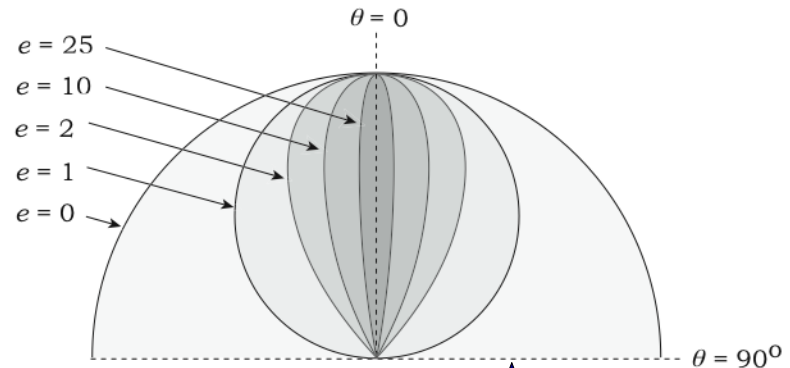
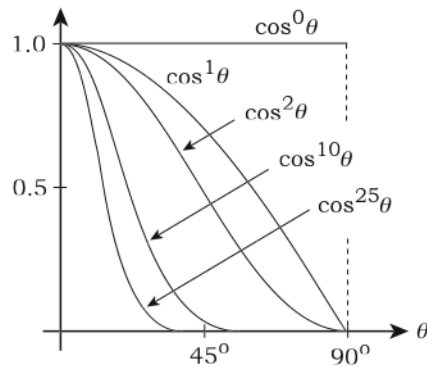
- The equation for (θ, ϕ) where (x_s, y_s) is a position in the unit square with range $[0,1]$
 - $\theta = 2\xi \sigma$
 - $\phi = \cos^{-1}[(1-y_s)^{1/(e+1)}]$
- And then as a point in 3D space
 - $\mathbf{p} = \sin \theta \cos \phi \mathbf{u} + \sin \theta \sin \phi \mathbf{v} + \cos \theta \mathbf{w}$

Hemisphere Mapping Algorithm

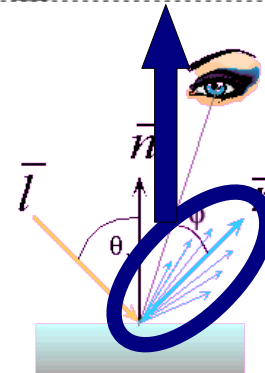
- $\phi = 2\pi x_s$
 - As x_s increases from $0 \rightarrow 1$ then ϕ goes from $0^\circ \rightarrow 360^\circ$
- $\theta = \cos^{-1}[(1-y_s)^{1/(e+1)}]$
 - Ignore the e for right now
 - As y_s increases from $0 \rightarrow 1$ then θ goes from $0^\circ \rightarrow 90^\circ$
- $\mathbf{p} = \sin \theta \cos \phi \mathbf{u} + \sin \theta \sin \phi \mathbf{v} + \cos \theta \mathbf{w}$
 - General equation for spherical coordinates

Cosine Distribution

- What about that e in $\square = \cos^{-1}[(1-y_s)^{1/(e+1)}]$
- The book describes this as the cosine distribution function
 - As general function $d = \cos^e(\square)$

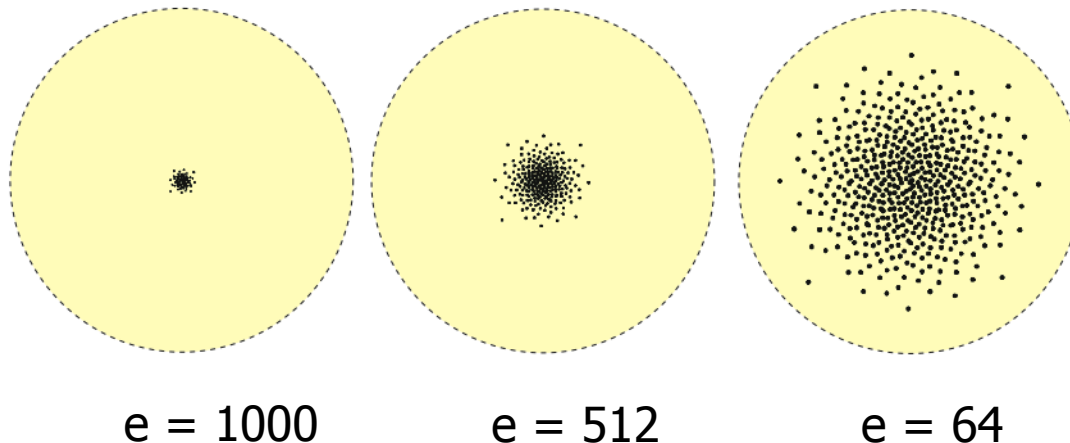


Phong $\rightarrow I_s = I_L \cos^{n_{shiny}} \square$



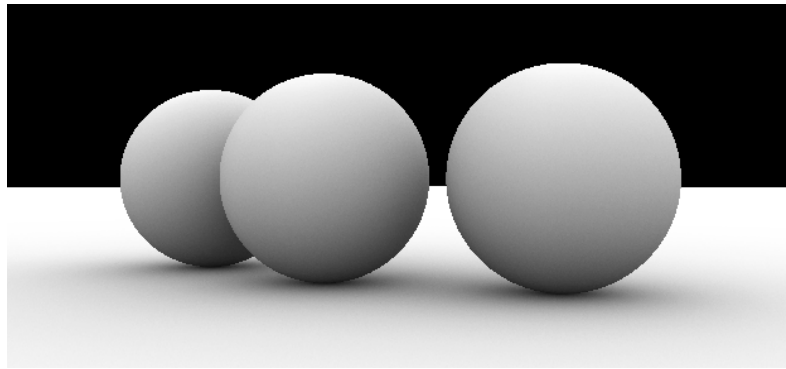
Cosine Distribution

- So what does it do for us?
- The distribution allows the system to tighten the sample distribution
 - As e gets larger the sample distribution gets tighter
 - $e = 0$ is a the unit hemisphere – radius of 1
 - $e = 1$ is a hemisphere is a radius of .5 (shifted)



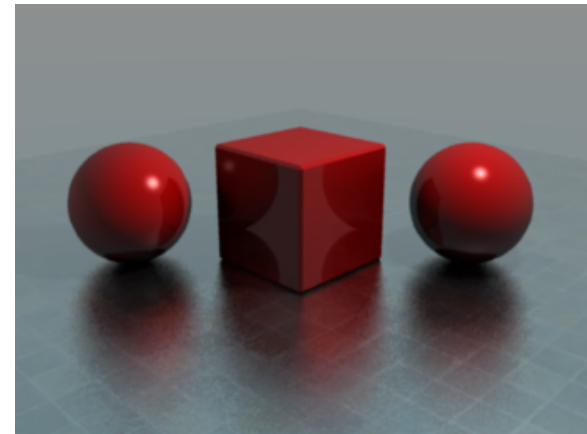
Applications of Hemisphere Mapping

- Here are a few places where hemisphere mapping is used in ray tracing



Glossy Reflection
(chapter 25)

Ambient occlusion
(chapter 17)



And many more ...

References

- Suffern, Kevin (2007). *Ray Tracing from the Ground Up*. pp. 119-131 Wellesley, MA: A K Peters, Ltd.
- Shirley, P. and K. Chiu (1997). A low distortion map between disk and square. *journal of graphics tools*, 2(3), 45-52