

IMGD 5100: Immersive HCI

Classifying 3D Input Devices

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Motivation

- The mouse and keyboard are good for general desktop UI tasks
 - Text entry, selection, drag and drop, scrolling, rubber banding, ...
 - Fixed computing environment
 - 2D mouse for 2D windows

□ How can we design effective techniques for 3D?

- Use a 2D device?
- Use multiple *n*-D devices?
- Use new devices?
- Use 2D interface widgets?
- Need new interaction techniques!



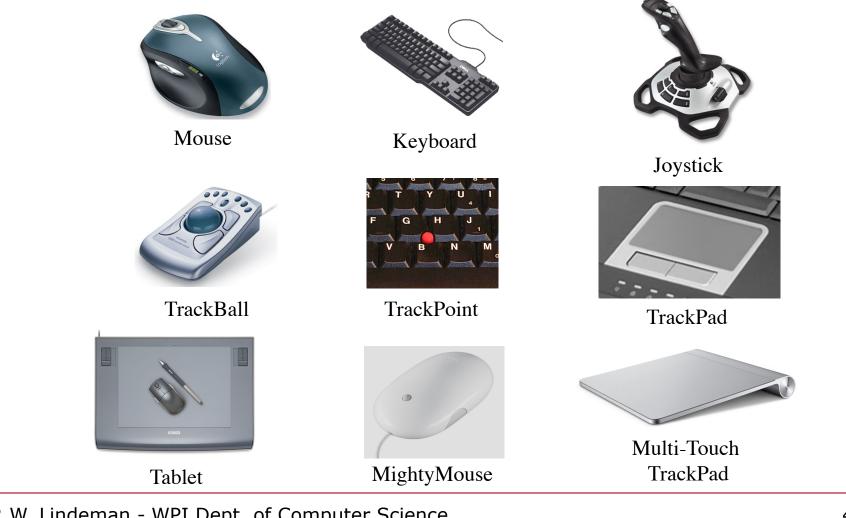
Motivation (cont.)

- □ Gaming and Virtual Reality
 - Tight coupling between action and reaction
 - Need for precision
- VR can give *real* first-person experiences, not just views
 - Head-mounted Display
 - □ In order to look behind you, turn your head!
 - Selecting/manipulating an object
 - Reach your hand out and grab it!
 - Travel
 - □ Just walk (well, not quite)!

Doing things that have no physical analog is more problematic



Common Input Devices





Game Controllers



Atari 2600 (1977)





PlayStation2 (2000)



Xbox 360 (2005)



PlayStation3 (2008)

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(1980)



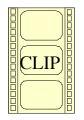
"Natural" Motion Controllers





Multi-Touch Surfaces

High resolutionCo-located interaction



http://www.ted.com/talks/jeff_han_demos_his_breakthrough_touchscreen.html



Prototypes of Controllers



WPI Prototypes of Controllers (cont.)





PlayStation3 Controller (prototype)

PlayStation3 SIXAXIS (released)



Hand-Held Devices

Becoming interesting!





Classification Schemes

- □ Relative vs. Absolute movement
- □ Integrated vs. Separable degrees of freedom
- Digital vs. Analog devices
- □ Isometric vs. Isotonic devices
- □ Rate control vs. Position control
- □ Special-purpose vs. General-purpose devices
- Direct vs. Indirect manipulation



More on Classifications

Relative vs. Absolute movement Mouse vs.Tablet

□Integrated vs. Separable degrees of freedom

- Mouse has integrated X, Y control
- Etch-a-sketch has separate X, Y control

Motions that are easy with one are hard with the other

Analog devices allow more sensitivity
 For example, analog game controllers

Isometric vs. Isotonic Input WPI Devices (Zhai)

□ No motion vs. No resistance

Actually a continuum of elasticity

- TrackPoint (mostly isometric) vs. mouse (mostly isotonic)
- Many devices are re-centering (e.g., joysticks)

Rate Control vs. Position Control (Zhai)



- Mouse is normally used for position control
- □ Mouse scroll-wheel
 - Position control
 - Click-drag for rate controlled scrolling
- □ Trackballs typically use position control
- Joysticks: Control position (cross-hair), or Control velocity (aircraft)
- Rate control eliminates need for clutching/ ratcheting
- Isotonic-rate control and isometric-position control tend to produce poor performance (Zhai)

Special-Purpose vs. General-WPI Purpose Input Devices (Buxton)

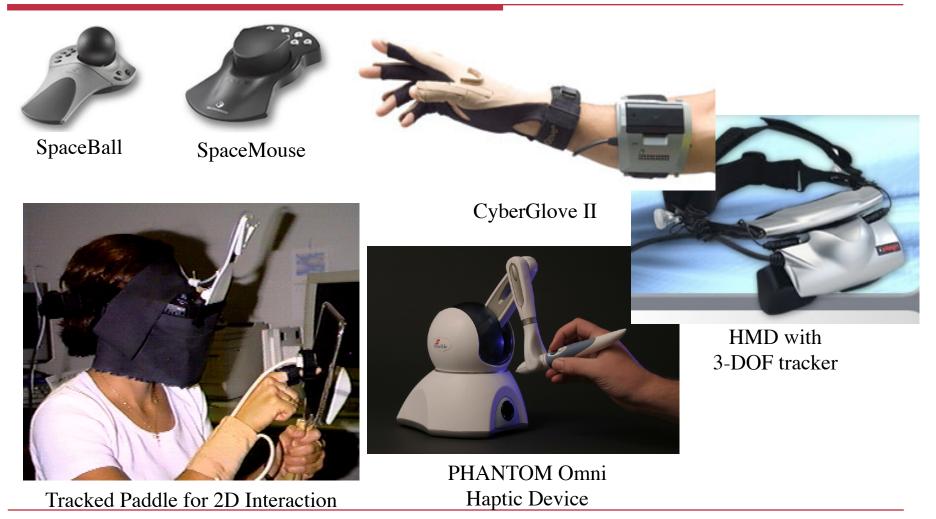
- □Game controllers are designed to support many types of games
 - Game developer decides on mapping
 - No "standard" mappings -> each game different
- Some special-purpose devices exist
 - Light guns
 - Steering wheels
 - RPG keyboard/joystick
 - Drum kits, dance pads, bongos, etc.

WPI Direct vs. Indirect Manipulation

- Direct
 - Clutch and drag an icon with mouse or stylus
 - Touch screens, PDAs use direct manipulation
 - Works well for things that have a physical analog
- Indirect
 - Use some widget to indirectly change something
- Problems with direct manipulation
 - Some things do not have a physical analog
 - Precision may be lacking
 - Selection/de-selection may be messy



3D Input Devices



WPI Motion-Capture/Tracking Systems

- □ Used heavily in movies and TV
 - Capture actual motion, and re-use
 - Example, Fox Sports NFL guy
- □ Can be done interactively, or offline
- □Can capture three or more (six) Degrees of Freedom (DoF)
 - Position, Orientation, or Both
- Many technical approaches

□No really good, general approaches



Tracking Technologies

- Mechanical
- □Magnetic
- Ultrasonic
- Inertial
- Optical
- □Time of flight
- □Hybrid



Mechanical Tracking

- Rigid linkage, potentiometers at joints
- □ Pros:
 - High accuracy
 - High resolution
- Cons:
 - Limited range of motion
 - Cumbersome



Magnetic Tracking

- Transmitter creates a magnetic field
 Transmitter is the origin
- Receivers are tracked using changes in magnetic field
- □Pros:
 - Fairly lightweight
 - Six DoF
- □Cons:
 - Very noisy near ferrous metal
 - Limited working range



Ultrasonic Tracking

- Transmitter sends pulses
- Receivers hear tones
- Distance is computed
- Can use "costellations" for orienation
- □Pros:
 - High accuracy
 - High resolution

Cons:

Requires line-of-sight (hearing)



Inertial Tracking

- AccelerometersTilt
 - Acceleration
- Gyroscopes
 - Measure movement
- □ Pros:
 - Not anchored to a place in space
- □Cons:
 - Accumulated error can cause drift
 - Only moderate accuracy



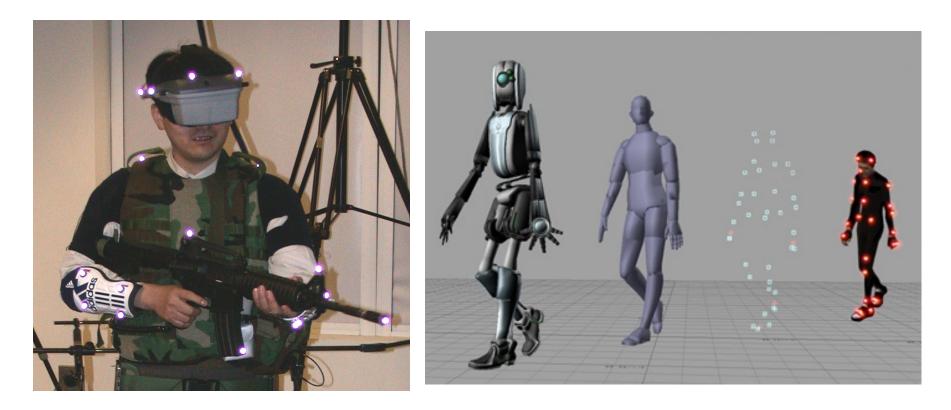
Optical Tracking

- Multiple fixed cameras capture markers
- Known camera parameters (FOV, focal length, position, orientation)
- □Use equations to compute position in 3-D space
- □ Markers can be simple points, or glyphs
- □ARToolKit
 - http://sourceforge.net/projects/artoolkit/



Optical Tracking (cont.)

□ Active vs. Passive Markers





Kinect

□ Structured light + sensor





Kinect Star Wars

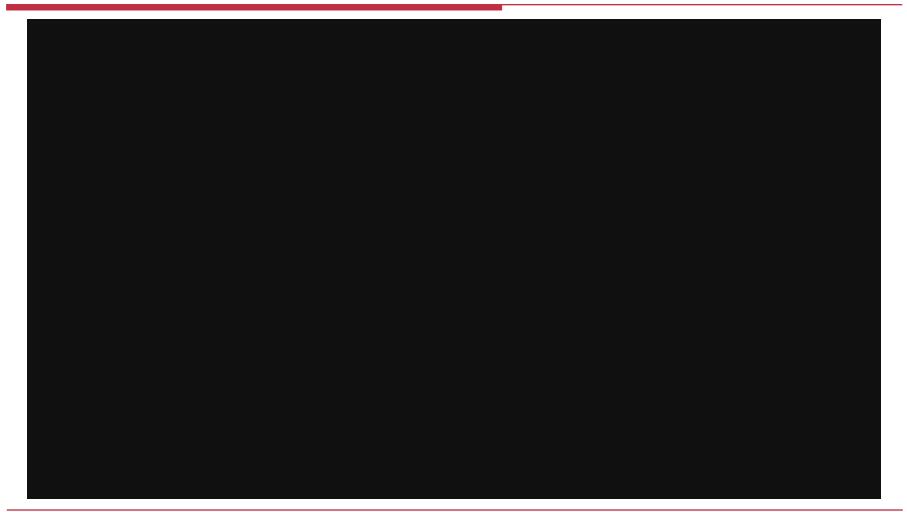




Kinect Fusion



Kinect IllumiRoom



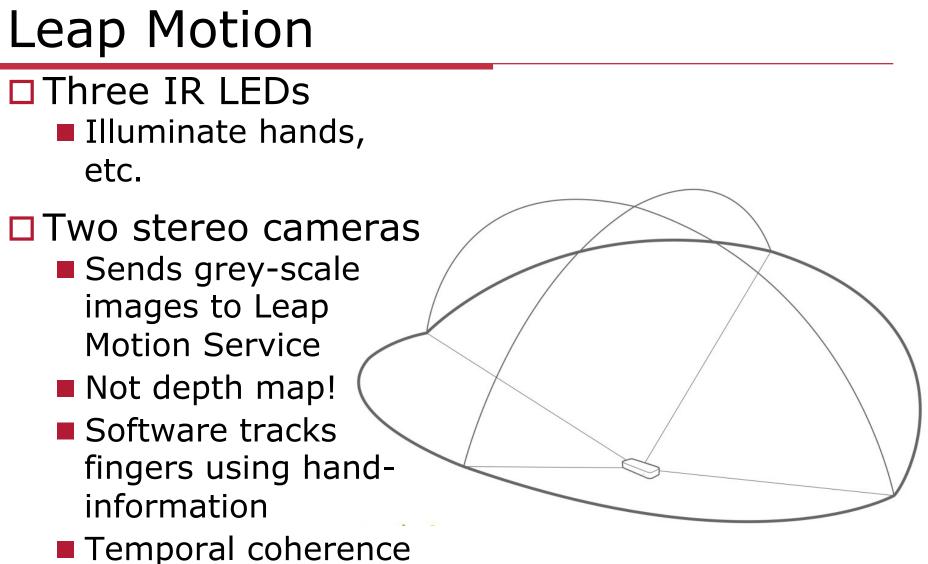


PlayStation MOVE

Camera tracker + inertial tracker









Leap Motion



WPI Leap Motion UX Design, Part 1



WPI Leap Motion UX Design, Part 2





Leap Motion UX Design

<u>http://blog.leapmotion.com/category/ux/</u>



Hybrid Tracking Techniques

- Compensate negative characteristics of one approach with another
 - Inertial and Magnetic
 - Inertial and Optical
 - WiiMote+MotionPlus
 - PlayStation Move



Other Options

- □ Some alternatives
 - Speech
 - Gestures: pointing to fly
 - Device actions (e.g., buttons, joysticks)
 - Head/gaze directed
- □Hybrid
 - Speech and gesture (e.g., "Put that, there.")

WP Special-Purpose Input Devices

- □ Some applications are more "real" with a device that matches the real action
 - Steering wheel
 - Light gun
 - Flight-simulator motion platform
 - Snowboard/surfboard
 - Pod racer
 - Motor cycle

□Today, since sensors are cheap, we can turn almost *anything* into an input device